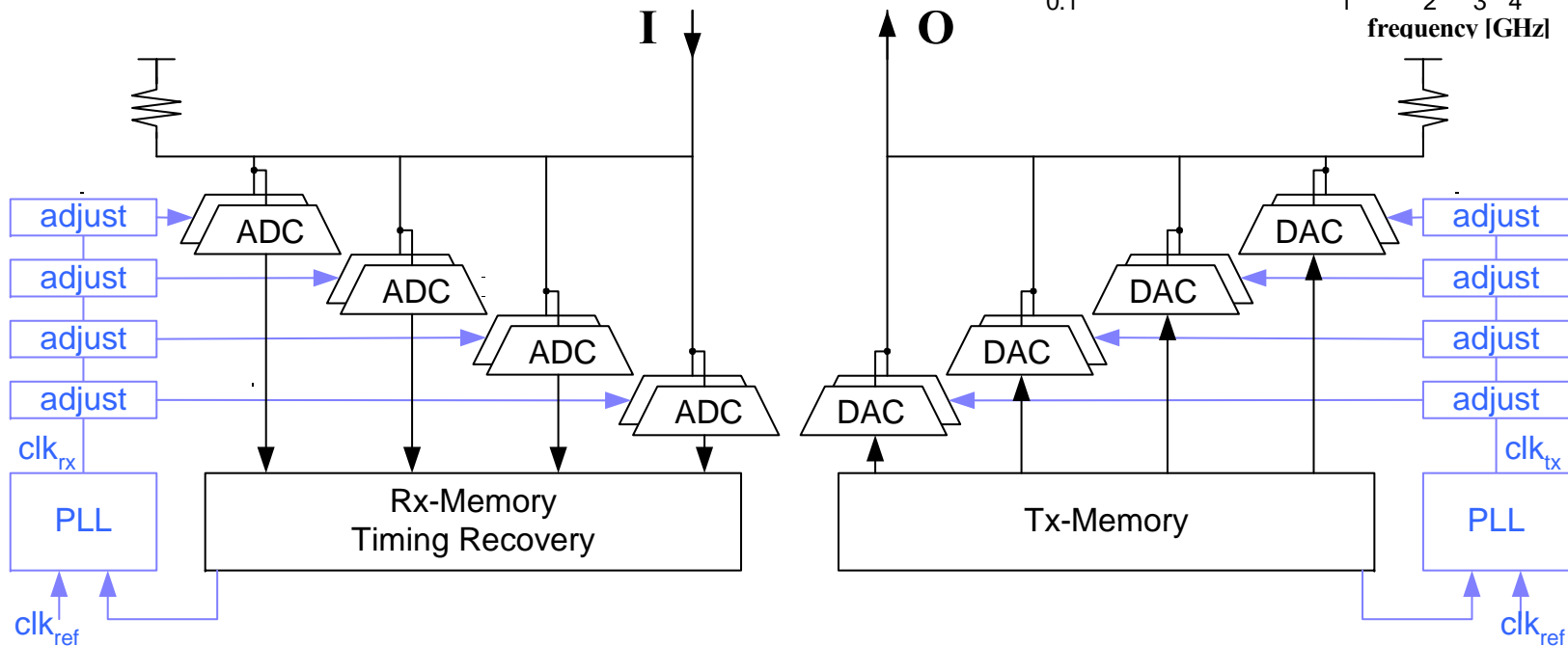
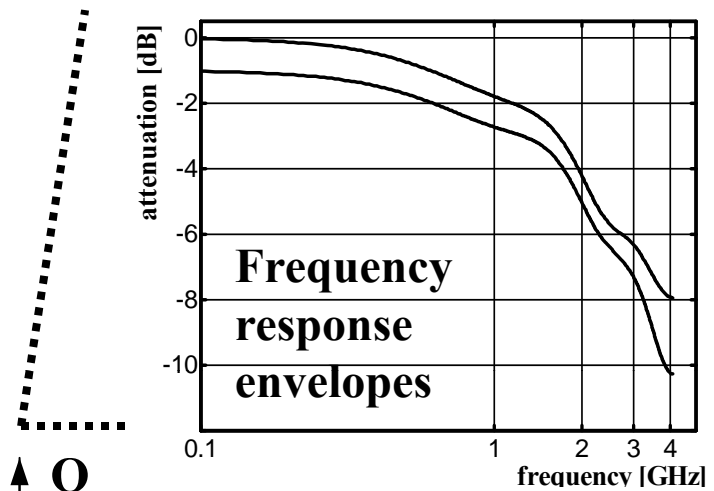


Transmit Pre-emphasis
for High-Speed
Time-Division-Multiplexed
Serial Link Transceiver

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Stanford University

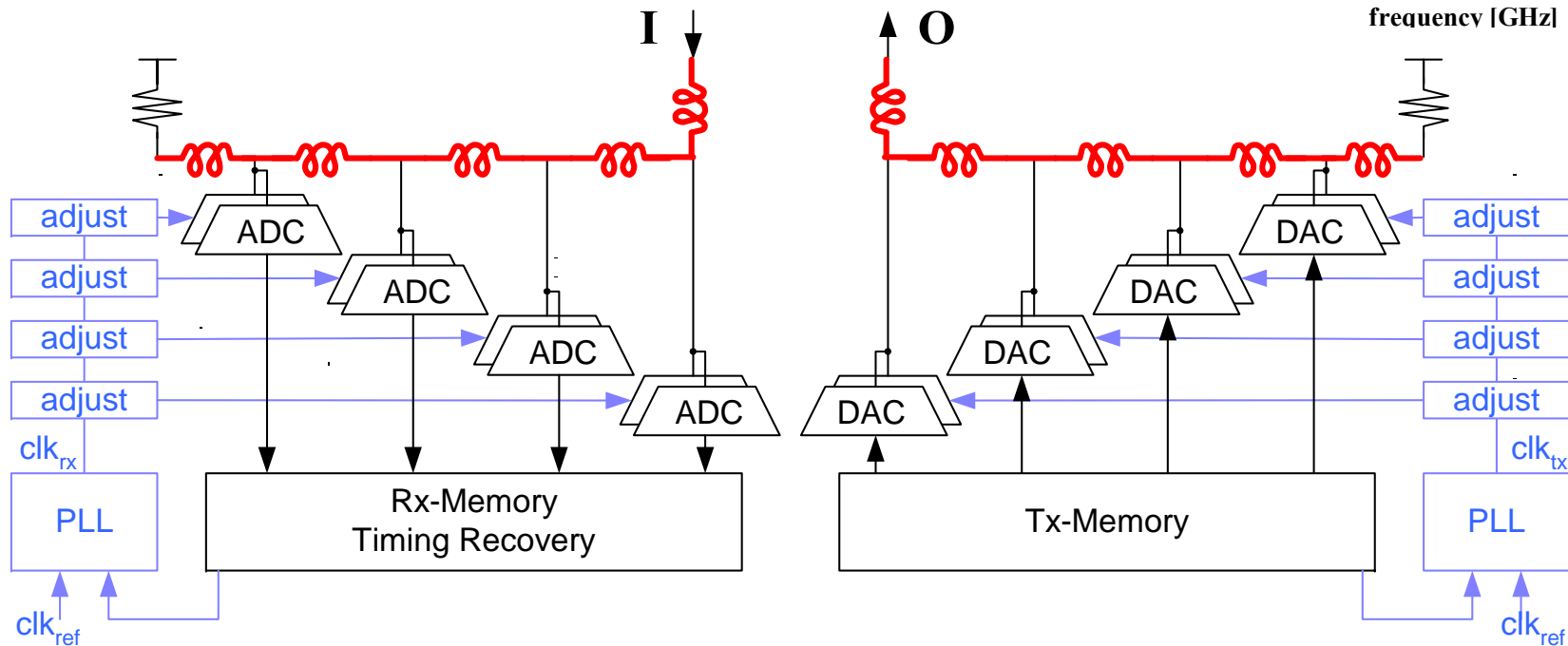
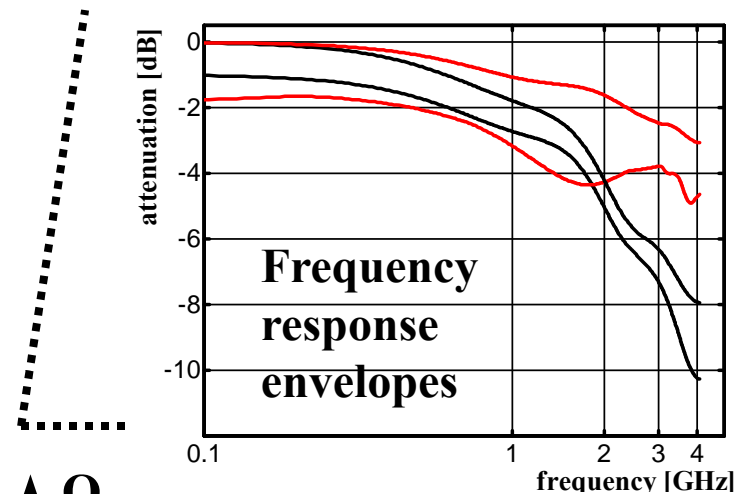
High-speed Link Transceiver

- 8GSa/s rate
- On chip clock freq limit
- TDM (8 DACs & 8 ADCs)
- Parasitic RC low-pass filtering

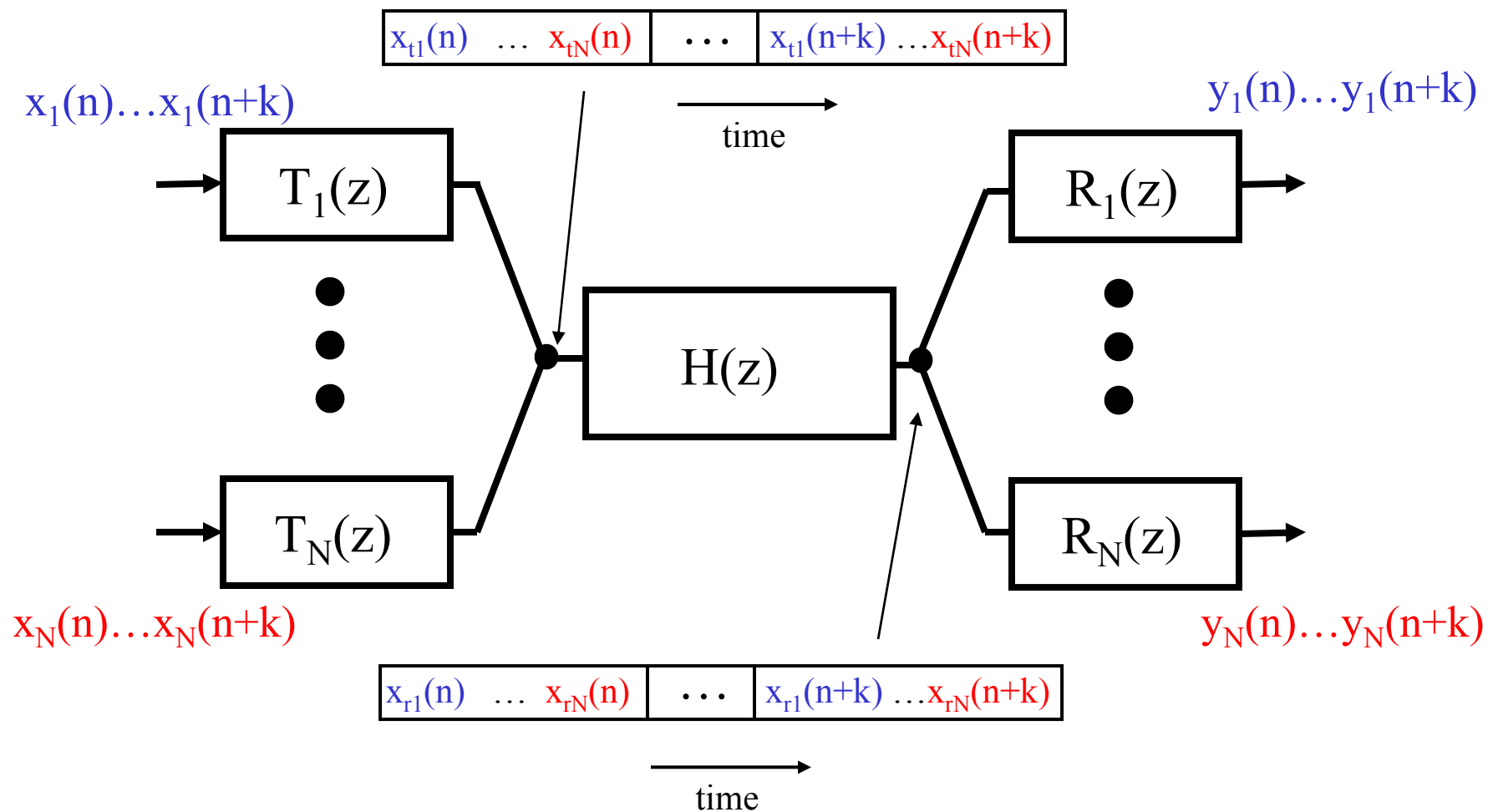


Passive, continuous time equalization

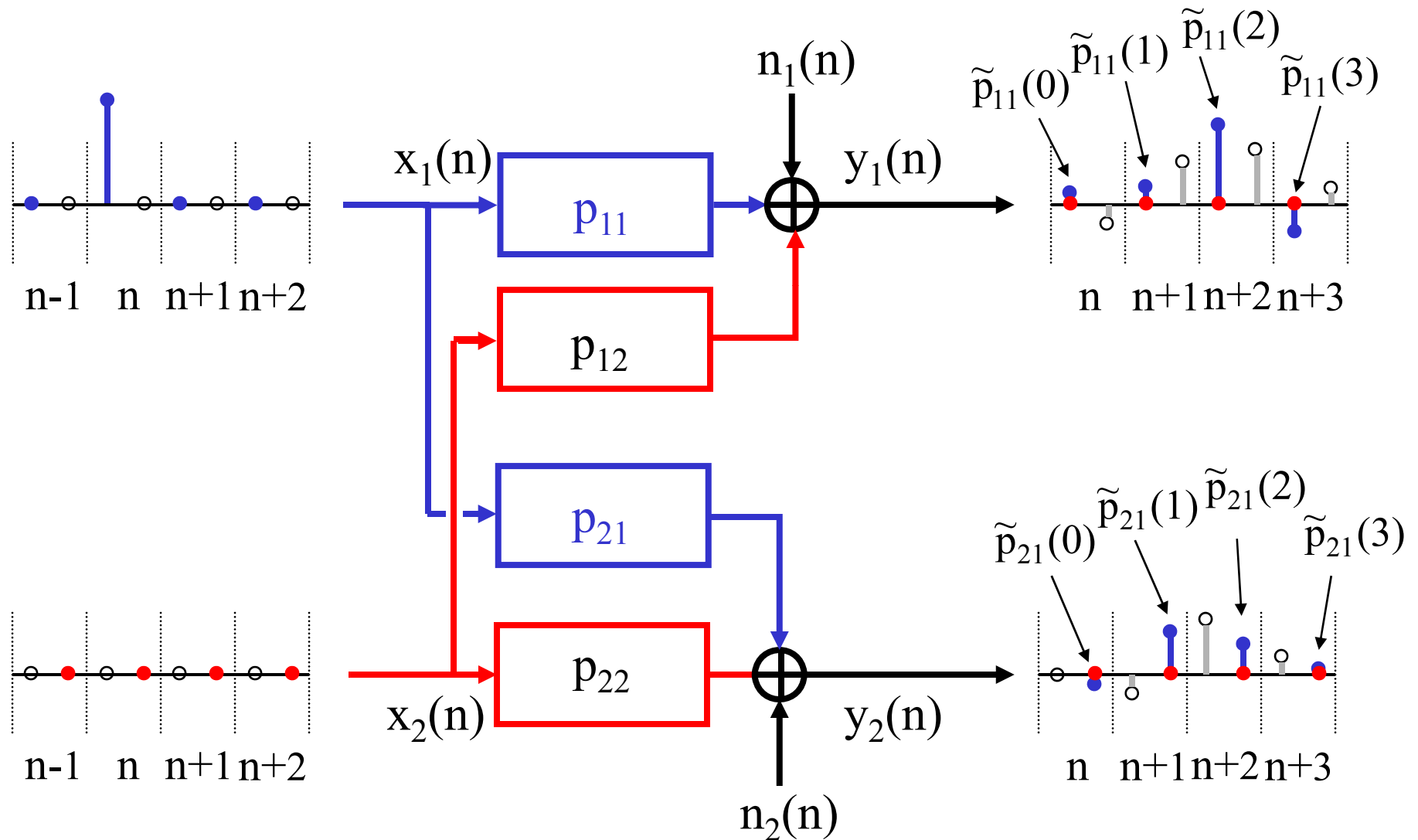
- “Distribute” parasitic RC
- Bondwire inductors
- *Distributed-TDM*



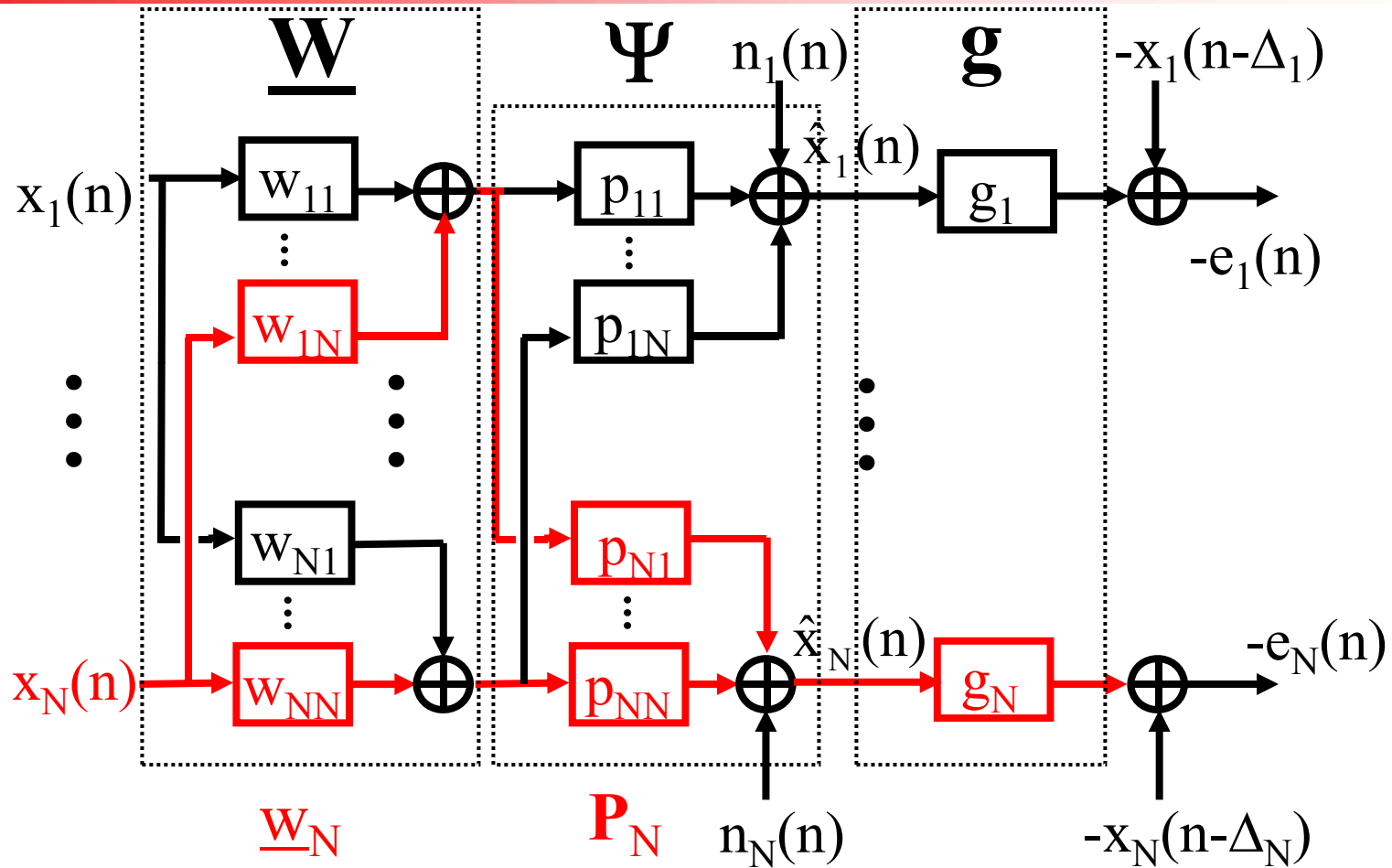
$N \times N$ Distributed-TDM System



Example: 2x2 Multi-channel System



System Model



Unbiased error:
$$\underline{e}(n)_{N \times 1} = \frac{1}{\sqrt{E_x}} \left(\underline{\mathbf{x}}(n - \underline{\Delta})_{N \times 1} - \mathbf{g}_{N \times N} \underline{\hat{\mathbf{x}}}(n)_{N \times 1} \right)$$

Optimal Solution Formulation

- Formulate pre-emphasis as optimization problem
- Output k receives *unbiased* data from input k :

$$\underline{g}_k \underline{\mathbf{w}}_k^T \mathbf{P}_k^T \mathbf{1}_{\Delta_k}^T = 1, \forall k = 1 \dots N$$

- Cost function – *Unbiased* mean-square error

$$\xi = -N + \sum_{k=1}^N \underline{\mathbf{w}}_k^T \left(\sum_{\substack{l=1 \\ k \neq l}}^N \frac{\mathbf{P}_l^T \mathbf{P}_l}{\left(\mathbf{1}_{\Delta_l}^T \mathbf{P}_l \underline{\mathbf{w}}_l \right)^2} \right) \underline{\mathbf{w}}_k + \frac{1}{SNR_0} \sum_{k=1}^N \left(\mathbf{1}_{\Delta_k}^T \mathbf{P}_k \underline{\mathbf{w}}_k \right)^{-2}$$

k=l (signal + ISI)
Noise

k≠l (crosstalk)

- Transmitter peak output power constraint:

$$\tilde{h}_j(\underline{\mathbf{w}}) = \sum_{k=1}^N \sum_{i=0}^{L-1} |w_{jk}(i)| \leq 1, \quad \forall j = 1 \dots N$$

Non-convexity Argument

- Assume 2x2 system with attenuation and crosstalk (no ISI)

$$\xi = \frac{1}{(\mathbf{P}_1 \underline{\mathbf{w}}_1)^2} \left[\frac{1}{SNR_o} + (\mathbf{P}_1 \underline{\mathbf{w}}_2)^2 \right] + \frac{1}{(\mathbf{P}_2 \underline{\mathbf{w}}_2)^2} \left[\frac{1}{SNR_o} + (\mathbf{P}_2 \underline{\mathbf{w}}_1)^2 \right]$$

- A function is convex only if it is convex on all lines. Let:

$$[\underline{\mathbf{w}}_1 \quad \underline{\mathbf{w}}_2] = [\underline{\mathbf{w}}_{o,1} \quad \underline{\mathbf{w}}_{o,2}] + t \cdot [\underline{\mathbf{w}}_{s,1} \quad \underline{\mathbf{w}}_{s,2}]$$

- ξ is convex in $[\underline{\mathbf{w}}_1 \quad \underline{\mathbf{w}}_2]$ only if it is convex in t for all $[\underline{\mathbf{w}}_{o,1} \quad \underline{\mathbf{w}}_{o,2}]$ and $[\underline{\mathbf{w}}_{s,1} \quad \underline{\mathbf{w}}_{s,2}]$.
- Each of the two terms in ξ becomes a ratio of quadratic expressions in t , which are known to be non-convex.
- Therefore, ξ is not convex in general.

Sub-optimal Solution

- First sub-optimal solution – change the constraint

$$\tilde{h}_{j,new}(\underline{\mathbf{W}}) = \sum_{k=1}^N \sum_{i=0}^{L-1} |w_{jk}(i)| = 1, \quad \forall j = 1 \dots N$$

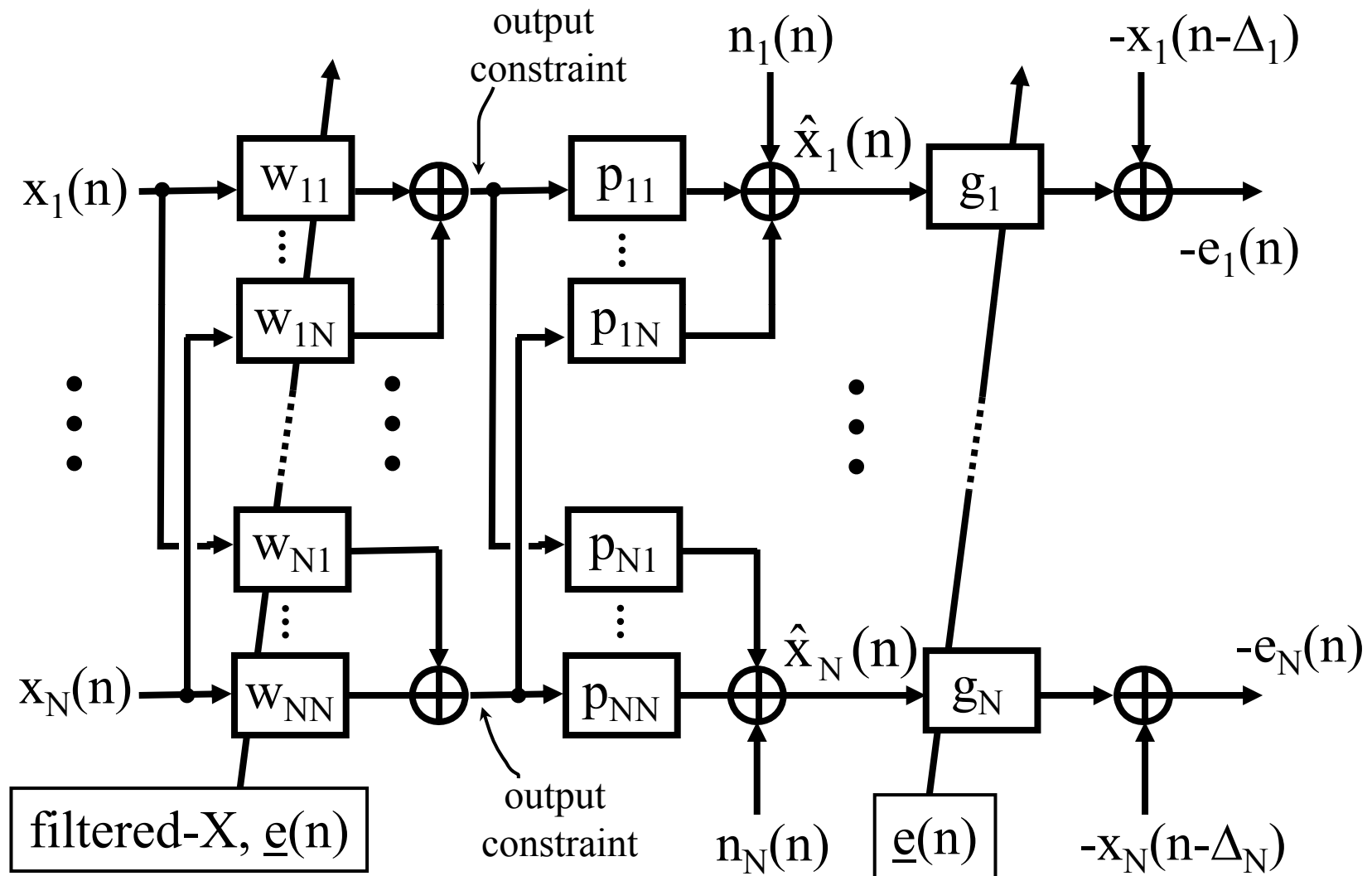
(every transmitter achieves peak output power)

- Second sub-optimal solution -
find unconstrained ZFE & scale to meet the constraint

$$\underline{\mathbf{W}}_{ZFEU} = (\Psi^T \Psi)^{-1} \Psi^T \mathbf{G}^T \underline{\mathbf{I}}_{\Delta}^T \quad ; \quad \underline{\mathbf{W}} = \frac{\underline{\mathbf{W}}_{ZFEU}}{\max_{j=1 \dots N} \left(\tilde{h}_j(\underline{\mathbf{W}}_{ZFEU}) \right)}$$

- These solutions allow the implementation of simple LMS-type adaptive algorithms

Adaptive System Model



Adaptive Solution

- Multi-channel, multi-error, filtered-X LMS algorithm

- **Pre-emphasis loop:** $\underline{\mathbf{U}}(n) = \mathbf{X}(n)\Psi$ - filtered-X

$$\underline{\tilde{\mathbf{W}}}_{n+1} = \underline{\mathbf{W}}_n - \mu_w \hat{\nabla}_n(\underline{\mathbf{W}}) = \underline{\mathbf{W}}_n + \frac{2\mu_w}{\sqrt{E_x}} \underline{\mathbf{U}}(n)^T \mathbf{g}^T \underline{\mathbf{e}}(n)$$

- Individual scaling (like first sub-optimal approach)

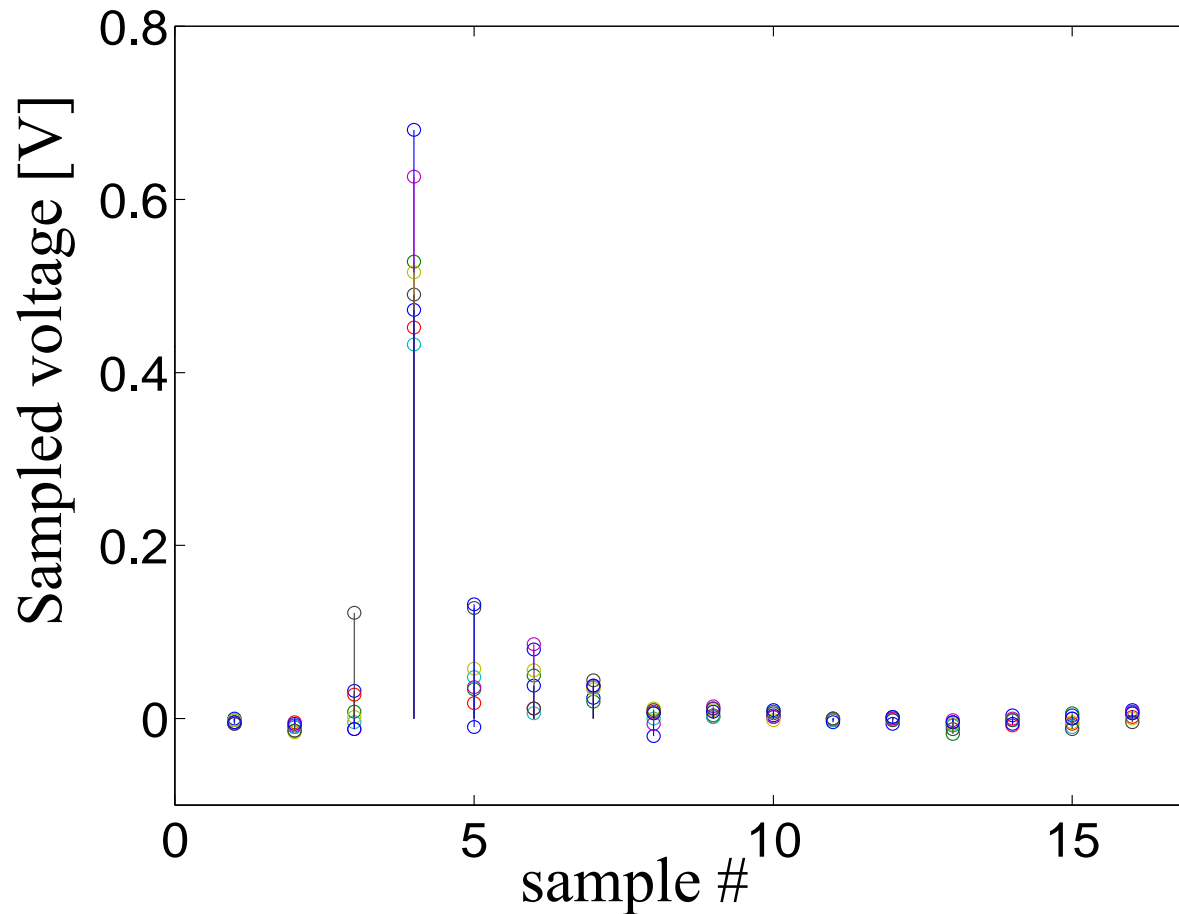
$$\underline{\mathbf{W}}_{n+1} = \begin{bmatrix} \frac{\tilde{\mathbf{w}}_{11}^T(n+1)}{\tilde{h}_1(\underline{\tilde{\mathbf{W}}}_{n+1})_{1 \times L}} & \dots & \frac{\tilde{\mathbf{w}}_{jk}^T(n+1)}{\tilde{h}_j(\underline{\tilde{\mathbf{W}}}_{n+1})_{1 \times L}} & \dots & \frac{\tilde{\mathbf{w}}_{NN}^T(n+1)}{\tilde{h}_N(\underline{\tilde{\mathbf{W}}}_{n+1})_{1 \times L}} \end{bmatrix}^T_{N^2 L \times 1}$$

- Maximal scaling (like second sub-optimal approach)

$$\underline{\mathbf{W}}_{n+1} = \frac{1}{\max_{j=1 \dots N} \left(\tilde{h}_j(\underline{\tilde{\mathbf{W}}}_{n+1}) \right)} \underline{\tilde{\mathbf{W}}}_{n+1}$$

- **Gain loop:** $diag(\mathbf{g}_{n+1}) = diag(\mathbf{g}_n) + \frac{2\mu_g}{\sqrt{E_x}} diag(\hat{\underline{\mathbf{x}}}(n)\underline{\mathbf{e}}^T(n))$

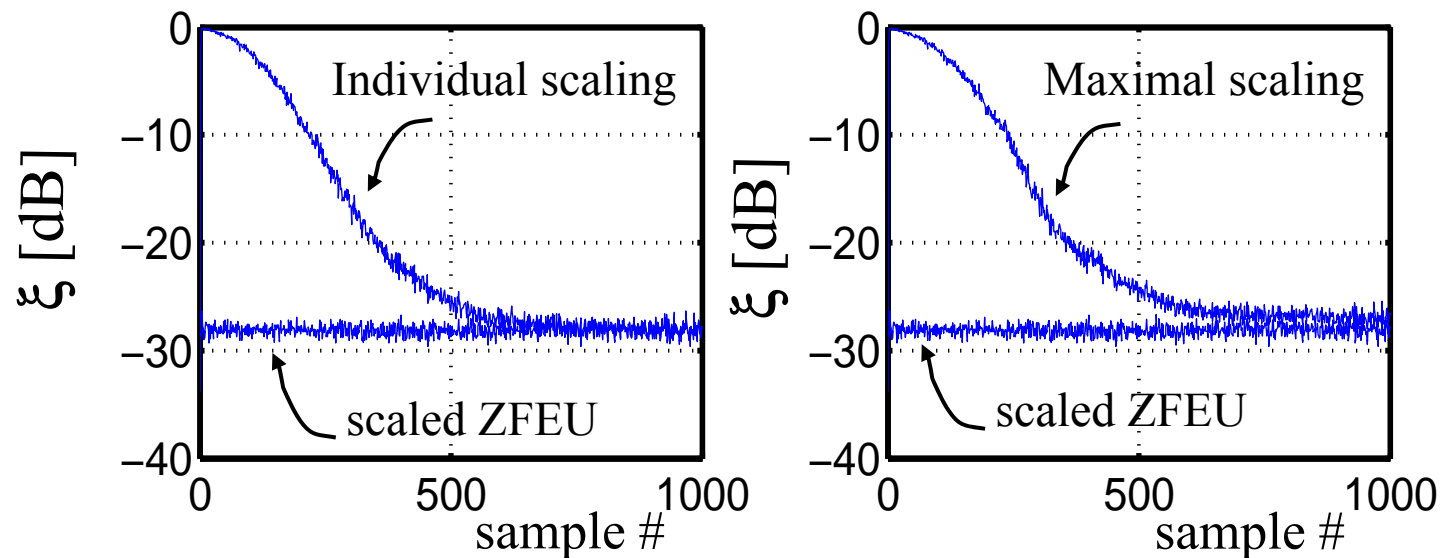
Pulse Responses – 8x8 TDM



- 8GSa/s rate
- 1GSa/s/channel
- Peak output swing 0.75V

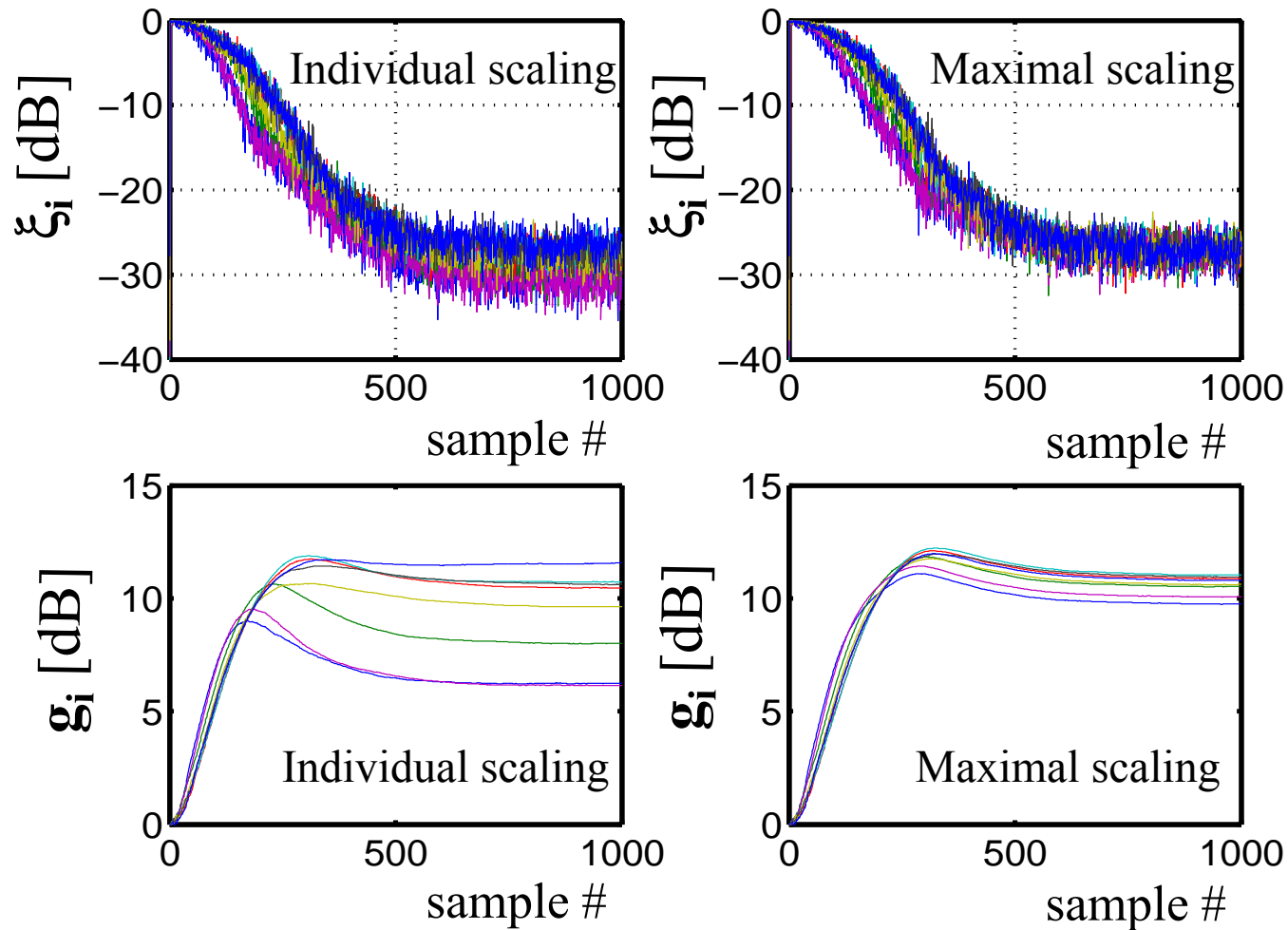
- Different gain and ISI “profiles” per channel

Cost function learning curves

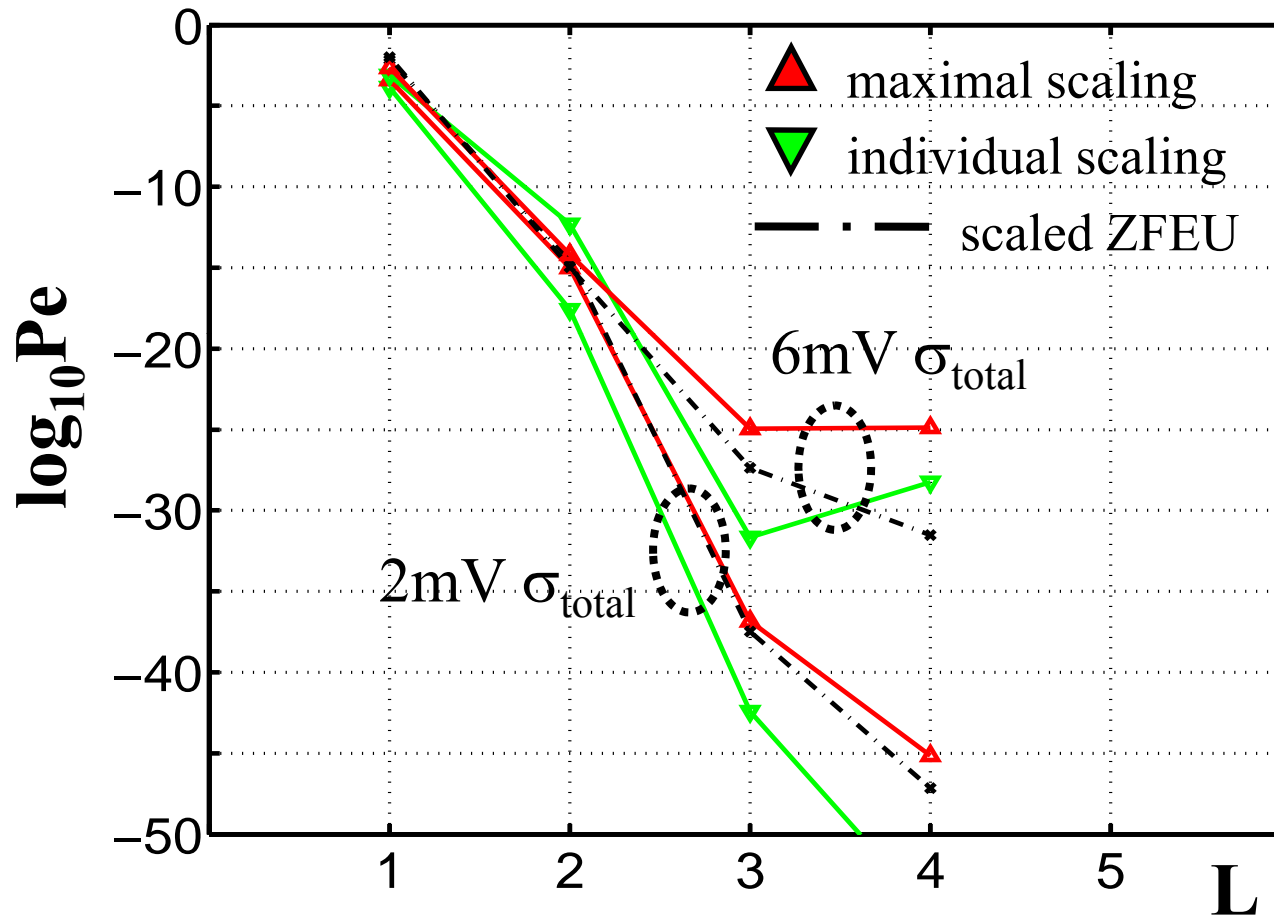


- $L=8 \times 4$ taps of pre-emphasis per channel
- Transmitter output peak constraint = 750mV
- $\sigma_{\text{total}}=4\text{mV}$, $\sigma_{\text{jitter}}=6\text{ps}$
- Individual scaling performs slightly better (highly dependent on the type of the channel)

Learning Curves per Channel



BER vs. filter length



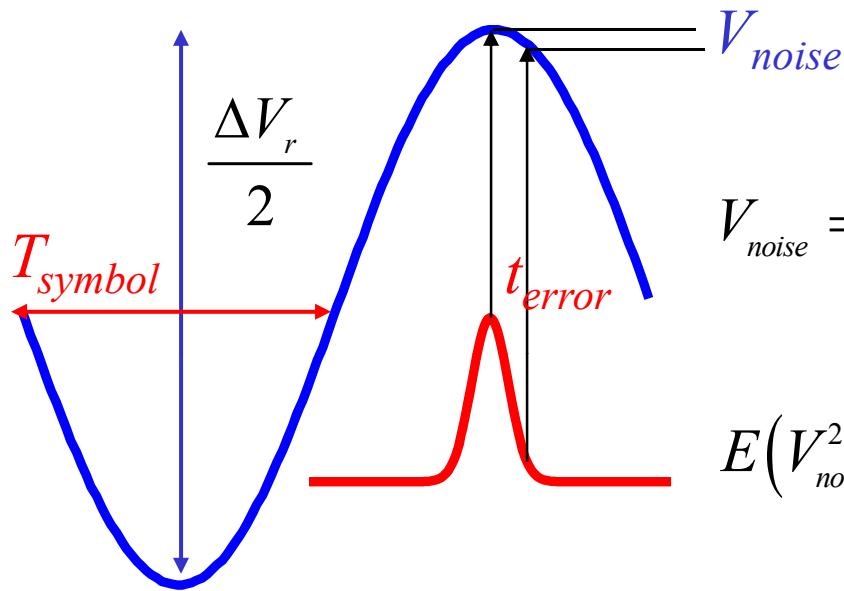
- Taps are found adaptively
- SNR calculated from tap values
- BER estimated from the SNR
- Noise: AWGN voltage noise & Gaussian timing noise

- Noise-ISI tradeoff point at 3-4 taps for higher noise setting

Conclusion

- *Distributed-TDM* alleviates the bandwidth problem of standard TDM for high-speed links
- Methodology is proposed that maps *distributed-TDM* to MIMO system
- **Very low** BER requirements ($<10^{-14}$) impose **peak** power constraint
- Pre-emphasis/gain optimization is **non-convex**
 - Develop sub-optimal solutions that enable
 - Simple adaptive solutions (modification to filtered-X LMS)

Appendix: Noise Analysis



$$V_{noise} = \frac{\Delta V_r}{2} \left(1 - \cos \left(\pi \frac{t_{error}}{T_{symbol}} \right) \right) \leq \frac{\Delta V_r}{4} \left(\pi \frac{t_{error}}{T_{symbol}} \right)^2$$

$$E(V_{noise}^2) \leq 3\Delta V_r^2 \left(\frac{\pi}{2T_{symbol}} \right)^4 \left(E(t_{error}^2) \right)^2$$

- Time to voltage noise mapping
- Time domain noise (t_{error}) – assume Gaussian pdf
- V_{noise} proportional to data
- Independent voltage noise (thermal and voltage reference noise) is assumed to be AWGN