

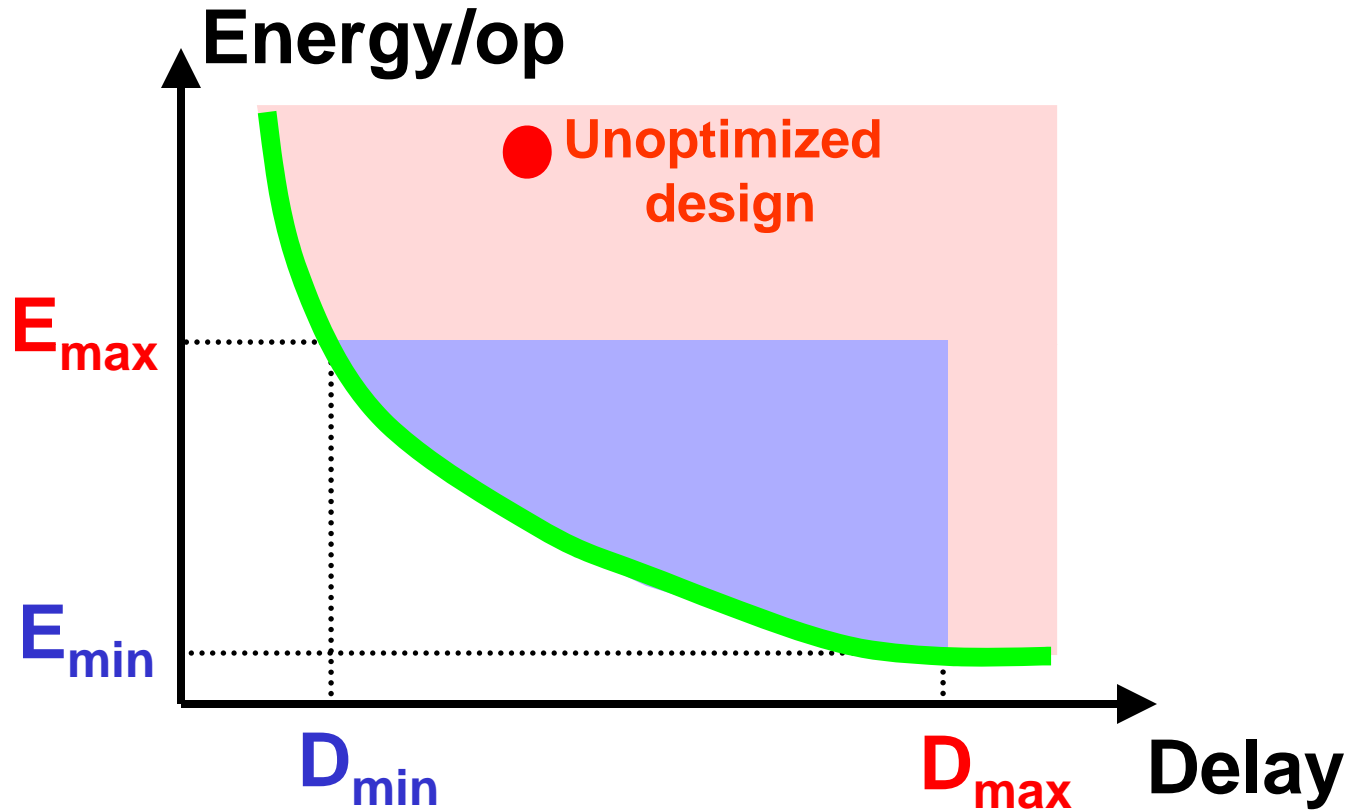
# Methods for True Power Minimization

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Borivoje Nikolic<sup>1</sup> and Vladimir Stojanovic<sup>2</sup>

<sup>1</sup>Berkeley Wireless Research Center, UC Berkeley

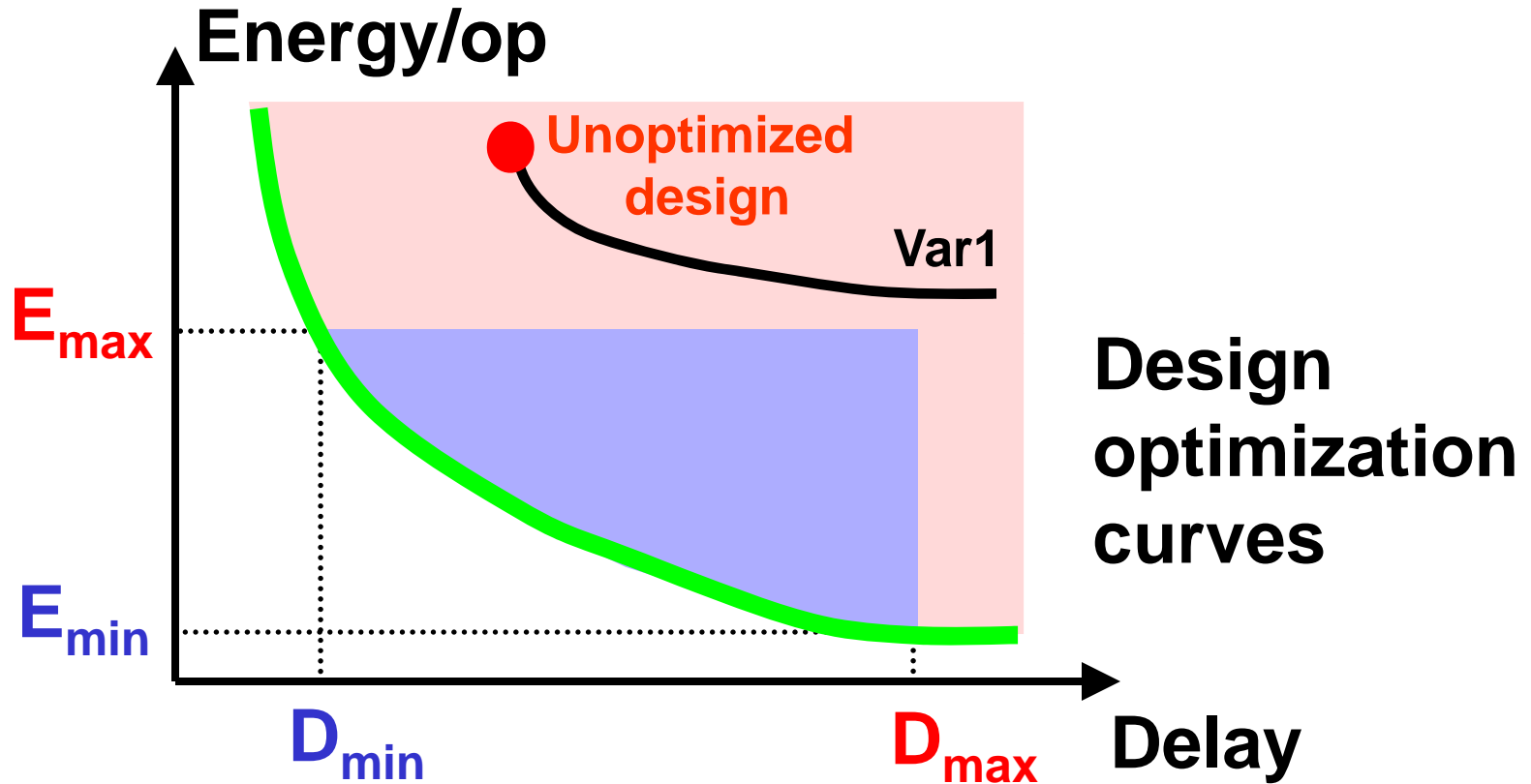
<sup>2</sup>Stanford University

# Power limited operation



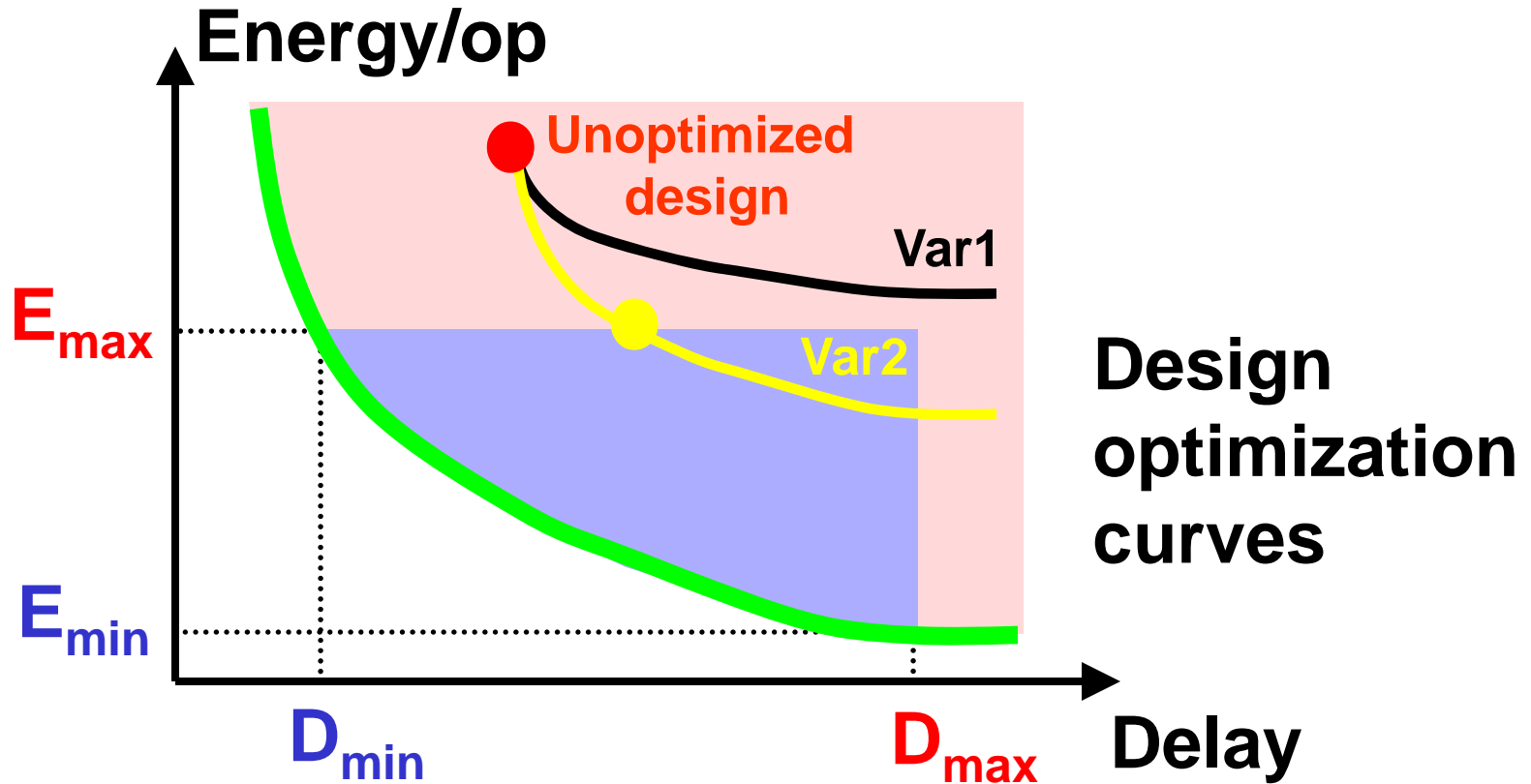
**Achieve the highest performance  
under the power cap**

# Power limited operation



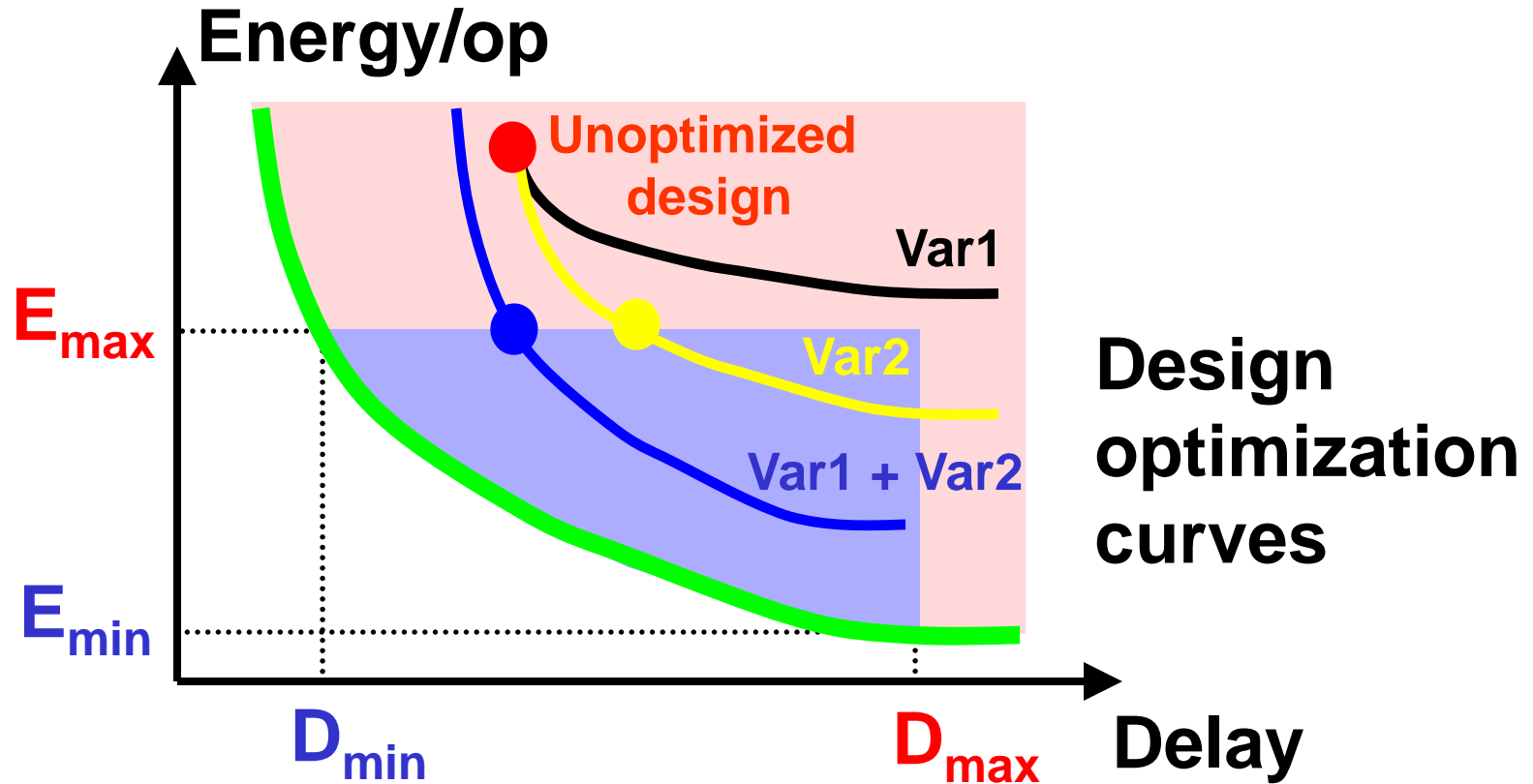
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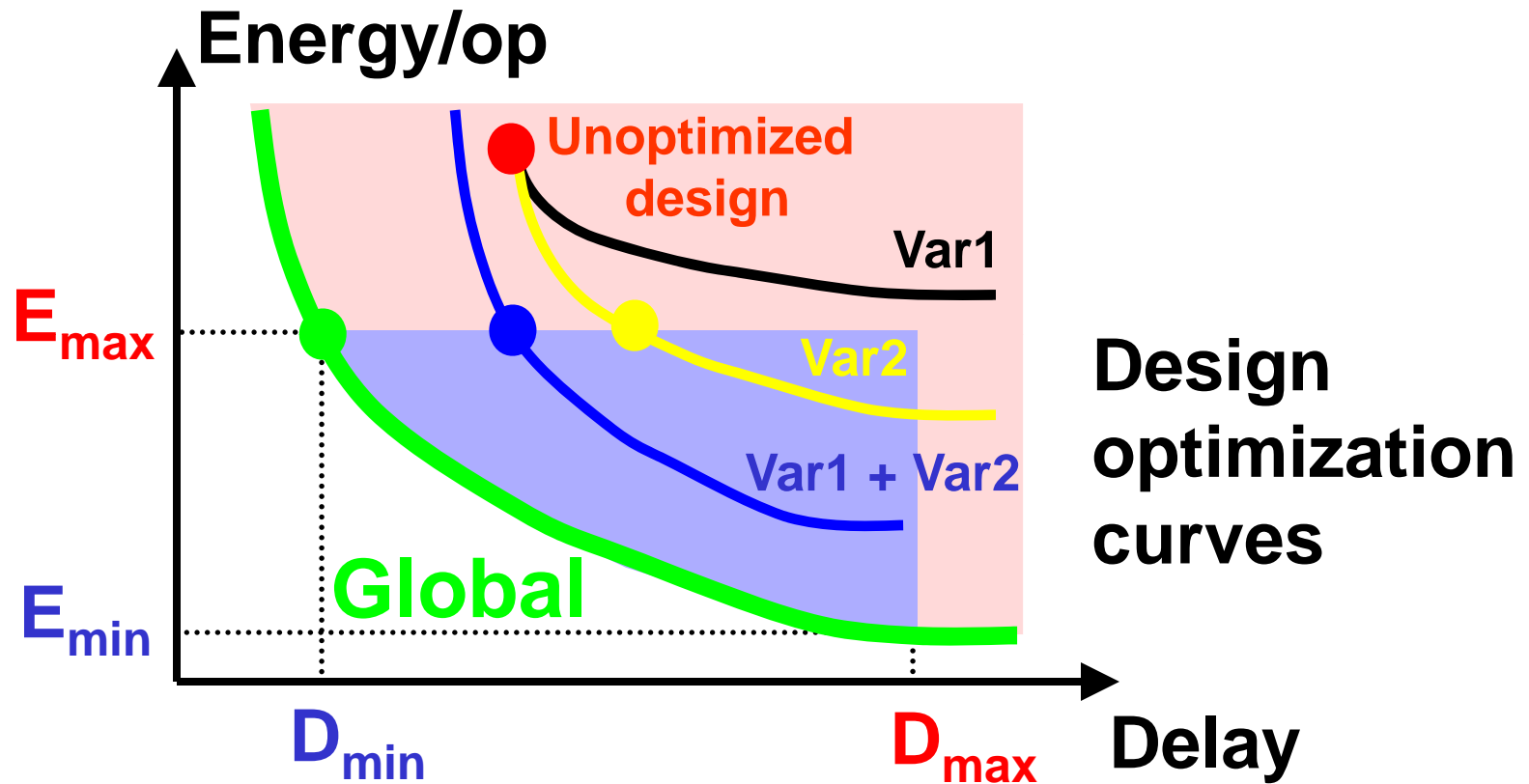
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# Power limited operation



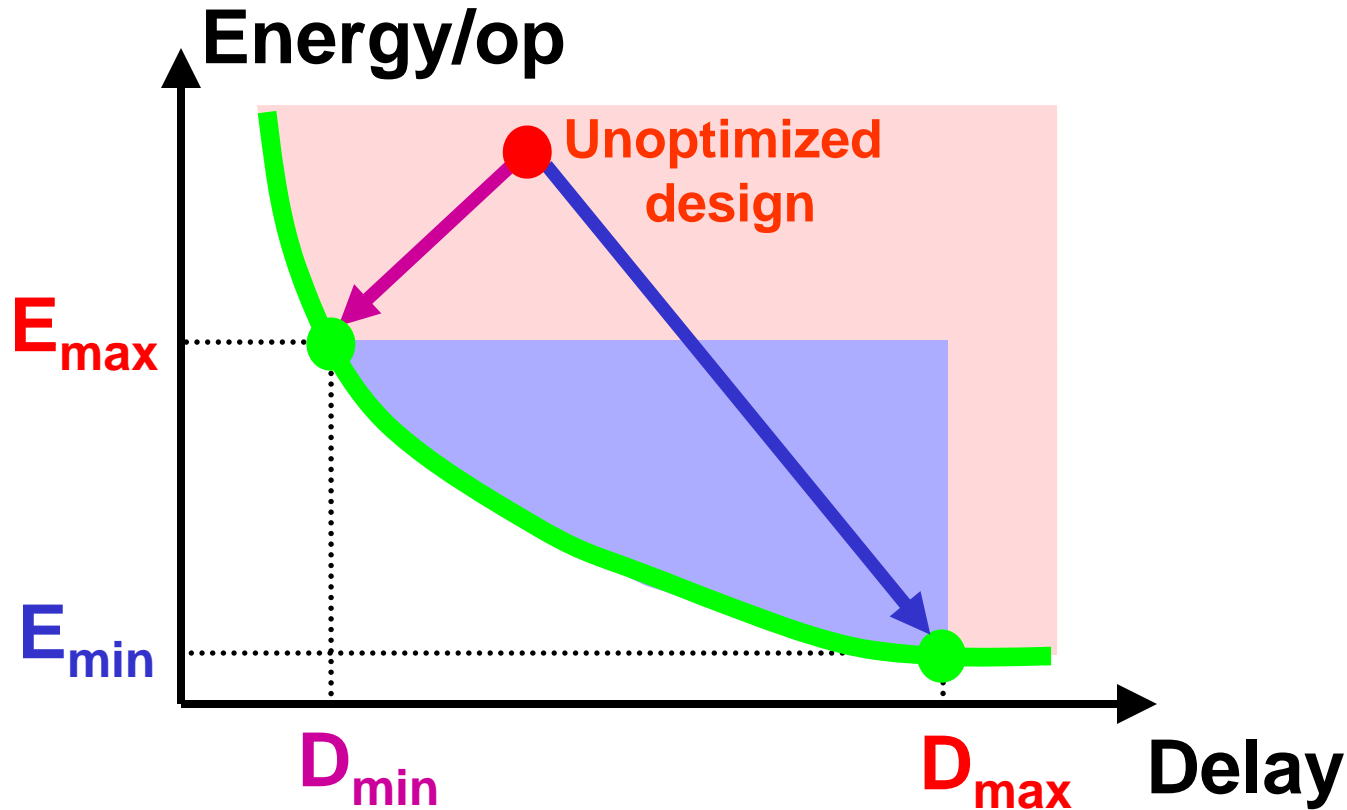
How far away are we from the optimal solution?

# Power limited operation



**Global optimum – best performance**

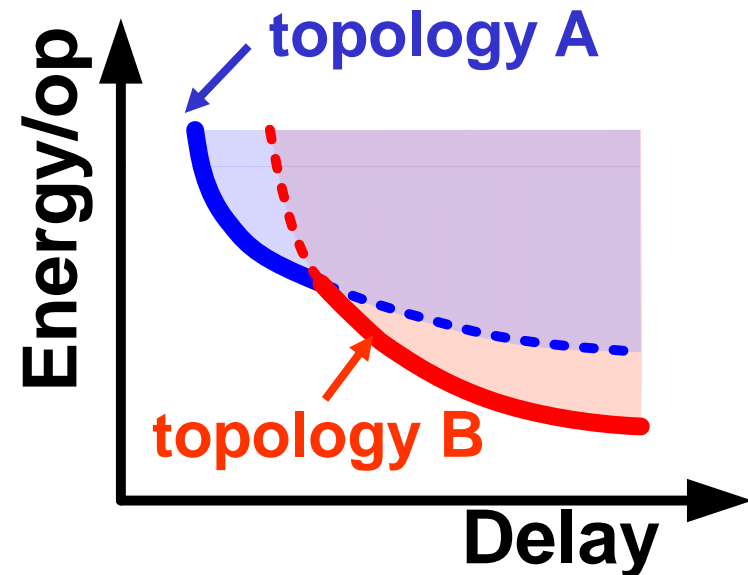
# Power limited operation



Maximize throughput for given energy or  
Minimize energy for given throughput

# Design optimization

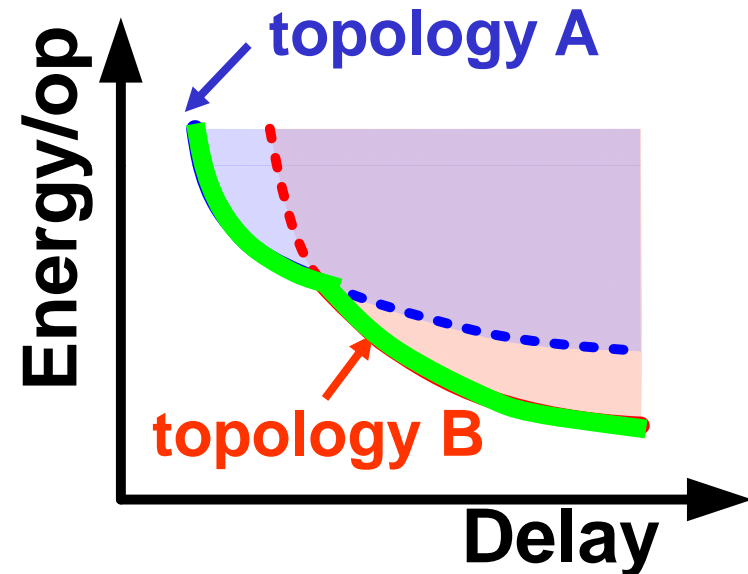
- ◆ There are many sets of parameters to adjust
- ◆ Tuning variables
  - Circuit  
(sizing, supply, threshold)
  - Logic style  
(domino, pass-gate, ...)
  - Block topology  
(adder: CLA, CSA, ...)
  - Micro-architecture  
(parallel, pipelined)





# Design optimization

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**Globally optimal boundary curve:  
pieces of E-D curves for different topologies**

# Outline

## ◆ **Circuit optimization**

- ◆ Joint optimization
- ◆ Select the most promising sets of tuning variables

## ◆ **Circuit & $\mu$ Architecture examples**

- ◆ Adder
- ◆ Add-Compare

## ◆ **Conclusions**

# Energy-delay sensitivity

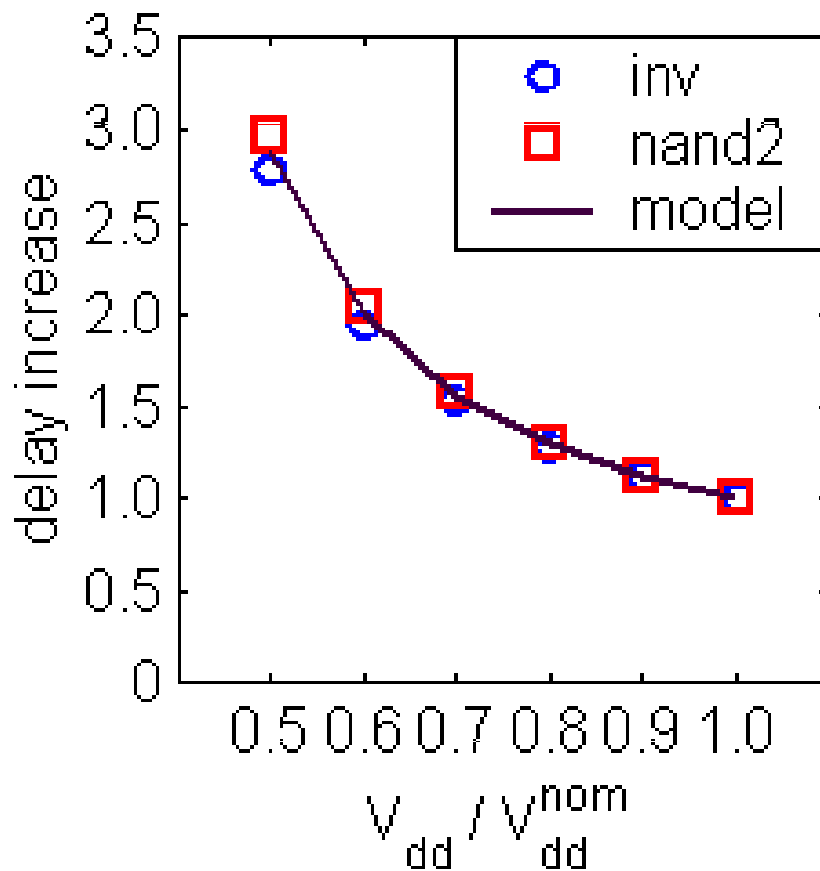
$$Sens(V_{dd}) = - \frac{\frac{\partial E}{\partial V_{dd}}}{\frac{\partial D}{\partial V_{dd}}} \Bigg|_{V_{dd} = V_{dd}^*}$$

- ◆ Proposed by Zyban at *ISLPED02*
- ◆  $\Delta E = Sens(A) \cdot (-\Delta D) + Sens(B) \cdot \Delta D$

**At the optimal point,  
all sensitivities should be the same**

# Alpha-power based delay model

$$t_p = \frac{K_d \cdot V_{dd}}{(V_{dd} - V_{on})^{\alpha_d}} \cdot \left( \frac{W_{out}}{W_{in}} + \frac{W_{par}}{W_{in}} \right)$$

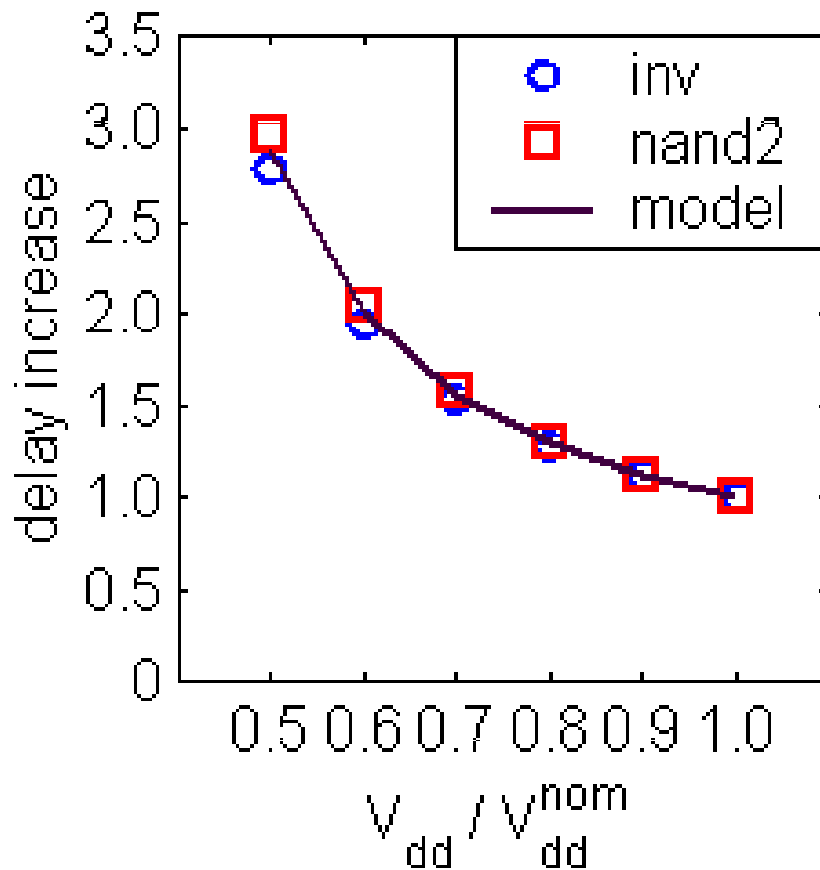


- ◆ Fitting parameters  
 $V_{on}, \alpha_d, K_d$

# Alpha-power based delay model

$$t_p = \frac{K_d \cdot V_{dd}}{(V_{dd} - V_{on})^{\alpha_d}} \cdot \left( \frac{W_{out}}{W_{in}} + \frac{W_{par}}{W_{in}} \right)$$

$h_{eff}$



- ◆ Fitting parameters

$V_{on}, \alpha_d, K_d$

- ◆ Effective fanout,  $h_{eff}$

# Energy model

## ◆ Switching energy

$$E_{Sw} = \alpha_{0 \rightarrow 1} \cdot \left( C(W_{out}) + C(W_{par}) \right) \cdot V_{dd}^2$$

## ◆ Leakage energy

$$E_{Lk} = W_{in} \cdot I_0(S_{in}) \cdot e^{\frac{-(V_{th} - \gamma V_{dd})}{V_0}} \cdot V_{dd} \cdot D$$

# Sensitivity to sizing and supply

## ◆ Gate sizing ( $W_i$ )

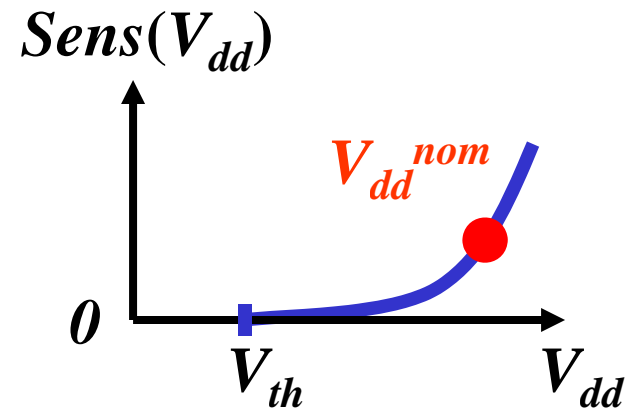
$$-\frac{\partial E_{Sw} / \partial W_i}{\partial D / \partial W_i} = \frac{ec_i}{\tau_{nom} \cdot (h_{eff,i} - h_{eff,i-1})}$$

$\infty$  for equal  $h_{eff}$   
( $D_{min}$ )

## ◆ Supply voltage ( $V_{dd}$ )

$$-\frac{\partial E_{Sw} / \partial V_{dd}}{\partial D / \partial V_{dd}} = \frac{E_{Sw}}{D} \cdot 2 \frac{1 - x_v}{\alpha_d - 1 + x_v}$$

$$x_v = (V_{on} + \Delta V_{th}) / V_{dd}$$



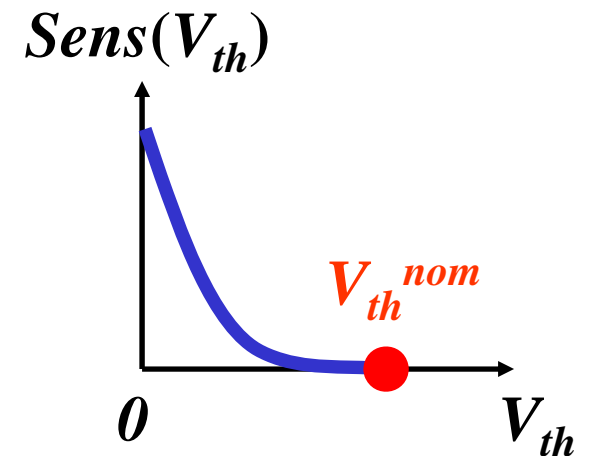
# Sensitivity to V<sub>th</sub>

## ◆ Threshold voltage ( $V_{th}$ )

$$-\frac{\frac{\partial E}{\partial(\Delta V_{th})}}{\frac{\partial D}{\partial(\Delta V_{th})}} = P_{Lk} \cdot \left( \frac{V_{dd} - V_{on} - \Delta V_{th}}{\alpha_d \cdot V_0} - 1 \right)$$

**Low initial leakage**

**⇒ speedup comes for “free”**

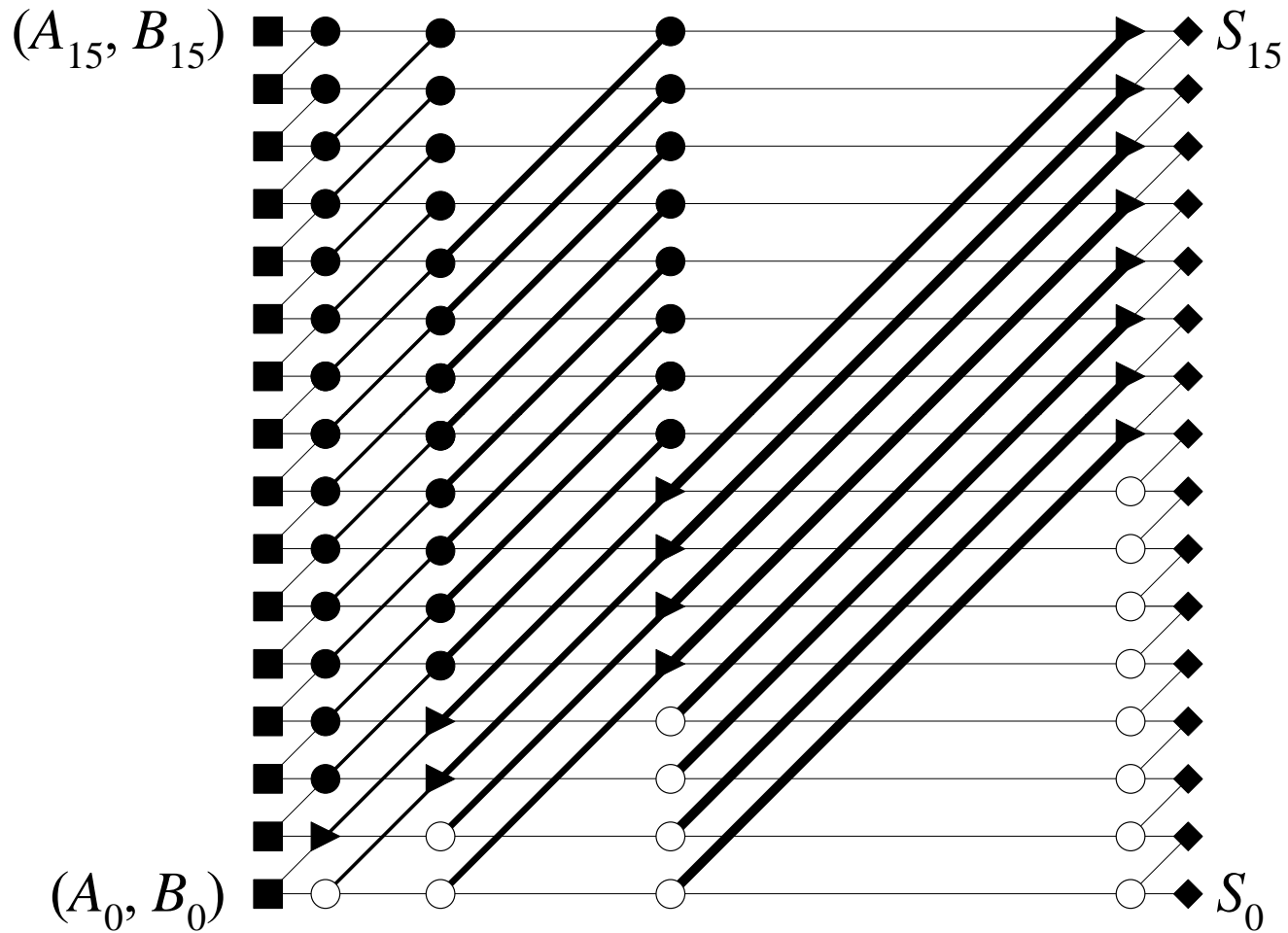




# Optimization setup

- ◆ Reference/nominal circuit
  - sized for  $D_{min}$  @  $V_{dd}^{nom}$ ,  $V_{th}^{nom}$
  - known average activity
- ◆ Set delay constraint
- ◆ Minimize energy under delay constraint
  - gate sizing
  - $V_{dd}$ ,  $V_{th}$  scaling

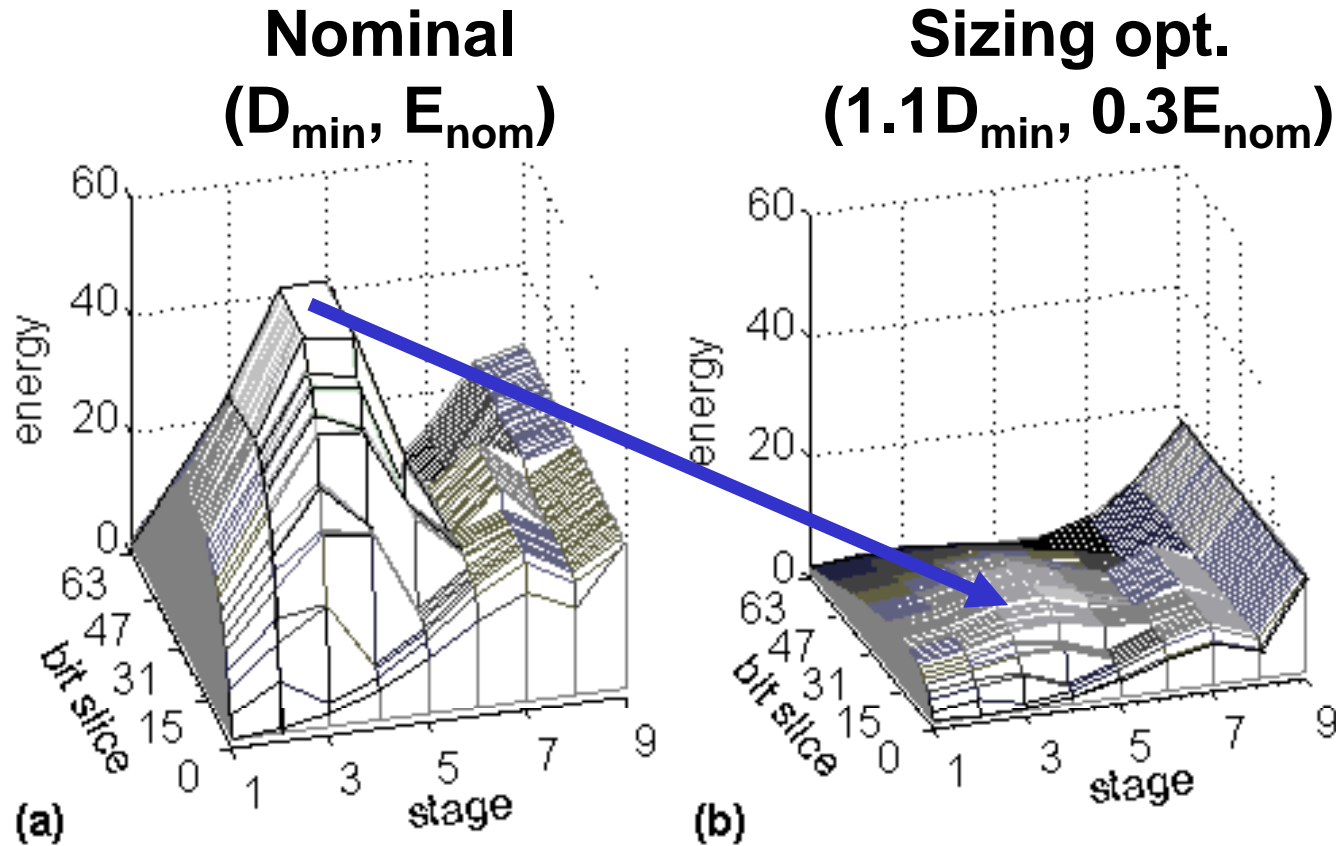
# Kogge-Stone tree adder topology



- ◆ Off-path load (gates + wires)
- ◆ Reconvergence (inside ●-block)

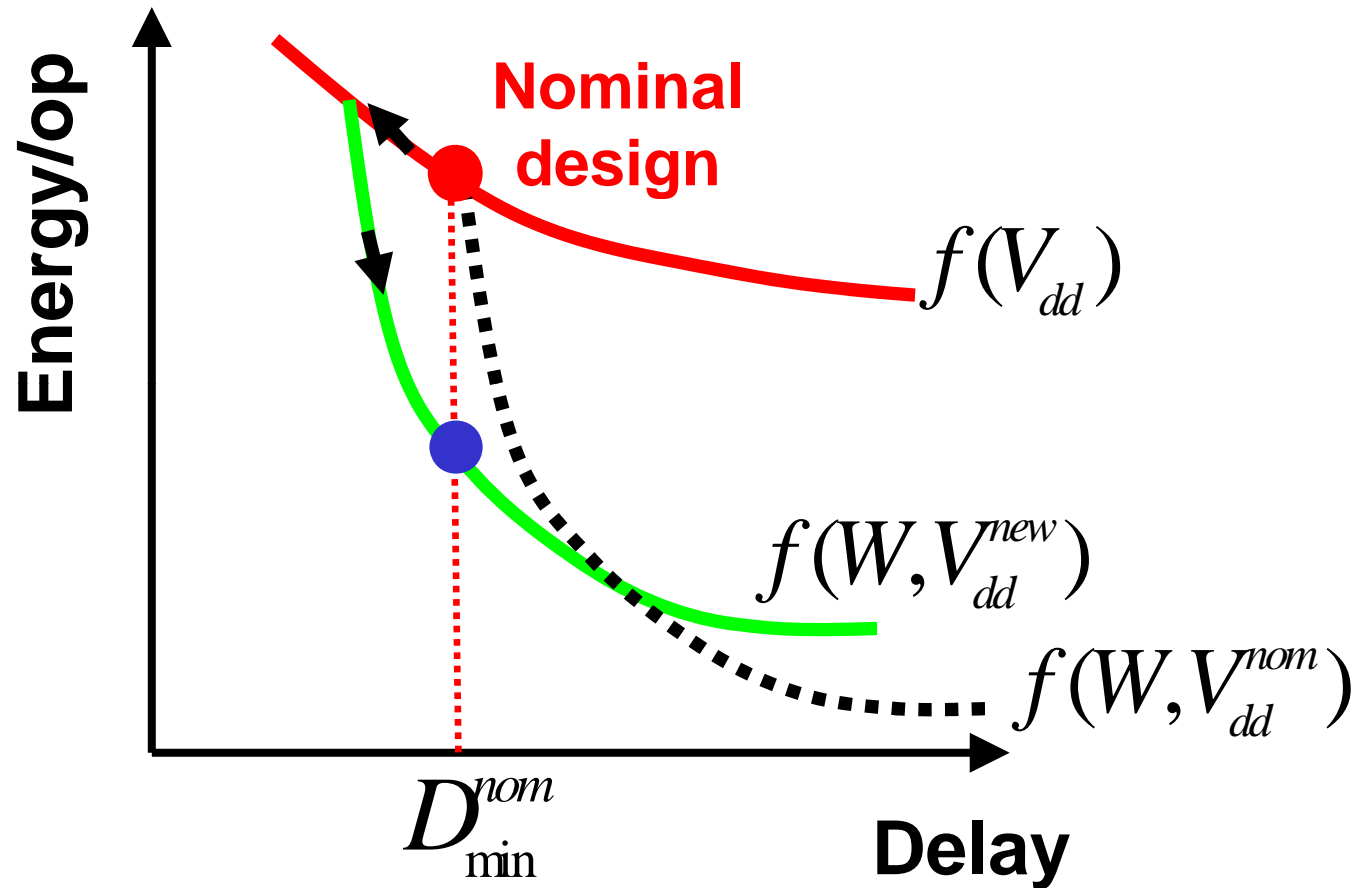
# Tree adder: Sizing optimization

- ◆ Reference: all paths are critical



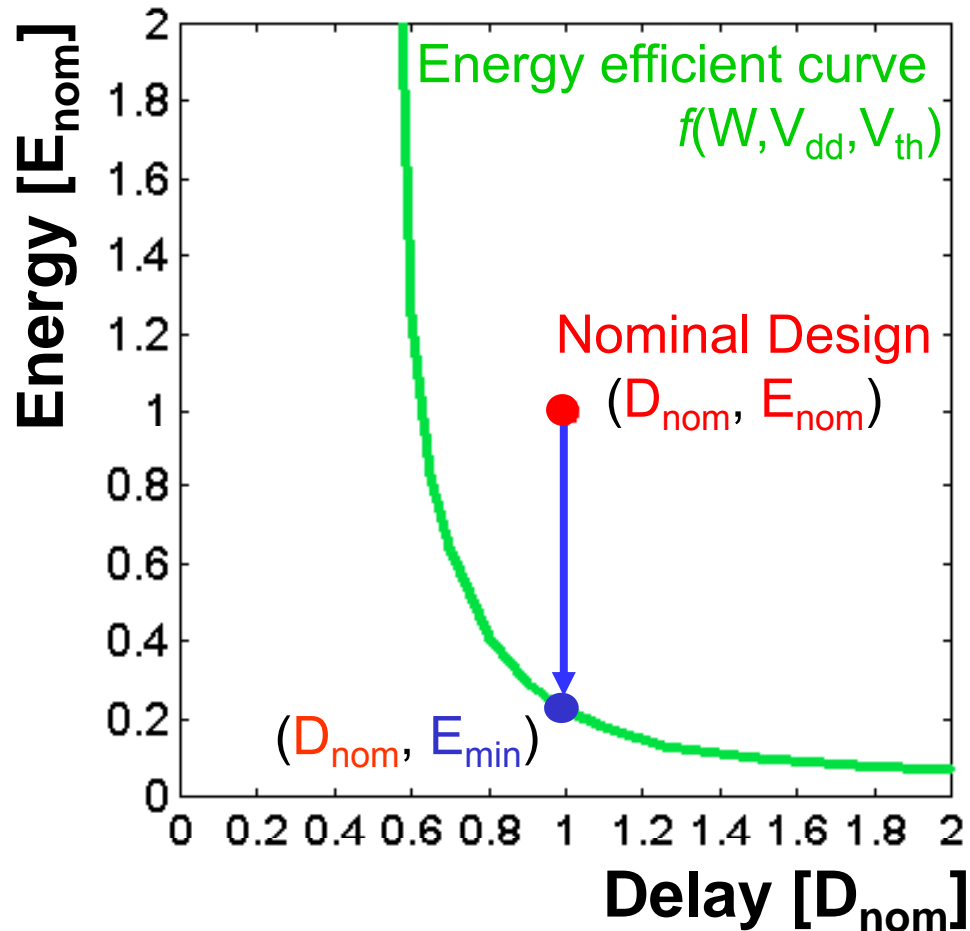
**Internal energy peaks  $\Rightarrow$   
Big savings for small delay penalty with resizing**

# Joint optimization: sizing and Vdd



$$\Delta E = \text{Sens}(V_{dd}) \cdot (-\Delta D) + \text{Sens}(W) \cdot \Delta D$$

# Results of joint optimization

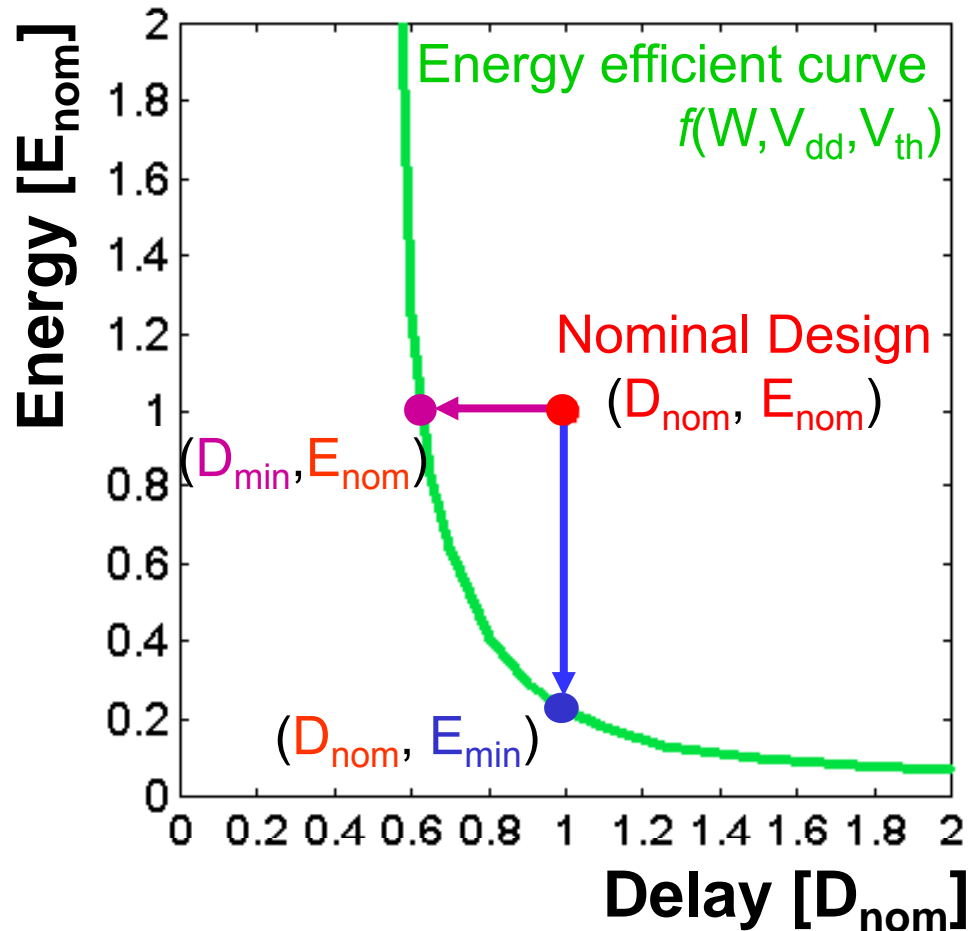


## Sensitivity table

Sens	W	Vdd	Vth
$(D_{nom}, E_{nom})$	$\infty$	1.5	0.2
$(D_{nom}, E_{min})$	1 (reference)		

80% of energy saved without delay penalty

# Results of joint optimization



## Sensitivity table

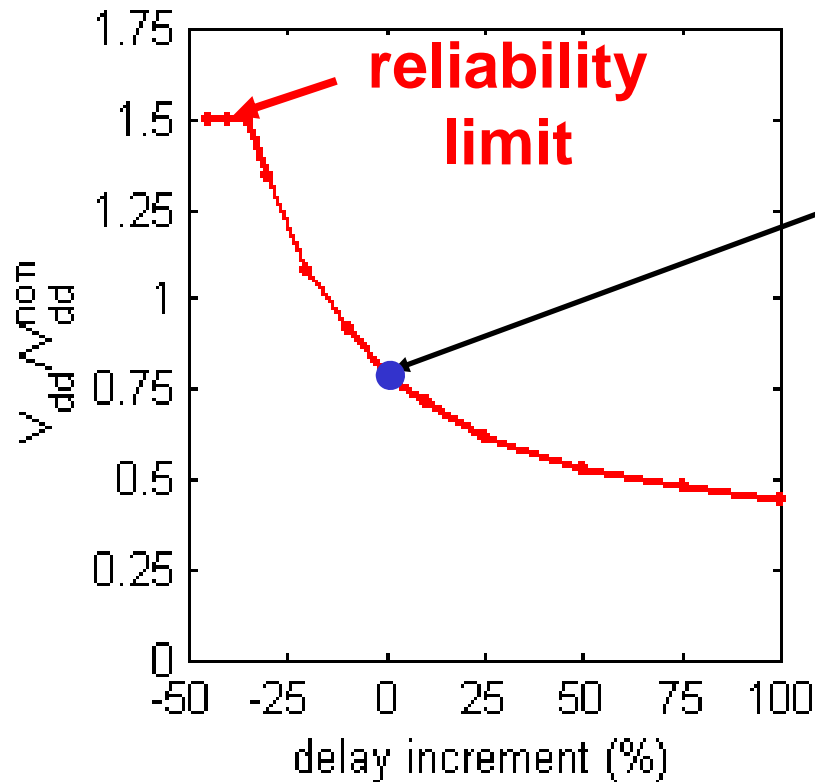
Sens	W	Vdd	Vth
(D <sub>nom</sub> , E <sub>nom</sub> )	∞	1.5	0.2
(D <sub>nom</sub> , E <sub>min</sub> )	1 (reference)		
(D <sub>min</sub> , E <sub>nom</sub> )	22	16	22

80% of energy saved without delay penalty

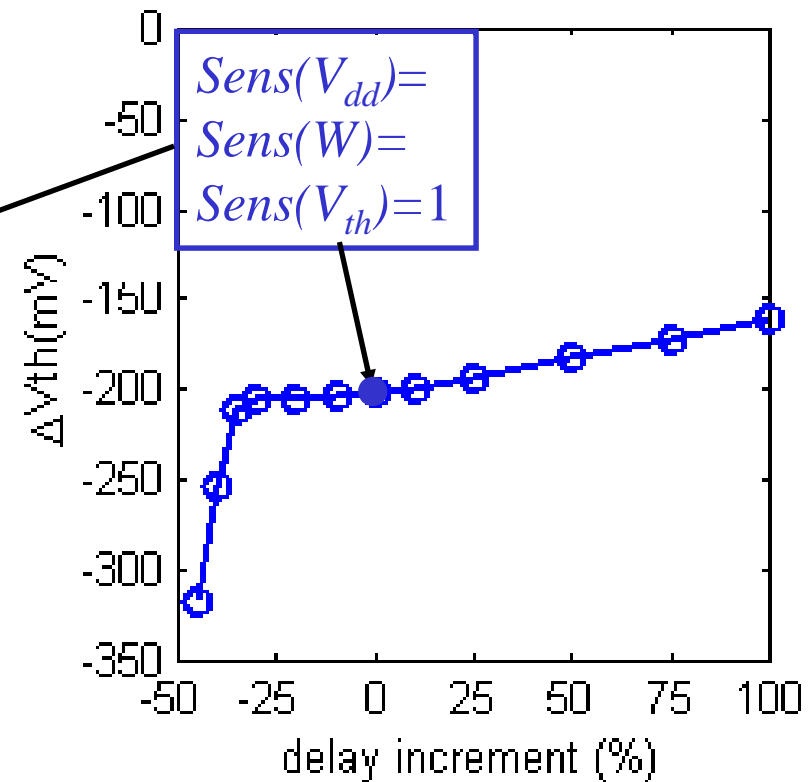
40% speedup for same energy

# A look at tuning variables

Supply



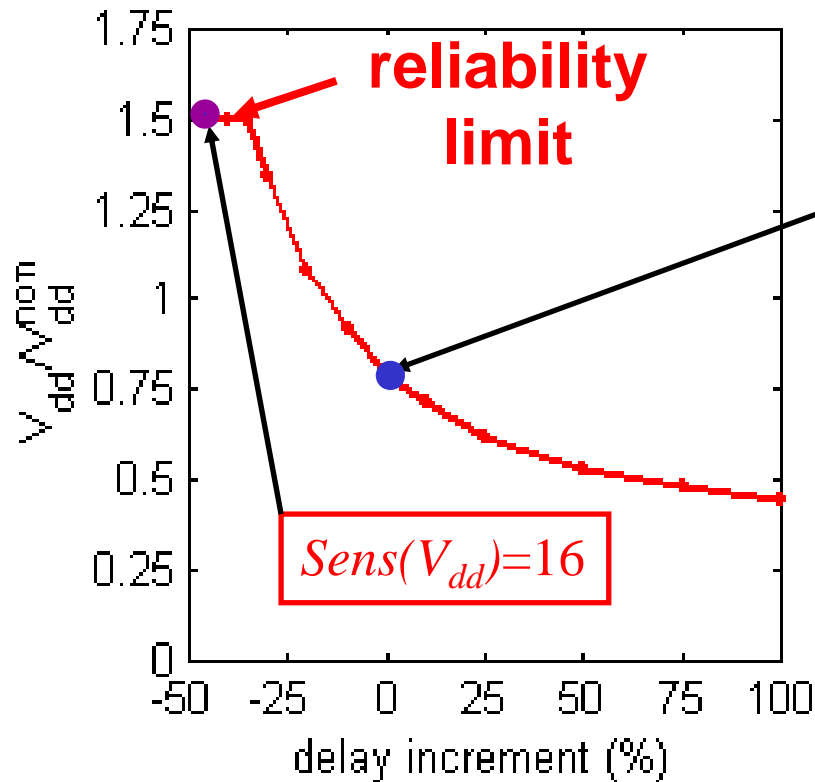
Threshold



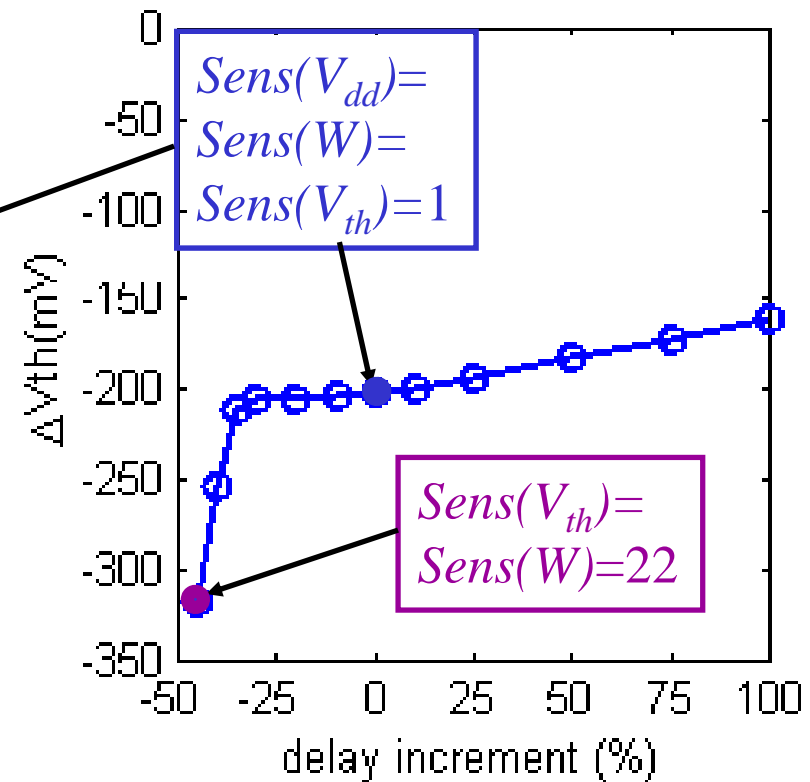
**Limited range of tuning variables**

# A look at tuning variables

## Supply



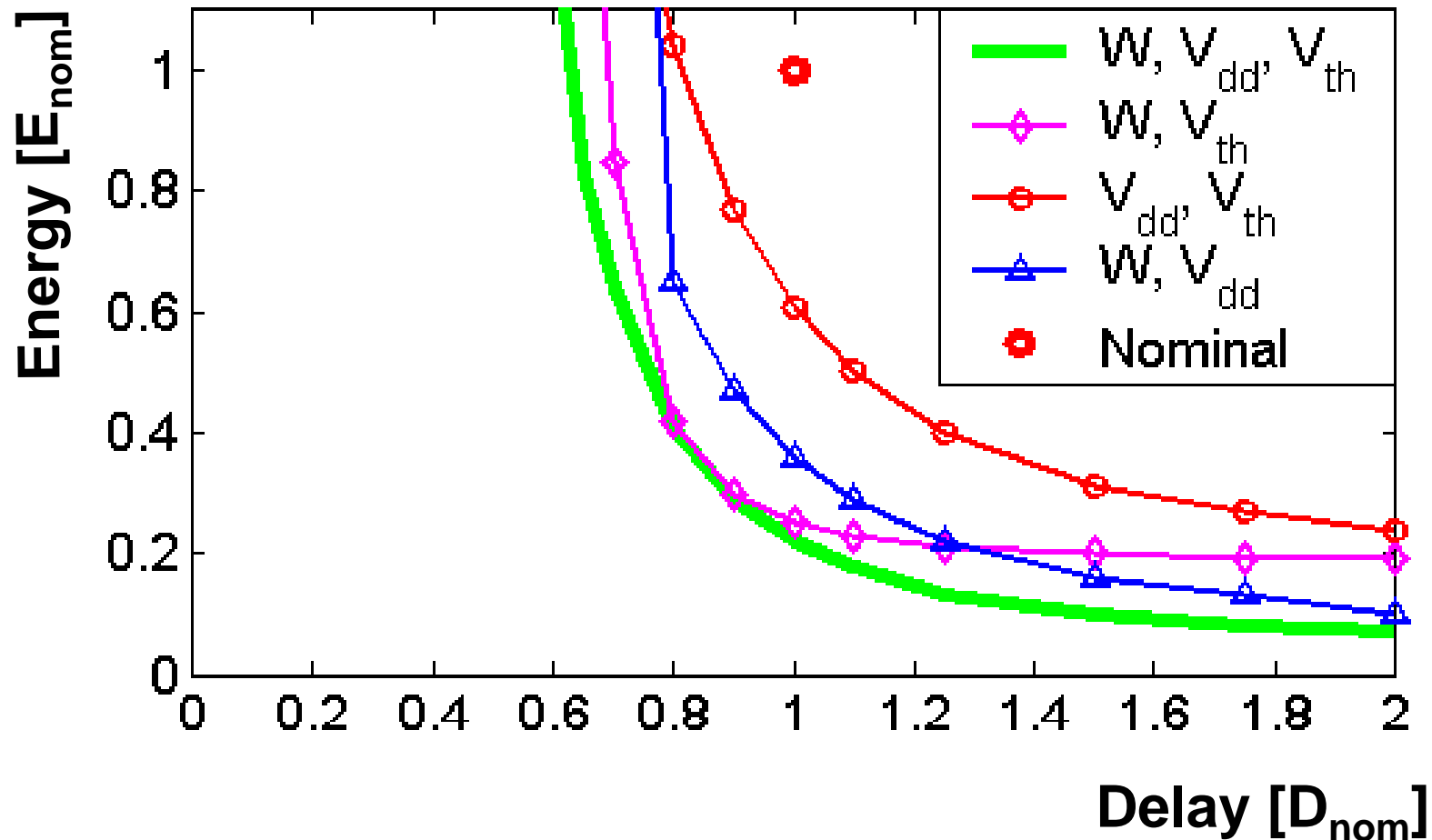
## Threshold



**Limited range of tuning variables**

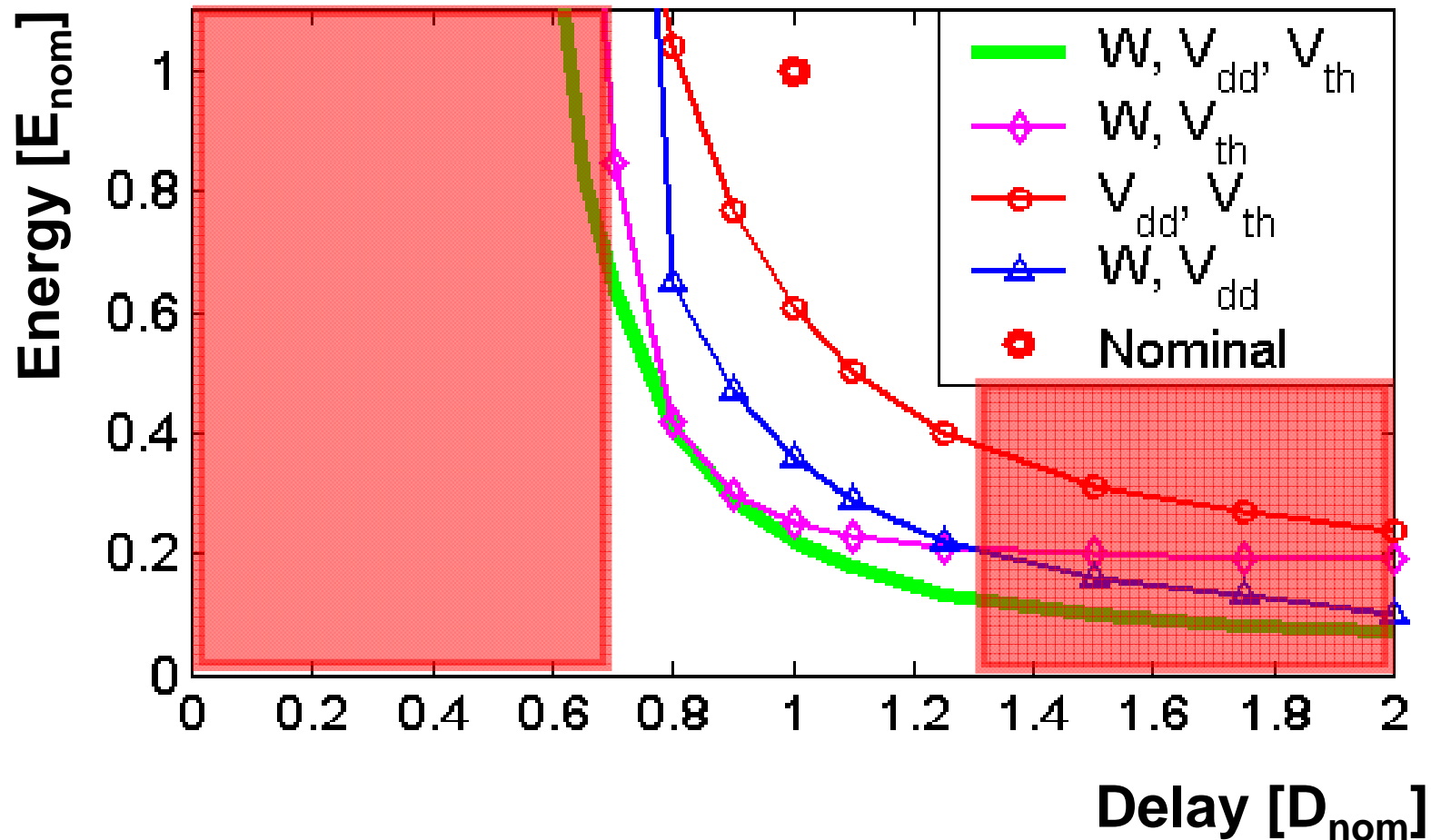


# Reducing the number of dimensions



**Threshold and sizing nearly optimal  
around the nominal point**

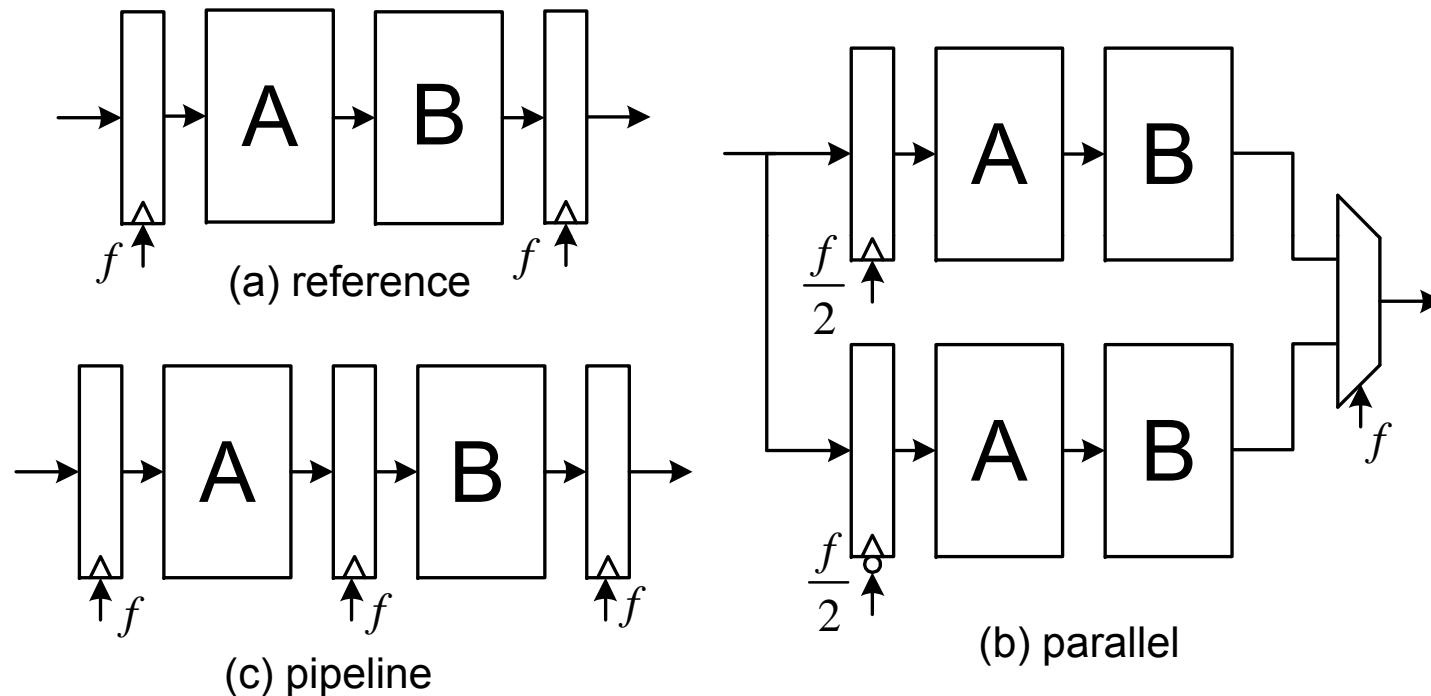
# Scope of circuit optimization



**Effective region +/-30% around nominal delay**

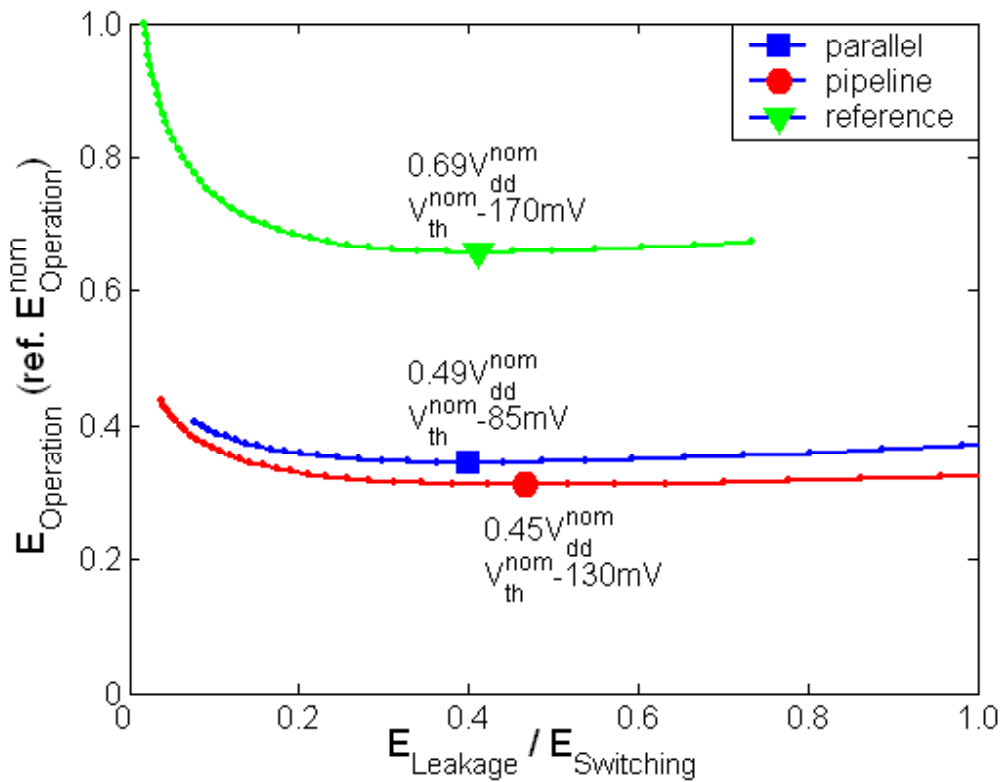
# Circuit & $\mu$ Architecture optimization

- ◆ Revisit the old argument for parallelism



- ◆ What happens if we can choose optimal  $V_{dd}$  and  $V_{th}$  for each design?

# Balance of leakage and switching energy



$$\left. \frac{E_{Lk}}{E_{Sw}} \right|_{Opt} = \frac{2}{\ln\left(\frac{L_d}{\alpha_{avg}}\right) - K_{tech}}$$

**Optimal designs have high leakage current**

# Conclusions

- ◆ All design levels need to be optimized jointly
- ◆ Equal marginal costs  $\Rightarrow$  Energy-efficient design
- ◆ Peak performance is VERY power inefficient
- ◆ Today's designs are not leaky enough to be truly power-optimal
- ◆ Pipelining starts to gain advantage over parallelism