Chapter 2

POISSON PROCESSES

2.1 Introduction

A Poisson process is a simple and widely used stochastic process for modeling the times at which arrivals enter a system. It is in many ways the continuous-time version of the Bernoulli process that was described in Section 1.3.5. For the Bernoulli process, the arrivals can occur only at positive integer multiples of some given increment size (often taken to be 1). Section 1.3.5 characterized the process by a sequence of IID binary random variables (rv’s), $Y_1, Y_2, \ldots$, where $Y_i = 1$ indicates an arrival at increment $i$ and $Y_i = 0$ otherwise. We observed (without any careful proof) that the process could also be characterized by the sequence of interarrival times. These interarrival times are geometrically distributed IID rv’s.

For the Poisson process, arrivals may occur at arbitrary positive times, and the probability of an arrival at any particular instant is 0. This means that there is no very clean way of describing a Poisson process in terms of the probability of an arrival at any given instant. It is more convenient to define a Poisson process in terms of the sequence of interarrival times, $X_1, X_2, \ldots$, which are defined to be IID. Before doing this, we describe arrival processes in a little more detail.

2.1.1 Arrival processes

An arrival process is a sequence of increasing rv’s, $0 < S_1 < S_2 < \cdots$, where\footnote{These rv’s $S_i$ can be viewed as sums of interarrival times. They should not be confused with the rv’s $S_t$ used in Section 1.3.5 to denote the number of arrivals by time $t$ for the Bernoulli process. We use $S_i$ throughout to denote the sum of $i$ rv’s. Understanding how such sums behave is a central issue of every chapter (and almost every section ) of these notes. Unfortunately, for the Bernoulli case, the IID sums of primary interest are the sums of binary rv’s at each time increment, whereas here the sums of primary interest are the sums of interarrival intervals.} $S_i < S_{i+1}$ means that $S_{i+1} - S_i$ is a positive rv, i.e., a rv $X$ such that $F_X(0) = 0$. The rv’s $S_1, S_2, \ldots$, are called arrival epochs (the word time is somewhat overused in this subject) and represent the times at which some repeating phenomenon occurs. Note that the process starts at time
0 and that multiple arrivals can’t occur simultaneously (the phenomenon of bulk arrivals can be handled by the simple extension of associating a positive integer rv to each arrival). We will sometimes permit simultaneous arrivals or arrivals at time 0 as events of zero probability, but these can be ignored. In order to fully specify the process by the sequence \( S_1, S_2, \ldots \) of rv’s, it is necessary to specify the joint distribution of the subsequences \( S_1, \ldots, S_n \) for all \( n > 1 \).

Although we refer to these processes as arrival processes, they could equally well model departures from a system, or any other sequence of incidents. Although it is quite common, especially in the simulation field, to refer to incidents or arrivals as events, we shall avoid that here. The \( n \)th arrival epoch \( S_n \) is a rv and \( \{ S_n \leq t \} \), for example, is an event. This would make it confusing to refer to the \( n \)th arrival itself as an event.

![Diagram](image)

**Figure 2.1**: A sample function of an arrival process and its arrival epochs \( \{ S_1, S_2, \ldots \} \), its interarrival intervals \( \{ X_1, X_2, \ldots \} \), and its counting process \( \{ N(t); t > 0 \} \)

As illustrated in Figure 2.1, any arrival process can also be specified by two alternative stochastic processes. The first alternative is the sequence of interarrival times, \( X_1, X_2, \ldots \). These are positive rv’s defined in terms of the arrival epochs by \( X_1 = S_1 \) and \( X_i = S_i - S_{i-1} \) for \( i > 1 \). Similarly, given the \( X_i \), the arrival epochs \( S_i \) are specified as

\[
S_n = \sum_{i=1}^{n} X_i.
\]  

(2.1)

Thus the joint distribution of \( X_1, \ldots, X_n \) for all \( n > 1 \) is sufficient (in principle) to specify the arrival process. Since the interarrival times are IID in most cases of interest, it is usually much easier to specify the joint distribution of the \( X_i \) than of the \( S_i \).

The second alternative for specifying an arrival process is the counting process \( N(t) \), where for each \( t > 0 \), the rv \( N(t) \) is the number of arrivals up to and including time \( t \).

The counting process \( \{ N(t); t > 0 \} \), illustrated in Figure 2.1, is an uncountably infinite family of rv’s \( \{ N(t); t > 0 \} \) where \( N(t) \), for each \( t > 0 \), is the number of arrivals in the interval \( (0, t] \). Whether the end points are included in these intervals is sometimes important, and we use parentheses to represent intervals without end points and square brackets to represent inclusion of the end point. Thus \( (a, b) \) denotes the interval \( \{ t : a < t < b \} \), and \( [a, b] \) denotes \( \{ t : a < t \leq b \} \). The counting rv’s \( N(t) \) for each \( t > 0 \) are then defined as the number of arrivals in the interval \( (0, t] \). \( N(0) \) is defined to be 0.

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\(^2\)Thus, for the Bernoulli process with an increment size of 1, \( N(n) \) is the rv denoted as \( S_n \) in Section 1.3.5
with probability 1, which means, as before, that we are considering only arrivals at strictly positive times.

The counting process \( \{ N(t); t > 0 \} \) for any arrival process has the properties that \( N(\tau) \geq N(t) \) for all \( \tau \geq t > 0 \) (i.e., \( N(\tau) - N(t) \) is a nonnegative random variable).

For any given integer \( n \geq 1 \) and time \( t > 0 \), the \( n \)th arrival epoch, \( S_n \), and the counting random variable, \( N(t) \), are related by

\[
\{ S_n \leq t \} = \{ N(t) \geq n \}. \tag{2.2}
\]

To see this, note that \( \{ S_n \leq t \} \) is the event that the \( n \)th arrival occurs at some time \( \tau \leq t \). This event implies that \( N(\tau) = n \), and thus that \( \{ N(t) \geq n \} \). Similarly, \( \{ N(t) = m \} \) for some \( m \geq n \) implies \( \{ S_m \leq t \} \), and thus that \( \{ S_n \leq t \} \). This equation is essentially obvious from Figure 2.1, but is one of those peculiar obvious things that is often difficult to see. An alternate form, which is occasionally more transparent, comes from taking the complement of both sides of (2.2), getting

\[
\{ S_n > t \} = \{ N(t) < n \}. \tag{2.3}
\]

For example, the event \( \{ S_1 > t \} \) means that the first arrival occurs after \( t \), which means \( \{ N(t) < 1 \} \) (i.e., \( \{ N(t) = 0 \} \)). These relations will be used constantly in going back and forth between arrival epochs and counting rv’s. In principle, (2.2) or (2.3) can be used to specify joint distribution functions of arrival epochs in terms of joint distribution functions of counting variables and vice versa, so either characterization can be used to specify an arrival process.

In summary, then, an arrival process can be specified by the joint distributions of the arrival epochs, the interarrival intervals, or the counting rv’s. In principle, specifying any one of these specifies the others also.\(^3\)

### 2.2 Definition and properties of a Poisson process

A Poisson process is an example of an arrival process, and the interarrival times provide the most convenient description since the interarrival times are defined to be IID. Processes with IID interarrival times are particularly important and form the topic of Chapter 4.

**Definition 2.2.1.** A renewal process is an arrival process for which the sequence of interarrival times is a sequence of positive IID rv’s.

**Definition 2.2.2.** A Poisson process is a renewal process in which the interarrival intervals

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\(^3\)By definition, a stochastic process is a collection of rv’s, so one might ask whether an arrival process (as a stochastic process) is ‘really’ the arrival epoch process \( 0 \leq S_1 \leq S_2 \leq \cdots \) or the interarrival process \( X_1, X_2, \ldots \) or the counting process \( \{ N(t); t > 0 \} \). The arrival time process comes to grips with the actual arrivals, the interarrival process is often the simplest, and the counting process ‘looks’ most like a stochastic process in time since \( N(t) \) is a rv for each \( t \geq 0 \). It seems preferable, since the descriptions are so clearly equivalent, to view arrival processes in terms of whichever description is most convenient.
have an exponential distribution function; i.e., for some real \( \lambda > 0 \), each \( X_i \) has the density\(^4\)
\[
f_X(x) = \lambda \exp(-\lambda x) \text{ for } x \geq 0.
\]

The parameter \( \lambda \) is called the rate of the process. We shall see later that for any interval of size \( t \), \( \lambda t \) is the expected number of arrivals in that interval. Thus \( \lambda \) is called the arrival rate of the process.

### 2.2.1 Memoryless property

What makes the Poisson process unique among renewal processes is the memoryless property of the exponential distribution.

**Definition 2.2.3. Memoryless random variables:** A rv \( X \) possesses the memoryless property if \( \Pr\{X > 0\} = 1 \), (i.e., \( X \) is a positive rv) and, for every \( x \geq 0 \) and \( t \geq 0 \),
\[
\Pr\{X > t + x\} = \Pr\{X > x\} \Pr\{X > t\}.
\]

(2.4)

Note that (2.4) is a statement about the complementary distribution function of \( X \). There is no intimation that the event \( \{X > t + x\} \) in the equation has any particular relation to the events \( \{X > t\} \) or \( \{X > x\} \).

For an exponential rv \( X \) of rate \( \lambda > 0 \), \( \Pr\{X > x\} = e^{-\lambda x} \) for \( x \geq 0 \). This satisfies (2.4) for all \( x \geq 0 \), \( t \geq 0 \), so \( X \) is memoryless. Conversely, an arbitrary rv \( X \) is memoryless only if it is exponential. To see this, let \( h(x) = \ln[\Pr\{X > x\}] \) and observe that since \( \Pr\{X > x\} \) is nonincreasing in \( x \), \( h(x) \) is also. In addition, (2.4) says that \( h(t + x) = h(x) + h(t) \) for all \( x, t \geq 0 \). These two statements (see Exercise 2.6) imply that \( h(x) \) must be linear in \( x \), and \( \Pr\{X > x\} \) must be exponential in \( x \).

Since a memoryless rv \( X \) must be exponential, \( \Pr\{X > t\} > 0 \) for all \( t \geq 0 \). This means that we can rewrite (2.4) as
\[
\Pr\{X > t + x \mid X > t\} = \Pr\{X > x\}.
\]

(2.5)

If \( X \) is interpreted as the waiting time until some given arrival, then (2.5) states that, given that the arrival has not occurred by time \( t \), the distribution of the remaining waiting time (given by \( x \) on the left side of (2.5)) is the same as the original waiting time distribution (given on the right side of (2.5)), i.e., the remaining waiting time has no ‘memory’ of previous waiting.

**Example 2.2.1.** Suppose \( X \) is the waiting time, starting at time 0, for a bus to arrive, and suppose \( X \) is memoryless. After waiting from 0 to \( t \), the distribution of the remaining waiting time from \( t \) is the same as the original distribution starting from 0. The still waiting customer is, in a sense, no better off at time \( t \) than at time 0. On the other hand, if the bus is known to arrive regularly every 16 minutes, then it will certainly arrive within a

\(^4\)With this density, \( \Pr\{X_i > 0\} = 1 \), so that we can regard \( X_i \) as a positive random variable. Since events of probability zero can be ignored, the density \( \lambda \exp(-\lambda x) \) for \( x \geq 0 \) and zero for \( x < 0 \) is effectively the same as the density \( \lambda \exp(-\lambda x) \) for \( x > 0 \) and zero for \( x \leq 0 \).
minute for a person who has already waited 15 minutes. Thus regular arrivals are not memoryless. The opposite situation is also possible. If the bus frequently breaks down, then a 15 minute wait can indicate that the remaining wait is probably very long, so again \( X \) is not memoryless. We study these non-memoryless situations when we study renewal processes in Chapter 4.

Although memoryless distributions must be exponential, it can be seen that if the definition of memoryless is restricted to integer times, then the geometric distribution becomes memoryless, and it can be seen as before that this is the only memoryless integer-time distribution. In this respect, the Bernoulli process (which has geometric interarrival times) is like a discrete-time version of the Poisson process (which has exponential interarrival times).

We now use the memoryless property of exponential rv’s to find the distribution of the first arrival in a Poisson process after an arbitrary given time \( t > 0 \). We not only find this distribution, but also show that this first arrival after \( t \) is independent of all arrivals up to and including \( t \). More precisely, we prove the following theorem.

**Theorem 2.2.1.** For a Poisson process of rate \( \lambda \), and any given \( t > 0 \), the length of the interval from \( t \) until the first arrival after \( t \) is a nonnegative rv \( Z \) with the distribution function \( 1 - \exp[-\lambda z] \) for \( z \geq 0 \). This rv is independent of both \( N(t) \) and of the \( N(t) \) arrival epochs before time \( t \). It is also independent of the set of rv’s \( \{ N(\tau); \tau \leq t \} \).

The basic idea behind this theorem is to note that \( Z \), conditional on the time \( \tau \) of the last arrival before \( t \), is simply the remaining time until the next arrival. Since the interarrival time starting at \( \tau \) is exponential and thus memoryless, \( Z \) is independent of \( \tau \leq t \), and of all earlier arrivals. The following proof carries this idea out in detail.

![Figure 2.2: For arbitrary fixed \( t > 0 \), consider the event \( N(t) = 0 \). Conditional on this event, \( Z \) is the distance from \( t \) to \( S_1 \); i.e., \( Z = X_1 - t \).](image)

**Proof:** Let \( Z \) be the distance from \( t \) until the first arrival after \( t \). We first condition on \( N(t) = 0 \) (see Figure 2.2). Given \( N(t) = 0 \), we see that \( X_1 > t \) and \( Z = X_1 - t \). Thus,

\[
\Pr\{Z > z \mid N(t)=0\} = \Pr\{X_1 > z + t \mid N(t)=0\} = \Pr\{X_1 > z + t \mid X_1 > t\} = \Pr\{X_1 > z\} = e^{-\lambda z}.
\]

In (2.6), we used the fact that \( \{N(t) = 0\} = \{X_1 > t\} \), which is clear from Figure 2.1 (and also from (2.3)). In (2.7) we used the memoryless condition in (2.5) and the fact that \( X_1 \) is exponential.
Next consider the conditions that \( N(t) = n \) (for arbitrary \( n > 1 \)) and \( S_n = \tau \) (for arbitrary \( \tau \leq t \)). The argument here is basically the same as that with \( N(t) = 0 \), with a few extra details (see Figure 2.3).

![Figure 2.3: Given \( N(t) = 2 \) and \( S_2 = \tau \), \( X_3 \) is equal to \( Z + (t - \tau) \). Also, the event \( \{N(t)=2, S_2=\tau\} \) is the same as the event \( \{S_2=\tau, X_3>t-\tau\} \).](attachment:image.png)

Conditional on \( N(t) = n \) and \( S_n = \tau \), the first arrival after \( t \) is the first arrival after the arrival at \( S_n \), i.e., \( Z = z \) corresponds to \( X_{n+1} = z + (t - \tau) \).

\[
\Pr\{Z > z \mid N(t)=n, S_n=\tau\} = \Pr\{X_{n+1} > z+t-\tau \mid N(t)=n, S_n=\tau\} = \Pr\{X_{n+1} > z+t-\tau \mid X_{n+1}>t-\tau, S_n=\tau\} = \Pr\{X_{n+1} > z\} = e^{-\lambda z},
\]

where (2.9) follows because, given \( S_n = \tau \leq t \), we have \( \{N(t) = n\} = \{X_{n+1} > t - \tau\} \) (see Figure 2.3). Eq. (2.10) follows because \( X_{n+1} \) is independent of \( S_n \). Eq. (2.11) follows from the memoryless condition in (2.5) and the fact that \( X_{n+1} \) is exponential.

The same argument applies if, in (2.8), we condition not only on \( S_n \) but also on \( S_1, \ldots, S_{n-1} \). Since this is equivalent to conditioning on \( N(\tau) \) for all \( \tau \) in \((0,t]\), we have

\[
\Pr\{Z > z \mid \{N(\tau), 0 < \tau \leq t\}\} = \exp(-\lambda z).
\]

Next consider subsequent interarrival intervals after a given time \( t \). For \( m \geq 2 \), let \( Z_m \) be the interarrival interval from the \( m-1 \)st arrival epoch after \( t \) to the \( m \)th arrival epoch after \( t \). Let \( Z \) in (2.12) be denoted as \( Z_1 \) here. Given \( N(t) = n \) and \( S_n = \tau \), we see that \( Z_m = X_{m+n} \) for \( m \geq 2 \), and therefore \( Z_1, Z_2, \ldots \) are IID exponentially distributed rv's, conditional on \( N(t) = n \) and \( S_n = \tau \) (see Exercise 2.8). Since this is independent of \( N(t) \) and \( S_n \), we see that \( Z_1, Z_2, \ldots \) are unconditionally IID and also independent of \( N(t) \) and \( S_n \). It should also be clear that \( Z_1, Z_2, \ldots \) are independent of \( \{N(\tau); 0 < \tau \leq t\} \).

The above argument shows that the portion of a Poisson process starting at an arbitrary time \( t > 0 \) is a probabilistic replica of the process starting at 0; that is, the time until the first arrival after \( t \) is an exponentially distributed rv with parameter \( \lambda \), and all subsequent interarrival intervals are independent of this first arrival and of each other and all have the same exponential distribution.
Definition 2.2.4. A counting process \( \{N(t); t > 0\} \) has the stationary increment property if \( N(t') - N(t) \) has the same distribution function as \( N(t' - t) \) for every \( t' > t > 0 \).

Let us define \( \tilde{N}(t, t') = N(t') - N(t) \) as the number of arrivals in the interval \( (t, t'] \) for any given \( t' \geq t \). We have just shown that for a Poisson process, the rv \( \tilde{N}(t, t') \) has the same distribution as \( N(t' - t) \), which means that a Poisson process has the stationary increment property. Thus, the distribution of the number of arrivals in an interval depends on the size of the interval but not on its starting point.

Definition 2.2.5. A counting process \( \{N(t); t > 0\} \) has the independent increment property if, for every integer \( k > 0 \), and every \( k \)-tuple of times \( 0 < t_1 < t_2 < \cdots < t_k \), the \( k \)-tuple of rv’s \( \tilde{N}(t_1), \tilde{N}(t_1, t_2), \ldots, \tilde{N}(t_{k-1}, t_k) \) are statistically independent.

For the Poisson process, Theorem 2.2.1 says that for any \( t \), the time \( Z_1 \) until the next arrival after \( t \) is independent of \( N(\tau) \) for all \( \tau \leq t \). Letting \( t_1 < t_2 < \cdots < t_{k-1} < t \), this means that \( Z_1 \) is independent of \( N(t_1), \tilde{N}(t_1, t_2), \ldots, \tilde{N}(t_{k-1}, t) \). We have also seen that the subsequent interarrival times after \( Z_1 \), and thus \( N(t, t') \) are independent of \( N(t_1), \tilde{N}(t_1, t_2), \ldots, \tilde{N}(t_{k-1}, t) \). Renaming \( t \) as \( t_k \) and \( t' \) as \( t_{k+1} \), we see that \( N(t_k, t_{k+1}) \) is independent of \( N(t_1), \tilde{N}(t_1, t_2), \ldots, \tilde{N}(t_{k-1}, t_k) \). Since this is true for all \( k \), the Poisson process has the independent increment property. In summary, we have proved the following:

Theorem 2.2.2. Poisson processes have both the stationary increment and independent increment properties.

Note that if we look only at integer times, then the Bernoulli process also has the stationary and independent increment properties.

2.2.2 Probability density of \( S_n \) and \( S_1, \ldots, S_n \)

Recall from (2.1) that, for a Poisson process, \( S_n \) is the sum of \( n \) IID rv’s, each with the density function \( f_X(x) = \lambda \exp(-\lambda x), \ x \geq 0 \). Also recall that the density of the sum of two independent rv’s can be found by convolving their densities, and thus the density of \( S_2 \) can be found by convolving \( f_X(x) \) with itself, \( S_3 \) by convolving the density of \( S_2 \) with \( f_X(x) \), and so forth. The result, for \( t \geq 0 \), is called the Erlang density,\(^5\)

\[
f_{S_n}(t) = \frac{\lambda^n t^{n-1} \exp(-\lambda t)}{(n-1)!}.
\]  

(2.13)

We can understand this density (and other related matters) much better by reviewing the above mechanical derivation more carefully. The joint density for two continuous independent rv’s \( X_1 \) and \( X_2 \) is given by \( f_{X_1,X_2}(x_1, x_2) = f_{X_1}(x_1)f_{X_2}(x_2) \). Letting \( S_2 = X_1 + X_2 \) and substituting \( S_2 - X_1 \) for \( X_2 \), we get the following joint density for \( X_1 \) and the sum \( S_2 \),

\[
f_{X_1,S_2}(x_1, s_2) = f_{X_1}(x_1)f_{X_2}(s_2 - x_1).
\]

\(^5\)Another (somewhat rarely used) name for the Erlang density is the gamma density.
The marginal density for $S_2$ then results from integrating $x_1$ out from the joint density, and this, of course, is the familiar convolution integration. For IID exponential rv's $X_1, X_2$, the joint density of $X_1, S_2$ takes the following interesting form:

$$f_{X_1S_2}(x_1s_2) = \lambda^2 \exp(-\lambda x_1) \exp(-\lambda(s_2-x_1)) = \lambda^2 \exp(-\lambda s_2) \quad \text{for } 0 \leq x_1 \leq s_2. \quad (2.14)$$

This says that the joint density does not contain $x_1$, except for the constraint $0 \leq x_1 \leq s_2$. Thus, for fixed $s_2$, the joint density, and thus the conditional density of $X_1$ given $S_2 = s_2$ is uniform over $0 \leq x_1 \leq s_2$. The integration over $x_1$ in the convolution equation is then simply multiplication by the interval size $s_2$, yielding the marginal distribution $f_{S_2}(s_2) = \lambda^2 s_2 \exp(-\lambda s_2)$, in agreement with (2.13) for $n = 2$.

This same curious behavior exhibits itself for the sum of an arbitrary number $n$ of IID exponential rv's. That is, $f_{X_1...X_n}(x_1, ..., x_n) = \lambda^n \exp(-\lambda x_1 - \lambda x_2 - ... - \lambda x_n)$. Letting $S_n = X_1 + \cdots + X_n$ and substituting $S_n - X_1 - \cdots - X_{n-1}$ for $X_n$, this becomes

$$f_{X_1...X_{n-1}S_n}(x_1, ..., x_{n-1}, s_n) = \lambda^n \exp(-\lambda s_n).$$

since each $x_i$ cancels out above. This equation is valid over the region where each $x_i \geq 0$ and $s_n - x_1 - \cdots - x_{n-1} \geq 0$. The density is 0 elsewhere.

The constraint region becomes more clear here if we replace the interarrival intervals $X_1, ..., X_{n-1}$ with the arrival epochs $S_1, ..., S_{n-1}$ where $S_1 = X_1$ and $S_i = X_i + S_{i-1}$ for $2 \leq i \leq n - 1$. The joint density then becomes$^6$

$$f_{S_1...S_n}(s_1, ..., s_n) = \lambda^n \exp(-\lambda s_n) \quad \text{for } 0 \leq s_1 \leq s_2 \cdots \leq s_n. \quad (2.15)$$

The interpretation here is the same as with $S_2$. The joint density does not contain any arrival time other than $s_n$, except for the ordering constraint $0 \leq s_1 \leq s_2 \leq \cdots \leq s_n$, and thus this joint density is constant over all choices of arrival times satisfying the ordering constraint for a fixed $s_n$. Mechanically integrating this over $s_1$, then $s_2$, etc. we get the Erlang formula (2.13). The Erlang density then is the joint density in (2.15) times the volume $s_n^{n-1}/(n-1)!$ of the region of $s_1, ..., s_{n-1}$ satisfying $0 < s_1 < \cdots < s_n$. This will be discussed further later.

Note that (2.15), for all $n$ specifies the joint distribution for all arrival times, and thus fully specifies a Poisson process. An alternate definition for the Poisson process is then any process whose joint arrival time distribution satisfies (2.15). This is not customarily used to define the Poisson process, whereas two alternate definitions given subsequently often are used as a starting definition.

### 2.2.3 The PMF for $N(t)$

The Poisson counting process, $\{N(t); t > 0\}$ consists of a nonnegative integer rv $N(t)$ for each $t > 0$. In this section, we show that the PMF for this rv is the well-known Poisson

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$^6$The random vector $S = (S_1, ..., S_n)$ is then related to the interarrival intervals $X = (X_1, ..., X_n)$ by a linear transformation, say $S = AX$ where $A$ is a lower triangular matrix with ones on the main diagonal and on all elements below the main diagonal. In general, the joint density of a non-singular linear transformation $AX$ at $X = x$ is $f_X(x)/|\det A|$. This is because the transformation $A$ carries an incremental cube, $\delta$ on each side, into a parallelepiped of volume $\delta^n|\det A|$. Since, for the case here, $A$ is lower triangular with 1's on the diagonal, $\det A = 1$. 

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PMF, as stated in the following theorem. We give two proofs for the theorem, each providing its own type of understanding and each showing the close relationship between \(\{N(t) = n\}\) and \(\{S_n = t\}\).

**Theorem 2.2.3.** For a Poisson process of rate \(\lambda\), and for any \(t > 0\), the PMF for \(N(t)\), i.e., the number of arrivals in \((0, t]\), is given by the Poisson PMF,

\[
p_{N(t)}(n) = \frac{(\lambda t)^n \exp(-\lambda t)}{n!}.
\]

**(Proof 1):** This proof, for given \(n\) and \(t\), is based on two ways of calculating \(\Pr\{t < S_{n+1} \leq t + \delta\}\) for some vanishingly small \(\delta\). The first way is based on the already known density of \(S_{n+1}\) and gives

\[
\Pr\{t < S_{n+1} \leq t + \delta\} = \int_t^{t+\delta} f_{S_{n+1}}(\tau) \, d\tau = f_{S_{n+1}}(t) (\delta + o(\delta)).
\]

The term \(o(\delta)\) is used to describe a function of \(\delta\) that goes to 0 faster than \(\delta\) as \(\delta \to 0\). More precisely, a function \(g(\delta)\) is said to be of order \(o(\delta)\) if \(\lim_{\delta \to 0} \frac{g(\delta)}{\delta} = 0\). Thus \(\Pr\{t < S_{n+1} \leq t + \delta\} = f_{S_{n+1}}(t)(\delta + o(\delta))\) is simply a consequence of the fact that \(S_{n+1}\) has a continuous probability density in the interval \([t, t + \delta]\).

The second way to calculate \(\Pr\{t < S_{n+1} \leq t + \delta\}\) is to first observe that the probability of more than 1 arrival in \((t, t+\delta]\) is \(o(\delta)\). Ignoring this possibility, \(\{t < S_{n+1} \leq t + \delta\}\) occurs if exactly \(n\) arrivals are in the interval \([0, t]\) and one arrival occurs in \((t, t + \delta]\). Because of the independent increment property, this is an event of probability \(p_{N(t)}(n)(\lambda \delta + o(\delta))\). Thus

\[
p_{N(t)}(n)(\lambda \delta + o(\delta)) + o(\delta) = f_{S_{n+1}}(t)(\delta + o(\delta)).
\]

Dividing by \(\delta\) and taking the limit \(\delta \to 0\), we get

\[
\lambda p_{N(t)}(n) = f_{S_{n+1}}(t).
\]

Using the density for \(f_{S_n}\) in (2.13), we get (2.16).

**(Proof 2):** The approach here is to use the fundamental relation that \(\{N(t) \geq n\} = \{S_n \leq t\}\). Taking the probabilities of these events,

\[
\sum_{i=n}^{\infty} p_{N(t)}(i) = \int_0^t f_{S_n}(\tau) \, d\tau \quad \text{for all } n \geq 1 \text{ and } t > 0.
\]

The term on the right above is the distribution function of \(S_n\) and the term on the left is the complementary distribution function of \(N(t)\). The complementary distribution function and the PMF of \(N(t)\) uniquely specify each other, so the theorem is equivalent to showing that

\[
\sum_{i=n}^{\infty} \frac{(\lambda t)^i \exp(-\lambda t)}{i!} = \int_0^t f_{S_n}(\tau) \, d\tau.
\]
If we take the derivative with respect to $t$ of each side of (2.17), we find that almost magically each term except the first on the left cancels out, leaving us with

$$\frac{\lambda^n t^{n-1} \exp(-\lambda t)}{(n - 1)!} = f_{S_n}(t).$$

Thus the derivative with respect to $t$ of each side of (2.17) is equal to the derivative of the other for all $n \geq 1$ and $t > 0$. The two sides of (2.17) are also equal in the limit $t \to \infty$, so it follows that (2.17) is satisfied everywhere, completing the proof. 

\[\square\]

### 2.2.4 Alternate definitions of Poisson processes

**Definition 2 of a Poisson process:** A Poisson counting process $\{N(t); t > 0\}$ is a counting process that satisfies (2.16) (i.e., has the Poisson PMF) and has the independent and stationary increment properties.

We have seen that the properties in Definition 2 are satisfied starting with Definition 1 (using IID exponential interarrival times), so Definition 1 implies Definition 2. Exercise 2.4 shows that IID exponential interarrival times are implied by Definition 2, so the two definitions are equivalent.

It may be somewhat surprising at first to realize that a counting process that has the Poisson PMF at each $t$ is not necessarily a Poisson process, and that the independent and stationary increment properties are also necessary. One way to see this is to recall that the Poisson PMF for all $t$ in a counting process is equivalent to the Erlang density for the successive arrival epochs. Specifying the probability density for $S_1, S_2, \ldots$, as Erlang specifies the marginal densities of $S_1, S_2, \ldots$, but need not specify the joint densities of these rv’s. Figure 2.4 illustrates this in terms of the joint density of $S_1, S_2$, given as

$$f_{S_1, S_2}(s_1, s_2) = \lambda^2 \exp(-\lambda s_2) \quad \text{for } 0 \leq s_1 \leq s_2$$

and 0 elsewhere. The figure illustrates how the joint density can be changed without changing the marginals.

There is a similar effect with the Bernoulli process in that a discrete counting process for which the number of arrivals from 0 to $t$, for each integer $t$, is a binomial rv, but the process is not Bernoulli. This is explored in Exercise 2.5.

The next definition of a Poisson process is based on its incremental properties. Consider the number of arrivals in some very small interval $(t, t + \delta)$. Since $N(t, t + \delta)$ has the same distribution as $N(\delta)$, we can use (2.16) to get

$$\Pr\{N(t, t + \delta) = 0\} = e^{-\lambda \delta} \approx 1 - \lambda \delta + o(\delta)$$

$$\Pr\{N(t, t + \delta) = 1\} = \lambda \delta e^{-\lambda \delta} \approx \lambda \delta + o(\delta)$$

$$\Pr\{N(t, t + \delta) \geq 2\} \approx o(\delta).$$

\[2.18\]

**Definition 3 of a Poisson process:** A Poisson counting process is a counting process that satisfies (2.18) and has the stationary and independent increment properties.
Figure 2.4: The joint density of $S_1, S_2$ is nonzero in the region shown. It can be changed, while holding the marginals constant, by reducing the joint density by $\epsilon$ in the upper left and lower right squares above and increasing it by $\epsilon$ in the upper right and lower left squares.

We have seen that Definition 1 implies Definition 3. The essence of the argument the other way is that for any interarrival interval $X$, $F_X(x + \delta) - F_X(x)$ is the probability of an arrival in an appropriate infinitesimal interval of width $\delta$, which by (2.18) is $\lambda \delta + o(\delta)$. Turning this into a differential equation (see Exercise 2.7), we get the desired exponential interarrival intervals. Definition 3 has an intuitive appeal, since it is based on the idea of independent arrivals during arbitrary disjoint intervals. It has the disadvantage that one must do a considerable amount of work to be sure that these conditions are mutually consistent, and probably the easiest way is to start with Definition 1 and derive these properties. Showing that there is a unique process that satisfies the conditions of Definition 3 is even harder, but is not necessary at this point, since all we need is the use of these properties. Section 2.2.5 will illustrate better how to use this definition (or more precisely, how to use (2.18)).

What (2.18) accomplishes in Definition 3, beyond the assumption of independent and stationary increments, is the prevention of bulk arrivals. For example, consider a counting process in which arrivals always occur in pairs, and the intervals between successive pairs are IID and exponentially distributed with parameter $\lambda$ (see Figure 2.5). For this process, $\Pr \{ \tilde{N}(t, t + \delta) = 1 \} = 0$, and $\Pr \{ \tilde{N}(t, t + \delta) = 2 \} = \lambda \delta + o(\delta)$, thus violating (2.18). This process has stationary and independent increments, however, since the process formed by viewing a pair of arrivals as a single incident is a Poisson process.

### 2.2.5 The Poisson process as a limit of shrinking Bernoulli processes

The intuition of Definition 3 can be achieved in a less abstract way by starting with the Bernoulli process, which has the properties of Definition 3 in a discrete-time sense. We then go to an appropriate limit of a sequence of these processes, and find that this sequence of Bernoulli processes converges in some sense to the Poisson process.

Recall that a Bernoulli process is an IID sequence, $Y_1, Y_2, \ldots$, of binary random variables for which $p_Y(1) = p$ and $p_Y(0) = 1 - p$. We can visualize $Y_i = 1$ as an arrival at time $i$ and $Y_i = 0$ as no arrival, but we can also ‘shrink’ the time scale of the process so that for some integer $j > 0$, $Y_i$ is an arrival or no arrival at time $i2^{-j}$. We consider a sequence indexed
by \( j \) of such shrinking Bernoulli processes, and in order to keep the arrival rate constant, we let \( p = \lambda 2^{-j} \) for the \( j \)th process. Thus for each unit increase in \( j \), the Bernoulli process shrinks by replacing each slot with two slots, each with half the previous arrival probability. The expected number of arrivals per unit time is then \( \lambda \), matching the Poisson process that we are approximating.

If we look at this \( j \)th process relative to Definition 3 of a Poisson process, we see that for these regularly spaced increments of size \( \delta = 2^{-j} \), the probability of one arrival in an increment is \( \lambda \delta \) and that of no arrival is \( 1 - \lambda \delta \), and thus (2.18) is satisfied, and in fact the \( o(\delta) \) terms are exactly zero. For arbitrary sized increments, it is clear that disjoint increments have independent arrivals. The increments are not quite stationary, since, for example, an increment of size \( 2^{-j-1} \) might contain a time that is a multiple of \( 2^{-j} \) or might not, depending on its placement. However, for any fixed increment of size \( \delta \), the number of multiples of \( 2^{-j} \) (i.e., the number of possible arrival points) is either \( \lfloor \delta 2^j \rfloor \) or \( 1 + \lfloor \delta 2^j \rfloor \).

Thus in the limit \( j \to \infty \), the increments are both stationary and independent.

For each \( j \), the \( j \)th Bernoulli process has an associated Bernoulli counting process \( N_j(t) = \sum_{i=1}^{\lfloor t 2^j \rfloor} Y_i \). This is the number of arrivals up to time \( t \) and is a discrete rv with the binomial PMF. That is, \( p_{N_j(t)}(n) = \binom{\lfloor t 2^j \rfloor}{n} p^n (1 - p)^{\lfloor t 2^j \rfloor - n} \) where \( p = \lambda 2^{-j} \). We now show that this PMF approaches the Poisson PMF as \( j \) increases.\(^7\)

**Theorem 2.2.4.** Consider the sequence of shrinking Bernoulli processes with arrival probability \( \lambda 2^{-j} \) and time-slot size \( 2^{-j} \). Then for every fixed time \( t > 0 \) and fixed number of arrivals \( n \), the counting PMF \( p_{N_j(t)}(n) \) approaches the Poisson PMF (of the same \( \lambda \)) with increasing \( j \), i.e.,

\[
\lim_{j \to \infty} p_{N_j(t)}(n) = p_{N(t)}(n). \tag{2.19}
\]

\(^7\)This limiting result for the binomial distribution is very different from the asymptotic results in Chapter 1 for the binomial. Here the parameter \( p \) of the binomial is shrinking with increasing \( j \), whereas there, \( p \) is constant while the number of variables is increasing.
2.2. Definition and Properties of a Poisson Process

Proof: We first rewrite the binomial PMF, for \( |t^{2^j}| \) variables with \( p = \lambda 2^{-j} \) as

\[
\lim_{j \to \infty} p_{N_j(t)}(n) = \lim_{j \to \infty} \binom{|t^{2^j}|}{n} \left( \frac{\lambda 2^{-j}}{1 - \lambda 2^{-j}} \right)^n \exp\left[ |t^{2^j}| \ln(1 - \lambda 2^{-j}) \right] \\
= \lim_{j \to \infty} \binom{|t^{2^j}|}{n} \left( \frac{\lambda 2^{-j}}{1 - \lambda 2^{-j}} \right)^n \exp(-\lambda t) \\
= \lim_{j \to \infty} \frac{|t^{2^j}| \cdot |t^{2^j-1}| \cdots |t^{2^j-n+1}|}{n!} \left( \frac{\lambda 2^{-j}}{1 - \lambda 2^{-j}} \right)^n \exp(-\lambda t) \\
= \frac{(\lambda t)^n \exp(-\lambda t)}{n!}.
\]

We used \( \ln(1 - \lambda 2^{-j}) = -\lambda 2^{-j} + o(2^{-j}) \) in (2.20) and expanded the combinatorial term in (2.21). In (2.22), we recognized that \( \lim_{j \to \infty} |t^{2^j-i}| \left( \frac{\lambda 2^{-j}}{1 - \lambda 2^{-j}} \right) = \lambda t \) for \( 0 \leq i \leq n - 1 \).

Since the binomial PMF (scaled as above) has the Poisson PMF as a limit for each \( n \), the distribution function of \( N_j(t) \) also converges to the Poisson distribution function for each \( t \). In other words, for each \( t > 0 \), the counting random variables \( N_j(t) \) of the Bernoulli processes converge in distribution to \( N(t) \) of the Poisson process.

This does not say that the Bernoulli counting processes converge to the Poisson counting process in any meaningful sense, since the joint distributions are also of concern. The following corollary treats this.

Corollary 2.2.1. For any finite integer \( k > 0 \), let \( 0 < t_1 < t_2 < \cdots < t_k \) be any set of time instants. Then the joint distribution function of \( N_j(t_1), N_j(t_2), \ldots, N_j(t_k) \) approaches the joint distribution function of \( N(t_1), N(t_2), \ldots, N(t_k) \) as \( j \to \infty \).

Proof: We can rewrite the joint PMF for each Bernoulli process as

\[
p_{N_j(t_1),\ldots,N_j(t_k)}(n_1, \ldots, n_k) = p_{N_j(t_1),\hat{N}_j(t_1,t_2),\ldots,\hat{N}_j(t_{k-1},t_k)}(n_1, n_2-n_1, \ldots, n_k-n_{k-1}) \\
= p_{N_j(t_1)}(n_1) \prod_{\ell=2}^k p_{\hat{N}_j(t_{\ell-1},t_{\ell})}(n_{\ell} - n_{\ell-1})
\]

where we have used the independent increment property for the Bernoulli process. For the Poisson process, we similarly have

\[
p_{N(t_1),\ldots,N(t_k)}(n_1, \ldots, n_k) = p_{N(t_1)}(n_1) \prod_{\ell=2}^k p_{\hat{N}(t_{\ell-1},t_{\ell})}(n_{\ell} - n_{\ell-1})
\]

Taking the limit of (2.23) as \( j \to \infty \), we recognize from Theorem 2.2.4 that each term of (2.23) goes to the corresponding term in (2.24). For the \( \hat{N} \) rv’s , this requires a trivial generalization in Theorem 2.2.4 to deal with the arbitrary starting time.

We conclude from this that the sequence of Bernoulli processes above converges to the Poisson process in the sense of the corollary. Recall from Section 1.5.5 that there are a
number of ways in which a sequence of rv’s can converge. As one might imagine, there are many more ways in which a sequence of stochastic processes can converge, and the corollary simply establishes one of these. We have neither the mathematical tools nor the need to delve more deeply into these convergence issues.

Both the Poisson process and the Bernoulli process are so easy to analyze that the convergence of shrinking Bernoulli processes to Poisson is rarely the easiest way to establish properties about either. On the other hand, this convergence is a powerful aid to the intuition in understanding each process. In other words, the relation between Bernoulli and Poisson is very useful in suggesting new ways of looking at problems, but is usually not the best way to analyze those problems.

2.3 Combining and splitting Poisson processes

Suppose that \( \{N_1(t); t > 0\} \) and \( \{N_2(t); t > 0\} \) are independent Poisson counting processes\(^8\) of rates \( \lambda_1 \) and \( \lambda_2 \) respectively. We want to look at the sum process where \( N(t) = N_1(t) + N_2(t) \) for all \( t \geq 0 \). In other words, \( \{N(t); t > 0\} \) is the process consisting of all arrivals to both process 1 and process 2. We shall show that \( \{N(t); t > 0\} \) is a Poisson counting process of rate \( \lambda = \lambda_1 + \lambda_2 \). We show this in three different ways, first using Definition 3 of a Poisson process (since that is most natural for this problem), then using Definition 2, and finally Definition 1. We then draw some conclusions about the way in which each approach is helpful. Since \( \{N_1(t); t > 0\} \) and \( \{N_2(t); t > 0\} \) are independent and both possess the stationary and independent increment properties, it follows from the definitions that \( \{N(t); t > 0\} \) also possesses the stationary and independent increment properties. Using the approximations in (2.18) for the individual processes, we see that

\[
\Pr\left\{ \widetilde{N}(t, t + \delta) = 0 \right\} = \Pr\left\{ \widetilde{N}_1(t, t + \delta) = 0 \right\} \Pr\left\{ \widetilde{N}_2(t, t + \delta) = 0 \right\} = (1 - \lambda_1 \delta)(1 - \lambda_2 \delta) \approx 1 - \lambda \delta.
\]

where \( \lambda_1 \lambda_2 \delta^2 \) has been dropped. In the same way, \( \Pr\left\{ \widetilde{N}(t, t + \delta) = 1 \right\} \) is approximated by \( \lambda \delta \) and \( \Pr\left\{ \widetilde{N}(t, t + \delta) \geq 2 \right\} \) is approximated by 0, both with errors proportional to \( \delta^2 \). It follows that \( \{N(t); t > 0\} \) is a Poisson process.

In the second approach, we have \( N(t) = N_1(t) + N_2(t) \). Since \( N(t) \), for any given \( t \), is the sum of two independent Poisson rv’s, it is also a Poisson rv with mean \( \lambda t = \lambda_1 t + \lambda_2 t \). If the reader is not aware that the sum of two independent Poisson rv’s is Poisson, it can be derived by discrete convolution of the two PMF’s (see Exercise 1.19). More elegantly, one can observe that we have already implicitly shown this fact. That is, if we break an interval \( I \) into disjoint subintervals, \( I_1 \) and \( I_2 \), then the number of arrivals in \( I \) (which is Poisson) is the sum of the number of arrivals in \( I_1 \) and in \( I_2 \) (which are independent Poisson).

\(^8\)Two processes \( \{N_1(t); t > 0\} \) and \( \{N_2(t); t > 0\} \) are said to be independent if for all positive integers \( k \) and all sets of times \( 0 < t_1 < t_2 < \cdots < t_k \), the random variables \( N_1(t_1), \ldots, N_1(t_k) \) are independent of \( N_2(t_1), \ldots, N_2(t_k) \). Here it is enough to extend the independent increment property to independence between increments over the two processes; equivalently, one can require the interarrival intervals for one process to be independent of the interarrivals for the other process.
Finally, since $N(t)$ is Poisson for each $t$, and since the stationary and independent increment properties are satisfied, $\{N(t); t > 0\}$ is a Poisson process.

In the third approach, $X_1$, the first interarrival interval for the sum process, is the minimum of $X_{11}$, the first interarrival interval for the first process, and $X_{21}$, the first interarrival interval for the second process. Thus $X_1 > t$ if and only if both $X_{11}$ and $X_{21}$ exceed $t$, so

$$\Pr\{X_1 > t\} = \Pr\{X_{11} > t\} \Pr\{X_{21} > t\} = \exp(-\lambda_1 t - \lambda_2 t) = \exp(-\lambda t).$$

Using the memoryless property, each subsequent interarrival interval can be analyzed in the same way.

The first approach above was the most intuitive for this problem, but it required constant care about the order of magnitude of the terms being neglected. The second approach was the simplest analytically (after recognizing that sums of independent Poisson rv’s are Poisson), and required no approximations. The third approach was very simple in retrospect, but not very natural for this problem. If we add many independent Poisson processes together, it is clear, by adding them one at a time, that the sum process is again Poisson. What is more interesting is that when many independent counting processes (not necessarily Poisson) are added together, the sum process often tends to be approximately Poisson if the individual processes have small rates compared to the sum. To obtain some crude intuition about why this might be expected, note that the interarrival intervals for each process (assuming no bulk arrivals) will tend to be large relative to the mean interarrival interval for the sum process. Thus arrivals that are close together in time will typically come from different processes. The number of arrivals in an interval large relative to the combined mean interarrival interval, but small relative to the individual interarrival intervals, will be the sum of the number of arrivals from the different processes; each of these is 0 with large probability and 1 with small probability, so the sum will be approximately Poisson.

### 2.3.1 Subdividing a Poisson process

Next we look at how to break $\{N(t); t > 0\}$, a Poisson counting process of rate $\lambda$, into two processes, $\{N_1(t); t > 0\}$ and $\{N_2(t); t > 0\}$. Suppose that each arrival in $\{N(t); t > 0\}$ is sent to the first process with probability $p$ and to the second process with probability $1 - p$ (see Figure 2.6). Each arrival is switched independently of each other arrival and independently of the arrival epochs. It may be helpful to visualize this as the combination of two independent processes. The first is the Poisson process of rate $\lambda$ and the second is a Bernoulli process $\{X_n; n \geq 1\}$ where $p_{X_n}(1) = p$ and $p_{X_n}(2) = 1 - p$. The $n$th arrival of the Poisson process is then labeled as a type 1 arrival if $X_n = 1$ and as a type 2 arrival with probability $1 - p$.

We shall show that the resulting processes are each Poisson, with rates $\lambda_1 = \lambda p$ and $\lambda_2 = \lambda(1 - p)$ respectively, and that furthermore the two processes are independent. Note that, conditional on the original process, the two new processes are not independent; in fact one completely determines the other. Thus this independence might be a little surprising.

First consider a small increment $(t, t + \delta]$. The original process has an arrival in this incremental interval with probability $\lambda \delta$ (ignoring $\delta^2$ terms as usual), and thus process 1
has an arrival with probability \( \lambda \delta p \) and process 2 with probability \( \lambda \delta (1 - p) \). Because of the independent increment property of the original process and the independence of the division of each arrival between the two processes, the new processes each have the independent increment property, and from above have the stationary increment property. Thus each process is Poisson. Note now that we cannot verify that the two processes are independent from this small increment model. We would have to show that the number of arrivals for process 1 and 2 are independent over \( (t, t + \delta) \). Unfortunately, leaving out the terms of order \( \delta^2 \), there is at most one arrival to the original process and no possibility of an arrival to each new process in \( (t, t + \delta) \). If it is impossible for both processes to have an arrival in the same interval, they cannot be independent. It is possible, of course, for each process to have an arrival in the same interval, but this is a term of order \( \delta^2 \). Thus, without paying attention to the terms of order \( \delta^2 \), it is impossible to demonstrate that the processes are independent.

To demonstrate that process 1 and 2 are independent, we first calculate the joint PMF for \( N_1(t), N_2(t) \) for arbitrary \( t \). Conditioning on a given number of arrivals \( N(t) \) for the original process, we have

\[
\text{Pr}\{N_1(t)=m, N_2(t)=k \mid N(t)=m+k\} = \frac{(m+k)!}{m!k!} p^m (1-p)^k. \tag{2.25}
\]

Equation (2.25) is simply the binomial distribution, since, given \( m+k \) arrivals to the original process, each independently goes to process 1 with probability \( p \). Since the event \( \{N_1(t)=m, N_2(t)=k\} \) is a subset of the conditioning event above,

\[
\text{Pr}\{N_1(t)=m, N_2(t)=k \mid N(t)=m+k\} = \frac{\text{Pr}\{N_1(t)=m, N_2(t)=k\}}{\text{Pr}\{N(t)=m+k\}}.
\]

Combining this with (2.25), we have

\[
\text{Pr}\{N_1(t)=m, N_2(t)=k\} = \frac{(m+k)!}{m!k!} p^m (1-p)^k \frac{(\lambda t)^{m+k} e^{-\lambda t}}{(m+k)!} \tag{2.26}
\]

Rearranging terms, we get

\[
\text{Pr}\{N_1(t)=m, N_2(t)=k\} = \frac{(p \lambda t)^{m} e^{-\lambda pt}}{m!} \frac{(1-p) \lambda t)^{k} e^{-\lambda (1-p)t}}{k!} \tag{2.27}
\]
This shows that $N_1(t)$ and $N_2(t)$ are independent. To show that the processes are independent, we must show that for any $k > 1$ and any set of times $0 \leq t_1 \leq t_2 \leq \cdots \leq t_k$, the sets \{\(N_1(t_i); 1 \leq i \leq k\)\} and \{\(N_2(t_j); 1 \leq j \leq k\)\} are independent of each other. It is equivalent to show that the sets \{\(\tilde{N}_1(t_{i-1}, t_i); 1 \leq i \leq k\)\} and \{\(\tilde{N}_2(t_{j-1}, t_j); 1 \leq j \leq k\)\} (where $t_0$ is 0) are independent. The argument above shows this independence for $i = j$, and for $i \neq j$, the independence follows from the independent increment property of \(\{N(t); t > 0\}\).

### 2.3.2 Examples using independent Poisson processes

We have observed that if the arrivals of a Poisson process are split into two new arrival processes, each arrival of the original process independently going into the first of the new processes with some fixed probability $p$, then the new processes are Poisson processes and are independent. The most useful consequence of this is that any two independent Poisson processes can be viewed as being generated from a single process in this way. Thus, if one process has rate $\lambda_1$ and the other has rate $\lambda_2$, they can be viewed as coming from a process of rate $\lambda_1 + \lambda_2$. Each arrival to the combined process is then labeled as a first process arrival with probability $p = \lambda_1/(\lambda_1 + \lambda_2)$ and as a second process arrival with probability $1 - p$.

The above point of view is very useful for finding probabilities such as $\Pr\{S_{1k} < S_{2j}\}$ where $S_{1k}$ is the epoch of the $k$th arrival to the first process and $S_{2j}$ is the epoch of the $j$th arrival to the second process. The problem can be rephrased in terms of a combined process to ask: out of the first $k + j - 1$ arrivals to the combined process, what is the probability that $k$ or more of them are switched to the first process? (Note that if $k$ or more of the first $k + j - 1$ go to the first process, at most $j - 1$ go to the second, so the $k$th arrival to the first precedes the $j$th arrival to the second; similarly if fewer than $k$ of the first $k + j - 1$ go to the first process, then the $j$th arrival to the second process precedes the $k$th arrival to the first). Since each of these first $k + j - 1$ arrivals are switched independently with the same probability $p$, the answer is

$$
\Pr\{S_{1k} < S_{2j}\} = \sum_{i=k}^{k+j-1} \frac{(k+j-1)!}{i!(k+j-1-i)!} p^i (1-p)^{k+j-1-i}.
$$

#### Example 2.3.1. [The M/M/1 queue]

Queueing theorists use a standard notation of characters separated by slashes to describe common types of queueing systems. The first character describes the arrival process to the queue. $M$ stands for memoryless and means a Poisson arrival process; $D$ stands for deterministic and means that the interarrival interval is fixed and non-random; $G$ stands for general interarrival distribution. We assume that the interarrival intervals are IID (thus making the arrival process a renewal process), but many authors use $GI$ to explicitly indicate IID interarrivals. The second character describes the service process. The same letters are used, with $M$ indicating an exponential service time distribution. The third character gives the number of servers. It is assumed, when this notation is used, that the service times are IID, independent of the arrival times, and independent of which server is used.

Consider an M/M/1 queue, i.e., a queueing system with a Poisson arrival system (say of rate $\lambda$) and a single server who serves arriving customers in order with a service time distribution $F(y) = 1 - \exp[-\mu y]$. Thus during periods when the server is busy, customers
leave the system according to a Poisson process (process 2) of rate \( \mu \). We then see that if \( j \) or more customers are waiting at a given time, then (2.28) gives the probability that the \( k \)th subsequent arrival comes before the \( j \)th departure.

2.4 Non-homogeneous Poisson processes

The Poisson process, as we defined it, is characterized by a constant arrival rate \( \lambda \). It is often useful to consider a more general type of process in which the arrival rate varies as a function of time. A *non-homogeneous Poisson process* with time varying arrival rate \( \lambda(t) \) is defined\(^9\) as a counting process \( \{N(t); t > 0\} \) which has the independent increment property and, for all \( t \geq 0, \delta > 0 \), also satisfies:

\[
\begin{align*}
\Pr\{\tilde{N}(t, t + \delta) = 0\} &= 1 - \delta \lambda(t) + o(\delta) \\
\Pr\{\tilde{N}(t, t + \delta) = 1\} &= \delta \lambda(t) + o(\delta) \\
\Pr\{\tilde{N}(t, t + \delta) \geq 2\} &= o(\delta).
\end{align*}
\]

where \( \tilde{N}(t, t + \delta) = N(t + \delta) - N(t) \). The non-homogeneous Poisson process does not have the stationary increment property.

One common application occurs in optical communication where a non-homogeneous Poisson process is often used to model the stream of photons from an optical modulator; the modulation is accomplished by varying the photon intensity \( \lambda(t) \). We shall see another application shortly in the next example. Sometimes a Poisson process, as we defined it earlier, is called a homogeneous Poisson process.

We can use a “shrinking Bernoulli process” again to approximate a non-homogeneous Poisson process. To see how to do this, assume that \( \lambda(t) \) is bounded away from zero. We partition the time axis into increments whose lengths \( \delta \) vary inversely with \( \lambda(t) \), thus holding the probability of an arrival in an increment at some fixed value \( p = \delta \lambda(t) \). Thus, temporarily ignoring the variation of \( \lambda(t) \) within an increment,

\[
\begin{align*}
\Pr\{\tilde{N} \left( t, t + \frac{p}{\lambda(t)} \right) = 0\} &= 1 - p + o(p) \\
\Pr\{\tilde{N} \left( t, t + \frac{p}{\lambda(t)} \right) = 1\} &= p + o(p) \\
\Pr\{\tilde{N} \left( t, t + \frac{p}{\lambda(t)} \right) \geq 2\} &= o(p).
\end{align*}
\]

This partition is defined more precisely by defining \( m(t) \) as

\[
m(t) = \int_0^t \lambda(\tau)d\tau.
\]

\(^9\) We assume that \( \lambda(t) \) is right continuous, i.e., that for each \( t \), \( \lambda(t) \) is the limit of \( \lambda(t+\epsilon) \) as \( \epsilon \) approaches 0 from above. This allows \( \lambda(t) \) to contain discontinuities, as illustrated in Figure 2.7, but follows the convention that the value of the function at the discontinuity is the limiting value from the right. This convention is required in (2.29) to talk about the distribution of arrivals just to the right of time \( t \).
Then the \( i \)th increment ends at that \( t \) for which \( m(t) = i \) \( p \).

\[
\text{Figure 2.7: Partitioning the time axis into increments each with an expected number of arrivals equal to } p. \text{ Each rectangle or trapezoid above has the same area, which ensures that the } i \text{th partition ends where } m(t) = i \ p.
\]

As before, let \( \{Y_i; i \geq 1\} \) be a sequence of IID binary rv's with \( \Pr\{Y_i = 1\} = p \) and \( \Pr\{Y_i = 0\} = 1 - p \). Consider the counting process \( \{N(t); t > 0\} \) in which \( Y_i \), for each \( i \geq 1 \), denotes the number of arrivals in the interval \( (t_{i-1}, t_i] \), where \( t_i \) satisfies \( m(t_i) = i \) \( p \). Thus, \( N(t_i) = Y_1 + Y_2 + \cdots + Y_i \). If \( p \) is decreased as \( 2^{-j} \), each increment is successively split into a pair of increments. Thus by the same argument as in (2.22),

\[
\Pr\{N(t) = n\} = \frac{[1 + o(p)]\{m(t)\}^n \exp[-m(t)]}{n!}.
\]

Similarly, for any interval \( (t, \tau] \), taking \( \bar{m}(t, \tau) = \int_t^\tau \lambda(u)du \), and taking \( t = t_k \), \( \tau = t_i \) for some \( k, i \), we get

\[
\Pr\{\bar{N}(t, \tau) = n\} = \frac{[1 + o(p)]\{\bar{m}(t, \tau)\}^n \exp[-\bar{m}(t, \tau)]}{n!}.
\]

Going to the limit \( p \to 0 \), the counting process \( \{N(t); t > 0\} \) above approaches the non-homogeneous Poisson process under consideration, and we have the following theorem:

**Theorem 2.4.1.** For a non-homogeneous Poisson process with right-continuous arrival rate \( \lambda(t) \) bounded away from zero, the distribution of \( \bar{N}(t, \tau) \), the number of arrivals in \( (t, \tau] \), satisfies

\[
\Pr\{\bar{N}(t, \tau) = n\} = \frac{[\bar{m}(t, \tau)]^n \exp[-\bar{m}(t, \tau)]}{n!} \quad \text{where } \bar{m}(t, \tau) = \int_t^\tau \lambda(u)du.
\]

Hence, one can view a non-homogeneous Poisson process as a (homogeneous) Poisson process over a non-linear time scale. That is, let \( \{N^*(s); s \geq 0\} \) be a (homogeneous) Poisson process with rate 1. The non-homogeneous Poisson process is then given by \( N(t) = N^*(m(t)) \) for each \( t \).

**Example 2.4.1 (The \( M/G/\infty \) Queue).** Using the queueing notation explained in Example 2.3.1, an \( M/G/\infty \) queue indicates a queue with Poisson arrivals, a general service distribution, and an infinite number of servers. Since the \( M/G/\infty \) queue has an infinite number of servers, no arriving customers are ever queued. Each arrival immediately starts to be served by some server, and the service time \( Y_i \) of customer \( i \) is IID over \( i \) with some given distribution function \( G(y) \); the service time is the interval from start to completion.
The expected number of arrivals still in service at time \( \tau \) is then
\[
m(\tau) = \lambda \int_{t=0}^{\tau} [1 - G(\tau - t)] dt = \lambda \int_{t=0}^{\tau} [1 - G(t)] dt.
\] (2.35)

and the PMF of the number in service at time \( \tau \) is given by
\[
\Pr\{N_1(\tau) = n\} = \frac{m(\tau)^n \exp(-m(\tau))}{n!}.
\] (2.36)

Note that as \( \tau \to \infty \), the integral in (2.35) approaches the mean of the service time distribution (i.e., it is the integral of the complementary distribution function, \( 1 - G(t) \), of the service time). This means that in steady state (as \( \tau \to \infty \)), the distribution of the number in service at \( \tau \) depends on the service time distribution only through its mean. This example can be used to model situations such as the number of phone calls taking place at a given epoch. This requires arrivals of new calls to be modeled as a Poisson process and the holding time of each call to be modeled as a random variable independent of other holding times and of call arrival times. Finally, as shown in Figure 2.8, we can regard \( \{N_1(t); 0 < t \leq \tau\} \) as a splitting of the arrival process \( \{N(t); t > 0\} \). By the same type of argument as in Section 2.3, the number of customers who have completed service by time \( \tau \) is independent of the number still in service.
2.5 Conditional arrival densities and order statistics

A diverse range of problems involving Poisson processes are best tackled by conditioning on a given number \( n \) of arrivals in the interval \((0, t]\), i.e., on the event \( N(t) = n \). Because of the incremental view of the Poisson process as independent and stationary arrivals in each incremental interval of the time axis, we would guess that the arrivals should have some sort of uniform distribution given \( N(t) = n \). More precisely, the following theorem shows that the joint density of \( S^{(n)} = (S_1, S_2, \ldots, S_n) \) given \( N(t) = n \) is uniform over the region \( 0 < S_1 < \cdots < S_n < t \).

**Theorem 2.5.1.** Let \( f_{S^{(n)|N(t)=n}}(s^{(n)} | n) \) be the joint density of \( S^{(n)} \) conditional on \( N(t) = n \). This density is constant over the region \( 0 < s_1 < \cdots < s_n < t \) and has the value

\[
f_{S^{(n)|N(t)=n}}(s^{(n)} | n) = \frac{n!}{t^n}.
\]

(2.37)

Two proofs are given, each illustrative of useful techniques.

**Proof 1:** Recall that the joint density of the first \( n+1 \) arrivals \( S^{(n+1)} = (S_1, \ldots, S_n, S_{n+1}) \) with no conditioning is given in (2.15). We first use Bayes law to calculate the joint density of \( S^{(n+1)} \) conditional on \( N(t) = n \).

\[
f_{S^{(n+1)|N(t)=n}}(s^{(n+1)} | n) p_{N(t)}(n) = p_{N(t)|S^{(n+1)}}(n | s^{(n+1)}) f_{S^{(n+1)}}(s^{(n+1)}).
\]

Note that \( N(t) = n \) if and only if \( S_n \leq t \) and \( S_{n+1} > t \). Thus \( p_{N(t)|S^{(n+1)}}(n | s^{(n+1)}) = 1 \) if \( S_n \leq t \) and \( S_{n+1} > t \) and is 0 otherwise. Restricting attention to the case \( N(t) = n, S_n \leq t \) and \( S_{n+1} > t \),

\[
f_{S^{(n+1)|N(t)=n}}(s^{(n+1)} | n) = \frac{f_{S^{(n+1)}}(s^{(n+1)})}{p_{N(t)}(n)} = \frac{\lambda^{n+1} \exp(-\lambda s_{n+1})}{(\lambda t^n \exp(-\lambda t)/n!)} = \frac{n! \lambda \exp[-\lambda(s_{n+1} - t)]}{t^n}.
\]

(2.38)

This is a useful expression, but we are interested in \( S^{(n)} \) rather than \( S^{(n+1)} \). Thus we break up the left side of (2.38) as follows:

\[
f_{S^{(n+1)|N(t)}}(s^{(n+1)} | n) = f_{S^{(n)|N(t)}}(s^{(n)} | n) f_{S_{n+1}|S^{(n)|N(t)}}(s_{n+1} | s^{(n)}, n).
\]

Conditional on \( N(t) = n, S_{n+1} \) is the first arrival epoch after \( t \), which by the memoryless property is conditionally independent of \( S^{(n)} \), again given \( N(t) = n \). Thus that final term is simply \( \lambda \exp(-\lambda(s_{n+1} - t)) \) for \( s_{n+1} > t \). Substituting this into (2.38), the result is (2.37).

\[\square\]

**Proof 2:** This alternative proof derives (2.37) by looking at arrivals in very small increments of size \( \delta \) (see Figure 2.9). For a given \( t \) and a given set of \( n \) times, \( 0 < s_1 < \cdots < s_n < t \), we
calculate the probability that there is a single arrival in each of the intervals \((s_i, s_i + \delta], 1 \leq i \leq n\) and no other arrivals in the interval \((0, t]\). Letting \(A(\delta)\) be this event,

\[
\Pr\{A(\delta)\} = p_{N(s_1)}(0) \ p_{N(s_1, s_1+\delta)}(1) \ p_{\tilde{N}(s_1+s_2)}(0) \ p_{\tilde{N}(s_2, s_2+\delta)}(1) \cdots p_{\tilde{N}(s_n+s_\delta)}(0).
\]

The sum of the lengths of the above intervals is \(t\), so if we represent \(p_{\tilde{N}(s_i,s_i+\delta)}(1)\) as 

\[
\lambda \delta \exp(-\lambda \delta) + o(\delta)
\]

for each \(i\), then

\[
\Pr\{A(\delta)\} = (\lambda \delta)^n \exp(-\lambda t) + \delta^{n-1}o(\delta).
\]

The event \(A(\delta)\) can be characterized as the event that, first, \(N(t) = n\) and, second, that the \(n\) arrivals occur in \([s_i, s_i+\delta]\) for \(1 \leq i \leq n\). Thus we conclude that

\[
f_{g^{(n)}|N(t)}(s^{(n)}|n) = \lim_{\delta \to 0} \frac{\Pr\{A(\delta)\}}{\delta^n p_{N(t)}(n)},
\]

which simplifies to (2.37).

The joint density of the interarrival intervals, \(X^{(n)} = (X_1, \ldots, X_n)\) given \(N(t) = n\) can be found directly from Theorem 2.5.1 simply by making the linear transformation \(X_1 = S_1\) and \(X_i = S_i - S_{i-1}\) for \(2 \leq i \leq n\). The density is unchanged, but the constraint region transforms into \(\sum_{i=1}^n X_i < t\) with \(X_i > 0\) for \(1 \leq i \leq n\) (see Figure 2.10).

\[
f_{X^{(n)}|N(t)}(x^{(n)}|n) = \frac{n!}{t^n} \quad \text{for } x^{(n)} > 0, \sum_{i=1}^n X_i < t. \quad \text{(2.39)}
\]
2.5. **CONDITIONAL ARRIVAL DENSITIES AND ORDER STATISTICS**

It is also instructive to compare the joint distribution of \( S^{(n)} \) conditional on \( N(t) = n \) with the joint distribution of \( n \) IID uniformly distributed random variables, \( U^{(n)} = (U_1, \ldots, U_n) \) on \((0, t]\). For any point \( U^{(n)} = u^{(n)} \), this joint density is

\[
f_{U^{(n)}}(u^{(n)}) = \frac{1}{t^n} \quad \text{for } 0 < u_i \leq t, \ 1 \leq i \leq n.
\]

Both \( f_{S^{(n)}} \) and \( f_{U^{(n)}} \) are uniform over the volume of \( n \)-space where they are non-zero, but as illustrated in Figure 2.11 for \( n = 2 \), the volume for the latter is \( n! \) times larger than the volume for the former. To explain this more fully, we can define a set of random variables \( S_1, \ldots, S_n \), not as arrival epochs in a Poisson process, but rather as the order statistics function of the IID uniform variables \( U_1, \ldots, U_n \); that is

\[
S_1 = \min(U_1, \ldots, U_n); \ S_2 = 2^{\text{nd}} \text{ smallest } (U_1, \ldots, U_n); \text{ etc.}
\]

![Figure 2.11: Density for the order statistics of an IID 2-dimensional uniform distribution. Note that the square over which \( f_{U^{(2)}} \) is non-zero contains one triangle where \( u_2 > u_1 \) and another of equal size where \( u_1 > u_2 \). Each of these maps, by a permutation mapping, to the single triangle where \( s_2 > s_1 \).](image)

The \( n \)-cube is partitioned into \( n! \) regions, one where \( u_1 < u_2 < \cdots < u_n \). For each permutation \( \pi(i) \) of the integers 1 to \( n \), there is another region\(^{10}\) where \( u_{\pi(1)} < u_{\pi(2)} < \cdots < u_{\pi(n)} \). By symmetry, each of these regions has the same volume, which then must be \( 1/n! \) of the volume \( t^n \) of the \( n \)-cube.

All of these \( n! \) regions map to the same region of ordered values. Thus these order statistics have the same joint probability density function as the arrival epochs \( S_1, \ldots, S_n \) conditional on \( N(t) = n \). Anything we know (or can discover) about order statistics is valid for arrival epochs given \( N(t) = n \) and vice versa.\(^{11}\)

Next we want to find the marginal distribution functions of the individual \( S_i \), conditional on \( N(t) = n \). Starting with \( S_1 \), and viewing it as the minimum of the IID uniformly distributed

\(^{10}\)As usual, we are ignoring those points where \( u_i = u_j \) for some \( i, j \), since the set of such points has 0 probability.

\(^{11}\)There is certainly also the intuitive notion, given \( n \) arrivals in \((0, t]\), and given the stationary and independent increment properties of the Poisson process, that those \( n \) arrivals can be viewed as uniformly distributed. One way to view this is to visualize the Poisson process as the sum of a very large number \( k \) of independent processes of rate \( \lambda/k \) each. Then, given \( N(t) = n \), with \( k >> n \), there is negligible probability of more than one arrival from any one process, and for each of the \( n \) processes with arrivals, that arrival is uniformly distributed in \((0, t]\).
variables $U_1, \ldots, U_n$, we recognize that $S_1 > \tau$ if and only if $U_i > \tau$ for all $i$, $1 \leq i \leq n$. Thus,

$$\Pr\{S_1 > \tau \mid N(t)=n\} = \left[\frac{t-\tau}{t}\right]^n \quad \text{for } 0 < \tau \leq t. \quad (2.40)$$

For $S_2$ to $S_n$, the density is slightly simpler in appearance than the distribution function. To find $f_{S_i|N(t)}(s_i \mid n)$, look at $n$ uniformly distributed rv's in $(0, t]$. The probability that one of these lies in the interval $(s_i, s_i + dt]$ is $(n dt)/t$. Out of the remaining $n - 1$, the probability that $i - 1$ lie in the interval $(0, s_i]$ is given by the binomial distribution with probability of success $s_i/t$. Thus the desired density is

$$f_{S_i|N(t)}(s_i \mid n) = \frac{s_i^{i-1}(t-s_i)^{n-i}(n-1)!}{t^{n-1}(n-i)!(i-1)!} \quad \text{for } i = 1, \ldots, n.$$  \quad (2.41)

It is easy to find the expected value of $S_i$ conditional on $N(t) = n$ by integrating the complementary distribution function in (2.40), getting

$$E\{S_i \mid N(t)=n\} = \frac{t}{n+1}. \quad (2.42)$$

We come back later to find $E\{S_i \mid N(t) = n\}$ for $2 \leq i \leq n$. First, we look at the marginal distributions of the interarrival intervals. Recall from (2.39) that

$$f_{X^{(n)}|N(t)}(x^{(n)} \mid n) = \frac{n!}{t^n} \quad \text{for } X^{(n)} > 0, \sum_{i=1}^n X_i < t. \quad (2.43)$$

The joint density is the same for all points in the constraint region, and the constraint does not distinguish between $X_1$ to $X_n$. Thus $X_1, \ldots, X_n$ must all have the same marginal distribution, and more generally the marginal distribution of any subset of the $X_i$ can depend only on the size of the subset. We have found the distribution of $S_1$, which is the same as $X_1$, and thus

$$\Pr\{X_i > \tau \mid N(t)=n\} = \left[\frac{t-\tau}{t}\right]^n \quad \text{for } 1 \leq i \leq n \text{ and } 0 < \tau \leq t. \quad (2.44)$$

$$E\{X_i \mid N(t)=n\} = \frac{t}{n+1} \quad \text{for } 1 \leq i \leq n. \quad (2.45)$$

From this, we see immediately that for $1 \leq i \leq n,$

$$E\{S_i \mid N(t) = n\} = \frac{it}{n+1} \quad (2.46)$$

One could go on and derive joint distributions of all sorts at this point, but there is one additional type of interval that must be discussed. Define $X_{n+1}^* = t - S_n$ to be the interval from the largest arrival epoch before $t$ to $t$ itself. Rewriting (2.43),

$$f_{X^{(n)}|N(t)}(x^{(n)} \mid n) = \frac{n!}{t^n} \quad \text{for } X^{(n)} > 0, \ X_{n+1}^* > 0, \ \sum_{i=1}^n X_i + X_{n+1}^* = t.$$
The constraints above are symmetric in $X_1, \ldots, X_n, X^*_n, \ldots, X^*_{n+1}$, and, within the constraint region, the joint density of $X_1, \ldots, X_n$ (conditional on $N(t) = n$) is uniform. Note that there is no joint density over $X_1, \ldots, X_n, X^*_{n+1}$ conditional on $N(t) = n$, since $X^*_{n+1}$ is then a deterministic function of $X_1, \ldots, X_n$. However, the density over $X_1, \ldots, X_n$ can be replaced by a density over any other $n$ rv’s out of $X_1, \ldots, X_n, X^*_{n+1}$ by a linear transformation with unit determinant. Thus $X^*_{n+1}$ has the same marginal distribution as each of the $X_t$. This gives us a partial check on our work, since the interval $(0, t]$ is divided into $n+1$ intervals of sizes $X_1, X_2, \ldots, X_n, X^*_{n+1}$, and each of these has a mean size $t/(n+1)$. We also see that the joint distribution function of any proper subset of $X_1, X_2, \ldots, X_n, X^*_{n+1}$ depends only on the size of the subset and not the particular rv’s in the subset.

One important consequence of this is that we can look at the arrivals in a segment $(0, t]$ of a Poisson process either forward or backward\(^{12}\) in time and they ‘look the same.’ Looked at backwards, the interarrival intervals are $X^*_{n+1}, X_n, \ldots, X_2$. These intervals are IID, and $X_1$ is then determined as $t - X^*_{n+1} - X_n - \cdots - X_2$. We will not make any particular use of this property here, but we will later explore this property of time-reversibility for other types of processes. For Poisson processes, this reversibility is intuitively obvious from the stationary and independent properties. It is less obvious how to express this condition by equations, but that is not really necessary at this point.

### 2.6 Summary

We started the chapter with three equivalent definitions of a Poisson process—first as a renewal process with exponentially distributed inter-renewal intervals, second as a stationary and independent increment counting process with a Poisson distributed number of arrivals in each interval, and third essentially as a limit of shrinking Bernoulli processes. We saw that each definition provided its own insights into the properties of the process. We emphasized the importance of the memoryless property of the exponential distribution, both as a useful tool in problem solving and as an underlying reason why the Poisson process is so simple.

We next showed that the sum of independent Poisson processes is again a Poisson process. We also showed that if the arrivals in a Poisson process are independently routed to different locations with some fixed probability assignment, then the arrivals at these locations form independent Poisson processes. This ability to view independent Poisson processes either independently or as a splitting of a combined process is a powerful technique for finding almost trivial solutions to many problems.

It was next shown that a non-homogeneous Poisson process could be viewed as a (homogeneous) Poisson process on a non-linear time scale. This allows all the properties of (homogeneous) Poisson processes to be applied directly to the non-homogeneous case. The simplest and most useful result from this is (2.34), showing that the number of arrivals in

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\(^{12}\)This must be interpreted carefully, since if we ask about the distribution to the next arrival from some $\tau \in (0, t]$, it is exponential (possibly occurring after $t$). But if we look for the distribution of the previous arrival before $\tau$, we usually truncate the distribution at 0. Thus the proper interpretation is to look only at the interval $(0, t]$ under the condition of a given number of arrivals in that interval.
any interval has a Poisson PMF. This result was used to show that the number of customers in service at any given time $\tau$ in an $M/G/\infty$ queue has a Poisson PMF with a mean approaching $\lambda$ times the expected service time in the limit as $\tau \to \infty$.

Finally we looked at the distribution of arrival epochs conditional on $n$ arrivals in the interval $(0, t]$. It was found that these arrival epochs had the same joint distribution as the order statistics of $n$ uniform IID rv’s in $(0, t]$. By using symmetry and going back and forth between the uniform variables and the Poisson process arrivals, we found the distribution of the interarrival times, the arrival epochs, and various conditional distributions.

### 2.7 Exercises

**Exercise 2.1.** a) Find the Erlang density $f_{S_n}(t)$ by convolving $f_X(x) = \lambda \exp(-\lambda x)$ with itself $n$ times.

b) Find the moment generating function of $X$ (or find the Laplace transform of $f_X(x)$), and use this to find the moment generating function (or Laplace transform) of $S_n = X_1 + X_2 + \cdots + X_n$. Invert your result to find $f_{S_n}(t)$.

c) Find the Erlang density by starting with (2.15) and then calculating the marginal density for $S_n$.

**Exercise 2.2.** a) Find the mean, variance, and moment generating function of $N(t)$, as given by (2.16).

b) Show by discrete convolution that the sum of two independent Poisson rv’s is again Poisson.

c) Show by using the properties of the Poisson process that the sum of two independent Poisson rv’s must be Poisson.

**Exercise 2.3.** The purpose of this exercise is to give an alternate derivation of the Poisson distribution for $N(t)$, the number of arrivals in a Poisson process up to time $t$. Let $\lambda$ be the rate of the process.

a) Find the conditional probability $\Pr\{N(t) = n \mid S_n = \tau\}$ for all $\tau \leq t$.

b) Using the Erlang density for $S_n$, use (a) to find $\Pr\{N(t) = n\}$.

**Exercise 2.4.** Assume that a counting process $\{N(t); t > 0\}$ has the independent and stationary increment properties and satisfies (2.16) (for all $t > 0$). Let $X_1$ be the epoch of the first arrival and $X_n$ be the interarrival time between the $n - 1$st and the $n$th arrival. Use only these assumptions in doing the following parts of this exercise.

a) Show that $\Pr\{X_1 > x\} = e^{-\lambda x}$.

b) Let $S_{n-1}$ be the epoch of the $n - 1$st arrival. Show that $\Pr\{X_n > x \mid S_{n-1} = \tau\} = e^{-\lambda x}$.

c) For each $n > 1$, show that $\Pr\{X_n > x\} = e^{-\lambda x}$ and that $X_n$ is independent of $S_{n-1}$.

d) Argue that $X_n$ is independent of $X_1, X_2, \ldots X_{n-1}$.
Exercise 2.5. The point of this exercise is to show that the sequence of PMF’s for a Bernoulli counting process does not specify the process. In other words, knowing that $N(t)$ satisfies the binomial distribution for all $t$ does not mean that the process is Bernoulli. This helps us understand why the second definition of a Poisson process requires stationary and independent increments as well as the Poisson distribution for $N(t)$.

a) Let $Y_1, Y_2, Y_3, \ldots$ be a sequence of binary rvs in which each rv is 0 or 1 with equal probability. Find a joint distribution for $Y_1, Y_2, Y_3$ that satisfies the binomial distribution, $p_{N(t)}(k) = (\binom{t}{k}) 2^{-t}$ for $t = 1, 2, 3$ and $0 \leq k \leq t$, but for which $Y_1, Y_2, Y_3$ are not independent. One simple solution for this contains four 3-tuples with probability $1/8$ each, two 3-tuples with probability $1/4$ each, and two 3-tuples with probability $0$. Note that by making the subsequent arrivals IID and equiprobable, you have an example where $N(t)$ is binomial for all $t$ but the process is not Bernoulli. Hint: Use the binomial for $t = 3$ to find two 3-tuples that must have probability $1/8$. Combine this with the binomial for $t = 2$ to find two other 3-tuples that must have probability $1/8$. Finally look at the constraints imposed by the binomial distribution on the remaining four 3-tuples.

b) Generalize part a) to the case where $Y_1, Y_2, Y_3$ satisfy $Pr\{Y_i = 1\} = p$ and $Pr\{Y_i = 0\} = 1 - p$. Assume $p < 1/2$ and find a joint distribution on $Y_1, Y_2, Y_3$ that satisfies the binomial distribution, but for which the 3-tuple $(0, 1, 1)$ has zero probability.

c) More generally yet, view a joint PMF on binary $t$-tuples as a nonnegative vector in a $2^t$ dimensional vector space. Each binomial probability $p_{N(t)}(k) = (\binom{t}{k}) p^k (1 - p)^{t-k}$ constitutes a linear constraint on this vector. For each $\tau$, show that one of these constraints may be replaced by the constraint that the components of the vector sum to 1.

d) Using part c), show that at most $(t + 1)t/2 + 1$ of the binomial constraints are linearly independent. Note that this means that the linear space of vectors satisfying these binomial constraints has dimension at least $2^t - (t + 1)t/2 - 1$. This linear space has dimension 1 for $t = 3$, explaining the results in parts a) and b). It has a rapidly increasing dimension for $t > 3$, suggesting that the binomial constraints are relatively ineffectual for constraining the joint PMF of a joint distribution. More work is required for the case of $t > 3$ because of all the inequality constraints, but it turns out that this large dimensionality remains.

Exercise 2.6. Let $h(x)$ be a positive function of a real variable that satisfies $h(x + t) = h(x) + h(t)$ and let $h(1) = c$.

a) Show that for integer $k > 0$, $h(k) = kc$.

b) Show that for integer $j > 0$, $h(1/j) = c/j$.

c) Show that for all integer $k, j$, $h(k/j) = ck/j$.

d) The above parts show that $h(x)$ is linear in positive rational numbers. For very picky mathematicians, this does not guarantee that $h(x)$ is linear in positive real numbers. Show that if $h(x)$ is also monotonic in $x$, then $h(x)$ is linear in $x > 0$.

Exercise 2.7. Assume that a counting process $\{N(t); t > 0\}$ has the independent and sta-
tionary increment properties and, for all $t > 0$, satisfies
\[
\Pr\{\tilde{N}(t, t + \delta) = 0\} = 1 - \lambda \delta + o(\delta)
\]
\[
\Pr\{\tilde{N}(t, t + \delta) = 1\} = \lambda \delta + o(\delta)
\]
\[
\Pr\{\tilde{N}(t, t + \delta) > 1\} = o(\delta).
\]

a) Let $F_0(\tau) = \Pr\{N(\tau) = 0\}$ and show that $dF_0(\tau)/d\tau = -\lambda F_0(\tau)$.

b) Show that $X_1$, the time of the first arrival, is exponential with parameter $\lambda$.

c) Let $F_n(\tau) = \Pr\{\tilde{N}(t, t + \tau) = 0 \mid S_{n-1} = t\}$ and show that $dF_n(\tau)/d\tau = -\lambda F_n(\tau)$.

d) Argue that $X_n$ is exponential with parameter $\lambda$ and independent of earlier arrival times.

**Exercise 2.8.** Let $t > 0$ be an arbitrary time, let $Z_1$ be the duration of the interval from $t$ until the next arrival after $t$. Let $Z_m$, for each $m > 1$, be the interarrival time from the epoch of the $m-1^{st}$ arrival after $t$ until the $m$th arrival.

a) Given that $N(t) = n$, explain why $Z_m = X_{m+n}$ for $m > 1$ and $Z_1 = X_{n+1} - t + S_n$.

b) Conditional on $N(t) = n$ and $S_n = \tau$, show that $Z_1, Z_2, \ldots$ are IID.

c) Show that $Z_1, Z_2, \ldots$ are IID.

**Exercise 2.9.** Consider a “shrinking Bernoulli” approximation $N_\delta(m\delta) = Y_1 + \cdots + Y_m$ to a Poisson process as described in Subsection 2.2.5.

a) Show that
\[
\Pr\{N_\delta(m\delta) = n\} = \binom{m}{n}(\lambda \delta)^n(1 - \lambda \delta)^{m-n}.
\]

b) Let $t = m\delta$, and let $t$ be fixed for the remainder of the exercise. Explain why
\[
\lim_{\delta \to 0} \Pr\{N_\delta(t) = n\} = \lim_{m \to \infty} \binom{m}{n}\left(\frac{\lambda t}{m}\right)^n\left(1 - \frac{\lambda t}{m}\right)^{m-n}.
\]

where the limit on the left is taken over values of $\delta$ that divide $t$.

c) Derive the following two equalities:
\[
\lim_{m \to \infty} \binom{m}{n}\frac{1}{m^n} = \frac{1}{n!}; \quad \text{and} \quad \lim_{m \to \infty} \left(1 - \frac{\lambda t}{m}\right)^{m-n} = e^{-\lambda t}.
\]

d) Conclude from this that for every $t$ and every $n$, $\lim_{\delta \to 0} \Pr\{N_\delta(t)=n\} = \Pr\{N(t)=n\}$ where $\{N(t); t > 0\}$ is a Poisson process of rate $\lambda$.  

2.7. EXERCISES

**Exercise 2.10.** Let \( \{N(t); \ t > 0\} \) be a Poisson process of rate \( \lambda \).

a) Find the joint probability mass function (PMF) of \( N(t) \), \( N(t + s) \) for \( s > 0 \).

b) Find \( E[N(t) \cdot N(t + s)] \) for \( s > 0 \).

c) Find \( E[\tilde{N}(t_1, t_3) \cdot \tilde{N}(t_2, t_4)] \) where \( \tilde{N}(t, \tau) \) is the number of arrivals in \( (t, \tau] \) and \( t_1 < t_2 < t_3 < t_4 \).

**Exercise 2.11.** An elementary experiment is independently performed \( N \) times where \( N \) is a Poisson rv of mean \( \lambda \). Let \( \{a_1, a_2, \ldots, a_K\} \) be the set of sample points of the elementary experiment and let \( p_k, 1 \leq k \leq K \), denote the probability of \( a_k \).

a) Let \( N_k \) denote the number of elementary experiments performed for which the output is \( a_k \). Find the PMF for \( N_k \) \( (1 \leq k \leq K) \). (Hint: no calculation is necessary.)

b) Find the PMF for \( N_1 + N_2 \).

c) Find the conditional PMF for \( N_1 \) given that \( N = n \).

d) Find the conditional PMF for \( N_1 + N_2 \) given that \( N = n \).

e) Find the conditional PMF for \( N \) given that \( N_1 = n_1 \).

**Exercise 2.12.** Starting from time 0, northbound buses arrive at 77 Mass. Avenue according to a Poisson process of rate \( \lambda \). Customers arrive according to an independent Poisson process of rate \( \mu \). When a bus arrives, all waiting customers instantly enter the bus and subsequent customers wait for the next bus.

a) Find the PMF for the number of customers entering a bus (more specifically, for any given \( m \), find the PMF for the number of customers entering the \( m \)th bus).

b) Find the PMF for the number of customers entering the \( m \)th bus given that the inter-arrival interval between bus \( m - 1 \) and bus \( m \) is \( x \).

c) Given that a bus arrives at time 10:30 PM, find the PMF for the number of customers entering the next bus.

d) Given that a bus arrives at 10:30 PM and no bus arrives between 10:30 and 11, find the PMF for the number of customers on the next bus.

e) Find the PMF for the number of customers waiting at some given time, say 2:30 PM (assume that the processes started infinitely far in the past). Hint: think of what happens moving backward in time from 2:30 PM.

f) Find the PMF for the number of customers getting on the next bus to arrive after 2:30. Hint: this is different from part a); look carefully at part e).

g) Given that I arrive to wait for a bus at 2:30 PM, find the PMF for the number of customers getting on the next bus.
Exercise 2.13. a) Show that the arrival epochs of a Poisson process satisfy
\[ f_{S(n)|S_{n+1}}(s^{(n)}|s_{n+1}) = \frac{n!}{s_{n+1}^n}. \]

Hint: This is easy if you use only the results of Section 2.2.2.

b) Contrast this with the result of Theorem 2.5.1

Exercise 2.14. Equation (2.41) gives \( f_S(s_i \mid N(t)=n) \), which is the density of random variable \( S_i \) conditional on \( N(t) = n \) for \( n \geq i \). Multiply this expression by \( \Pr\{N(t) = n\} \) and sum over \( n \) to find \( f_S(s_i) \); verify that your answer is indeed the Erlang density.

Exercise 2.15. Consider generalizing the bulk arrival process in Figure 2.5. Assume that the epochs at which arrivals occur form a Poisson process \( \{N(t); t > 0\} \) of rate \( \lambda \). At each arrival epoch, \( S_n \), the number of arrivals, \( Z_n \), satisfies \( \Pr\{Z_n=1\} = p, \Pr\{Z_n=2\} = 1 - p \). The variables \( Z_n \) are IID.

a) Let \( \{N_1(t); t > 0\} \) be the counting process of the epochs at which single arrivals occur. Find the PMF of \( N_1(t) \) as a function of \( t \). Similarly, let \( \{N_2(t); t \geq 0\} \) be the counting process of the epochs at which double arrivals occur. Find the PMF of \( N_2(t) \) as a function of \( t \).

b) Let \( \{N_B(t); t \geq 0\} \) be the counting process of the total number of arrivals. Give an expression for the PMF of \( N_B(t) \) as a function of \( t \).

Exercise 2.16. a) For a Poisson counting process of rate \( \lambda \), find the joint probability density of \( S_1, S_2, \ldots, S_{n-1} \) conditional on \( S_n = t \).

b) Find \( \Pr\{X_1 > \tau \mid S_n=t\} \).

c) Find \( \Pr\{X_i > \tau \mid S_n=t\} \) for \( 1 \leq i \leq n \).

d) Find the density \( f_{S_i|S_n}(s_i|t) \) for \( 1 \leq i \leq n - 1 \).

e) Give an explanation for the striking similarity between the condition \( N(t) = n - 1 \) and the condition \( S_n = t \).

Exercise 2.17. a) For a Poisson process of rate \( \lambda \), find \( \Pr\{N(t)=n \mid S_1=\tau\} \) for \( t > \tau \) and \( n \geq 1 \).

b) Using this, find \( f_{S_1}(\tau \mid N(t)=n) \)

c) Check your answer against (2.40).

Exercise 2.18. Consider a counting process in which the rate is a rv \( \Lambda \) with probability density \( f_{\Lambda}(\lambda) = \alpha e^{-\alpha \lambda} \) for \( \lambda > 0 \). Conditional on a given sample value \( \lambda \) for the rate, the counting process is a Poisson process of rate \( \lambda \) (i.e., nature first chooses a sample value \( \lambda \) and then generates a sample path of a Poisson process of that rate \( \lambda \)).
2.7. EXERCISES

a) What is $\Pr\{N(t)=n \mid \Lambda=\lambda\}$, where $N(t)$ is the number of arrivals in the interval $(0, t]$ for some given $t > 0$?

b) Show that $\Pr\{N(t)=n\}$, the unconditional PMF for $N(t)$, is given by

$$\Pr\{N(t)=n\} = \frac{\alpha t^n}{(t + \alpha)^{n+1}}.$$  

\[86x106]

c) Find $f_\lambda(\lambda \mid N(t)=n)$, the density of $\lambda$ conditional on $N(t)=n$.

d) Find $E[\lambda \mid N(t)=n]$ and interpret your result for very small $t$ with $n = 0$ and for very large $t$ with $n$ large.

e) Find $E[\lambda \mid N(t)=n, S_1, S_2, \ldots, S_n]$. (Hint: consider the distribution of $S_1, \ldots, S_n$ conditional on $N(t)$ and $\Lambda$). Find $E[\lambda \mid N(t)=n, N(\tau)=m]$ for some $\tau < t$.

Exercise 2.19. a) Use Equation (2.41) to find $E[\lambda_i \mid N(t)=n]$. Hint: When you integrate $s_i f_{S_i} (s_i \mid N(t)=n)$, compare this integral with $f_{S_{i+1}} (s_i \mid N(t)=n + 1)$ and use the fact that the latter expression is a probability density.

b) Find the second moment and the variance of $S_i$ conditional on $N(t)=n$. Hint: Extend the previous hint.

c) Assume that $n$ is odd, and consider $i = (n + 1)/2$. What is the relationship between $S_i$, conditional on $N(t)=n$, and the sample median of $n$ IID uniform random variables.

d) Give a weak law of large numbers for the above median.

Exercise 2.20. Suppose cars enter a one-way infinite length, infinite lane highway at a Poisson rate $\lambda$. The $i$th car to enter chooses a velocity $V_i$ and travels at this velocity. Assume that the $V_i$’s are independent positive rv’s having a common distribution $F$. Derive the distribution of the number of cars that are located in an interval $(0, a)$ at time $t$.

Exercise 2.21. Consider an M/G/∞ queue, i.e., a queue with Poisson arrivals of rate $\lambda$ in which each arrival $i$, independent of other arrivals, remains in the system for a time $X_i$, where $\{X_i \mid i \geq 1\}$ is a set of IID rv’s with some given distribution function $F(x)$.

You may assume that the number of arrivals in any interval $(t, t + \epsilon)$ that are still in the system at some later time $\tau \geq t + \epsilon$ is statistically independent of the number of arrivals in that same interval $(t, t + \epsilon)$ that have departed from the system by time $\tau$.

a) Let $N(\tau)$ be the number of customers in the system at time $\tau$. Find the mean, $m(\tau)$, of $N(\tau)$ and find $\Pr\{N(\tau) = n\}$.

b) Let $D(\tau)$ be the number of customers that have departed from the system by time $\tau$. Find the mean, $E[D(\tau)]$, and find $\Pr\{D(\tau) = d\}$.

c) Find $\Pr\{N(\tau) = n, D(\tau) = d\}$.

d) Let $A(\tau)$ be the total number of arrivals up to time $\tau$. Find $\Pr\{N(\tau) = n \mid A(\tau) = a\}$.

e) Find $\Pr\{D(\tau + \epsilon) - D(\tau) = d\}$.
Exercise 2.22. The voters in a given town arrive at the place of voting according to a Poisson process of rate $\lambda = 100$ voters per hour. The voters independently vote for candidate $A$ and candidate $B$ each with probability $1/2$. Assume that the voting starts at time $0$ and continues indefinitely.

a) Conditional on 1000 voters arriving during the first 10 hours of voting, find the probability that candidate $A$ receives $n$ of those votes.

b) Again conditional on 1000 voters during the first 10 hours, find the probability that candidate $A$ receives $n$ votes in the first 4 hours of voting.

c) Let $T$ be the epoch of the arrival of the first voter voting for candidate $A$. Find the density of $T$.

d) Find the PMF of the number of voters for candidate $B$ who arrive before the first voter for $A$.

e) Define the $n$th voter as a reversal if the $n$th voter votes for a different candidate than the $n-1$st. For example, in the sequence of votes $AABAABB$, the third, fourth, and sixth voters are reversals; the third and sixth are $A$ to $B$ reversals and the fourth is a $B$ to $A$ reversal. Let $N(t)$ be the number of reversals up to time $t$ ($t$ in hours). Is $\{N(t); t > 0\}$ a Poisson process? Explain.

f) Find the expected time (in hours) between reversals.

g) Find the probability density of the time between reversals.

h) Find the density of the time from one $A$ to $B$ reversal to the next $A$ to $B$ reversal.

Exercise 2.23. Let $\{N_1(t); t > 0\}$ be a Poisson counting process of rate $\lambda$. Assume that the arrivals from this process are switched on and off by arrivals from a second independent Poisson process $\{N_2(t); t > 0\}$ of rate $\gamma$.

\[
\begin{array}{cccccccc}
\text{rate } \lambda & x & x & x & x & x & x & x & N_1(t) \\
\text{rate } \gamma & \leftarrow & x & \leftarrow & x & \leftarrow & x & \leftarrow & N_2(t) \\
\hline
& x & \leftarrow & x & \leftarrow & x & \leftarrow & N_A(t) \\
\end{array}
\]

Let $\{N_A(t); t \geq 0\}$ be the switched process; that is $N_A(t)$ includes the arrivals from $\{N_1(t); t > 0\}$ during periods when $N_2(t)$ is even and excludes the arrivals from $\{N_1(t); t > 0\}$ while $N_2(t)$ is odd.

a) Find the PMF for the number of arrivals of the first process, $\{N_1(t); t > 0\}$, during the $n$th period when the switch is on.

b) Given that the first arrival for the second process occurs at epoch $\tau$, find the conditional PMF for the number of arrivals of the first process up to $\tau$.

c) Given that the number of arrivals of the first process, up to the first arrival for the second process, is $n$, find the density for the epoch of the first arrival from the second process.
d) Find the density of the interarrival time for \( \{ N_A(t); t \geq 0 \} \). Note: This part is quite messy and is done most easily via Laplace transforms.

**Exercise 2.24.** Let us model the chess tournament between Fisher and Spassky as a stochastic process. Let \( X_i \), for \( i \geq 1 \), be the duration of the \( i \)th game and assume that \( \{ X_i; i \geq 1 \} \) is a set of IID exponentially distributed rv’s each with density \( f_X(x) = \lambda e^{-\lambda x} \). Suppose that each game (independently of all other games, and independently of the length of the games) is won by Fisher with probability \( p \), by Spassky with probability \( q \), and is a draw with probability \( 1 - p - q \). The first player to win \( n \) games is defined to be the winner, but we consider the match up to the point of winning as being embedded in an unending sequence of games.

a) Find the distribution of time, from the beginning of the match, until the completion of the first game that is won (i.e., that is not a draw). Characterize the process of the number \( \{ N(t); t > 0 \} \) of games won up to and including time \( t \). Characterize the process of the number \( \{ N_F(t); t \geq 0 \} \) of games won by Fisher and the number \( \{ N_S(t); t \geq 0 \} \) won by Spassky.

b) For the remainder of the problem, assume that the probability of a draw is zero; i.e., that \( p + q = 1 \). How many of the first \( 2n - 1 \) games must be won by Fisher in order to win the match?

c) What is the probability that Fisher wins the match? Your answer should not involve any integrals. Hint: consider the unending sequence of games and use part b).

d) Let \( T \) be the epoch at which the match is completed (i.e., either Fisher or Spassky wins). Find the distribution function of \( T \).

e) Find the probability that Fisher wins and that \( T \) lies in the interval \( (t, t + \delta) \) for arbitrarily small \( \delta \).

**Exercise 2.25.** a) Find the conditional density of \( S_{i+1} \), conditional on \( N(t) = n \) and \( S_i = s_i \).

b) Use part a) to find the joint density of \( S_1, \ldots, S_n \) conditional on \( N(t) = n \). Verify that your answer agrees with (2.37).

**Exercise 2.26.** A two-dimensional Poisson process is a process of randomly occurring special points in the plane such that (i) for any region of area \( A \) the number of special points in that region has a Poisson distribution with mean \( \lambda A \), and (ii) the number of special points in nonoverlapping regions is independent. For such a process consider an arbitrary location in the plane and let \( X \) denote its distance from its nearest special point (where distance is measured in the usual Euclidean manner). Show that

a) \( \Pr \{ X > t \} = \exp(-\lambda \pi t^2) \)

b) \( \mathbb{E} [X] = 1/(2\sqrt{\lambda}) \).
Exercise 2.27. This problem is intended to show that one can analyze the long term behavior of queueing problems by using just notions of means and variances, but that such analysis is awkward, justifying understanding the strong law of large numbers. Consider an M/G/1 queue. The arrival process is Poisson with \( \lambda = 1 \). The expected service time, \( \mathbb{E}[Y] \), is 1/2 and the variance of the service time is given to be 1.

a) Consider \( S_n \), the time of the \( n \)th arrival, for \( n = 10^{12} \). With high probability, \( S_n \) will lie within 3 standard derivations of its mean. Find and compare this mean and the 3\( \sigma \) range.

b) Let \( V_n \) be the total amount of time during which the server is busy with these \( n \) arrivals (i.e., the sum of \( 10^{12} \) service times). Find the mean and 3\( \sigma \) range of \( V_n \).

c) Find the mean and 3\( \sigma \) range of \( I_n \), the total amount of time the server is idle up until \( S_n \) (take \( I_n \) as \( S_n - V_n \), thus ignoring any service time after \( S_n \)).

d) An idle period starts when the server completes a service and there are no waiting arrivals; it ends on the next arrival. Find the mean and variance of an idle period. Are successive idle periods IID?

e) Combine (c) and (d) to estimate the total number of idle periods up to time \( S_n \). Use this to estimate the total number of busy periods.

f) Combine (e) and (b) to estimate the expected length of a busy period.

Exercise 2.28. The purpose of this problem is to illustrate that for an arrival process with independent but not identically distributed interarrival intervals, \( X_1, X_2, \ldots \), the number of arrivals \( N(t) \) in the interval \( (0, t] \) can be a defective rv. In other words, the ‘counting process’ is not a stochastic process according to our definitions. This illustrates that it is necessary to prove that the counting rv’s for a renewal process are actually rv’s.

a) Let the distribution function of the \( i \)th interarrival interval for an arrival process be \( F_{X_i}(x_i) = 1 - \exp(-\alpha^{-1}x_i) \) for some fixed \( \alpha \in (0, 1) \). Let \( S_n = X_1 + \cdots X_n \) and show that

\[
\mathbb{E}[S_n] = \frac{\alpha(1 - \alpha^n)}{1 - \alpha}.
\]

b) Sketch a ‘reasonable’ sample path for \( N(t) \).

c) Use the Markov inequality on \( \Pr\{S_n \geq t\} \) to find an upper bound on \( \Pr\{N(t) < n\} \) that is smaller than 1 for all \( n \) and for large enough \( t \). Use this to show that \( N(t) \) is defective for large enough \( t \).

d) (For those looking for a challenge) Show that \( N(t) \) is defective for all \( t > 0 \). Hint: Use the Markov inequality to find an upper bound on \( \Pr\{S_m - S_n \leq t/2\} \) for all \( m > n \) for any fixed \( n \). Show that, for any \( t > 0 \), this is bounded below 1 for large enough \( n \). Then show that \( S_n \) has a density that is positive for all \( t > 0 \).